

From Saint-Venant to Navier-Stokes with variable density

Modeling, kinetic interpretation, simulations

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Joint work with

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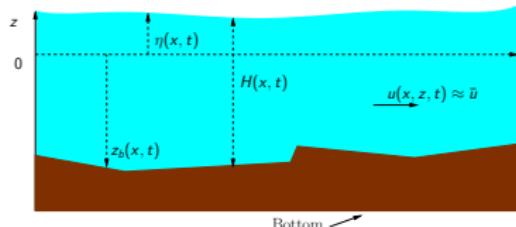
Shallow water systems

$$(NS) \left\{ \begin{array}{l} \operatorname{div} \underline{\mathbf{u}} = 0, \\ \dot{\underline{\mathbf{u}}} + (\underline{\mathbf{u}} \cdot \nabla) \underline{\mathbf{u}} + \nabla p = G + \operatorname{div} \underline{\Sigma}, \end{array} \right.$$

- small parameter $\varepsilon = \frac{H_0}{L_0}$, expansion in $\mathcal{O}(\varepsilon^2)$
- Saint-Venant 1872, Gerbeau 2001, Saleri 2004, Marche 2007

$$(SV) \left\{ \begin{array}{l} \frac{\partial H}{\partial t} + \frac{\partial(H\bar{u})}{\partial x} = 0, \\ \frac{\partial(H\bar{u})}{\partial t} + \frac{\partial}{\partial x} \left(H\bar{u}^2 + \frac{g}{2}H^2 \right) = -gH\frac{\partial z_b}{\partial x} + \frac{\partial}{\partial x} \left(4\mu \frac{\partial \bar{u}}{\partial x} \right) - \kappa(\bar{u}) \end{array} \right.$$

- Low complexity
- Many applications



NOTATIONS: free surface η , bottom z_b , water height $H = \eta - z_b$, velocities $\underline{\mathbf{u}} = (u, w)$, $\bar{u}(x, t) = \frac{1}{H} \int_{z_b}^{\eta} u(x, z, t) dz$

FROM SAINT-VENANT TO NAVIER-STOKES ?

Navier-Stokes vs. Saint-Venant

2D NAVIER-STOKES $\mathbf{u} = (u, w)$

$$\begin{cases} \operatorname{div} \underline{\mathbf{u}} = 0, \\ \dot{\underline{\mathbf{u}}} + (\underline{\mathbf{u}} \cdot \nabla) \underline{\mathbf{u}} + \nabla p = G + \operatorname{div} \underline{\underline{\Sigma}}, \end{cases}$$

SAINT-VENANT H, \bar{u}

$$\begin{cases} \frac{\partial H}{\partial t} + \frac{\partial(H\bar{u})}{\partial x} = 0, \\ \frac{\partial(H\bar{u})}{\partial t} + \frac{\partial}{\partial x} \left(H\bar{u}^2 + \frac{g}{2}H^2 \right) = -gH \frac{\partial z_b}{\partial x} - \kappa(\bar{u}) \end{cases}$$

Complexity of Navier-Stokes

- functional analysis
- numerical schemes
- geometrical meshes, ALE
- computational costs and use

Advantages of Saint-Venant

- fixed meshes
- reduced computational costs
- efficient numerical methods (FV, DG)



Derivation of the Saint-Venant system

(Navier-Stokes)
$$\left\{ \begin{array}{l} \frac{\partial u}{\partial x} + \frac{\partial w}{\partial z} = 0, \\ \frac{\partial u}{\partial t} + \frac{\partial u^2}{\partial x} + \frac{\partial uw}{\partial z} + \frac{\partial p}{\partial x} = \frac{\partial}{\partial x} \Sigma_{xx} + \frac{\partial}{\partial z} \Sigma_{xz}, \\ \frac{\partial w}{\partial t} + \frac{\partial uw}{\partial x} + \frac{\partial w^2}{\partial z} + \frac{\partial p}{\partial z} = -g + \frac{\partial}{\partial x} \Sigma_{zx} + \frac{\partial}{\partial z} \Sigma_{zz}, \end{array} \right.$$

One main assumption ($\varepsilon = H_0/L_0 \ll 1$)

1 Hydrostatic

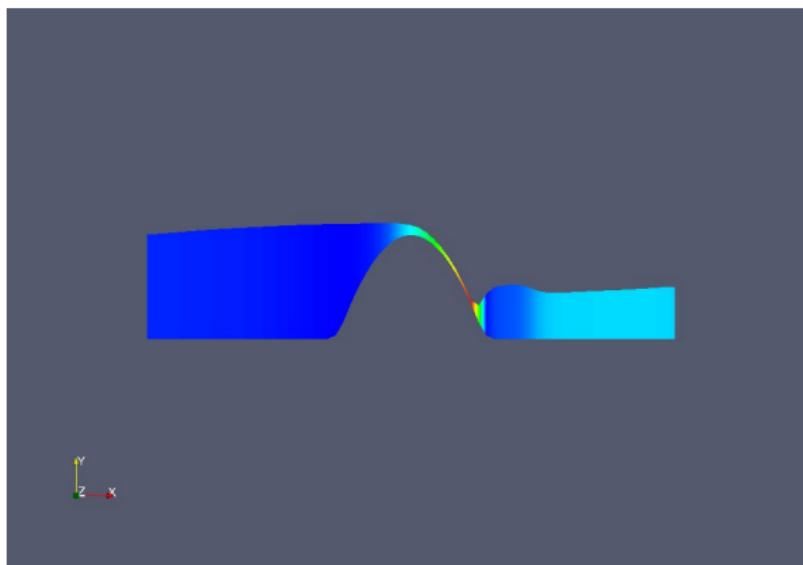
$$\frac{\partial w}{\partial t} + \frac{\partial uw}{\partial x} + \frac{\partial w^2}{\partial z} + \frac{\partial p}{\partial z} = -g \Rightarrow \frac{\partial p}{\partial z} = -g$$

2 Averaged velocity $\bar{u}(x, t) = \frac{1}{H} \int_{z_b}^{\eta} u(x, z, t) dz$

(St-Venant)
$$\left\{ \begin{array}{l} \frac{\partial H}{\partial t} + \frac{\partial(H\bar{u})}{\partial x} = 0, \\ \frac{\partial(H\bar{u})}{\partial t} + \frac{\partial}{\partial x} \left(H\bar{u}^2 + \frac{g}{2}H^2 - 4\mu H \frac{\partial \bar{u}}{\partial x} \right) = -gH \frac{\partial z_b}{\partial x} - \kappa(\bar{u}) \end{array} \right.$$

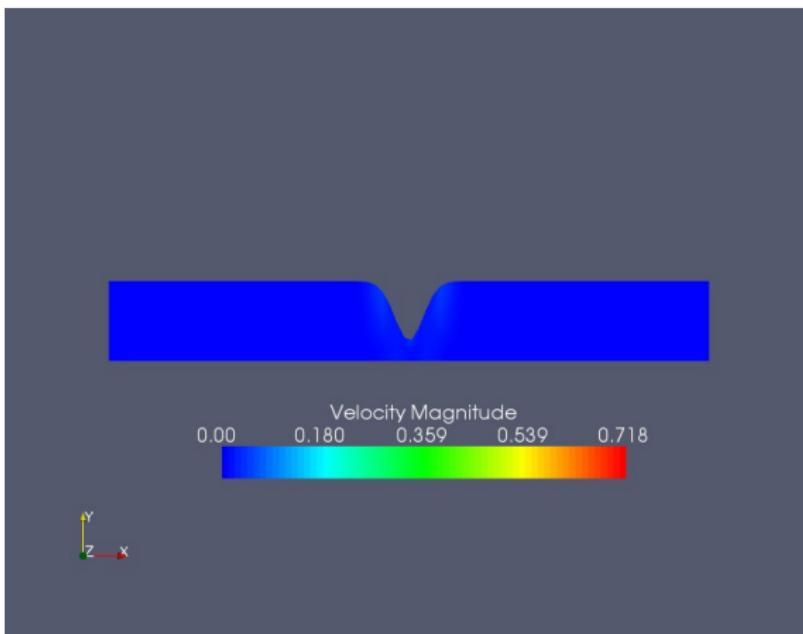
Three numerical examples

1 Hydraulic jump



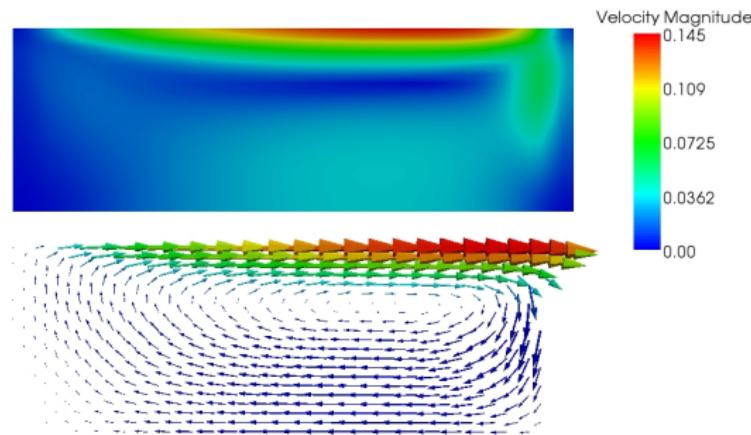
Three numerical examples

1 Waves propagation



Three numerical examples

1 Stratified velocities (wind effect)



Typical applications (Etang de Berre)



- Large scale : time (1 year) & space (155 km^2)
 - Water with variable density (temperature & salinity)
 - Hydrodynamics and biology

Outline

1 A multilayer Saint-Venant system

- Derivation
- Properties (energy equality, hyperbolicity, . . .)
- Kinetic interpretation
- Simulations

2 Multilayer Saint-Venant with varying density

- Passive pollutant
- Pollutant with varying density

3 Towards non-hydrostatic systems

- Archimedes' principle
- Gravity waves

Classical Saint-Venant system

Proposition (Gerbeau-Perthame 2001)

The viscous Saint-Venant system with friction

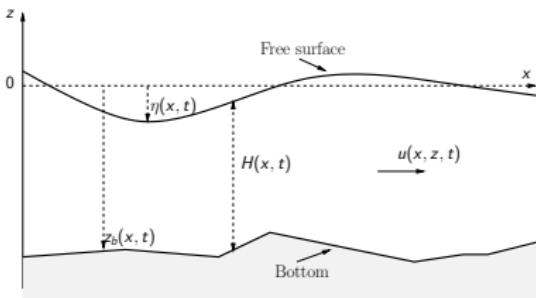
$$\begin{aligned}\frac{\partial H}{\partial t} + \frac{\partial(H\bar{u})}{\partial x} &= 0, \\ \frac{\partial(H\bar{u})}{\partial t} + \frac{\partial}{\partial x}\left(H\bar{u}^2 + \frac{g}{2}H^2\right) &= -gH\frac{\partial z_b}{\partial x} + \frac{\partial}{\partial x}\left(4\mu\frac{\partial\bar{u}}{\partial x}\right) - \kappa(\bar{u})\end{aligned}$$

results from an approximation in $O(\varepsilon^2)$ of the Navier-Stokes equations ($\varepsilon = H_0/L_0$).

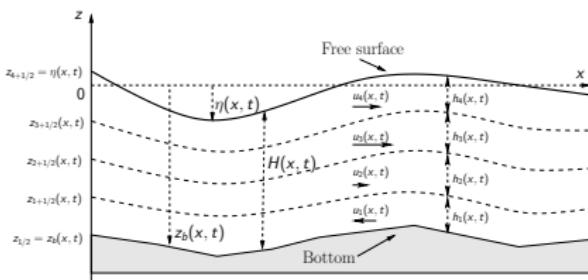
- Strictly hyperbolic
- Numerical schemes
 - finite volumes (relaxation schemes, cf. Bouchut, kinetic schemes, cf. Perthame , Simeoni)
 - discontinuous Galerkin (Ern)
- Not only free surface flows (blood in arteries, Quarteroni *et al.*, avalanches, Bouchut *et al.*)

Vertical discretization

Enrich the velocity field



$$\begin{aligned} \frac{\partial H}{\partial t} + \frac{\partial(H\bar{u})}{\partial x} &= 0, \\ \frac{\partial(H\bar{u})}{\partial t} + \frac{\partial}{\partial x}\left(H\bar{u}^2 + \frac{g}{2}H^2\right) &= -gH\frac{\partial z_b}{\partial x} \\ &\quad + \frac{\partial}{\partial x}\left(4\mu\frac{\partial \bar{u}}{\partial x}\right) - \kappa(\bar{u}) \end{aligned}$$



- Several attempts (Audusse, Pares)
- Valid for non-miscible fluids
- Hyperbolicity ?
- Key point :

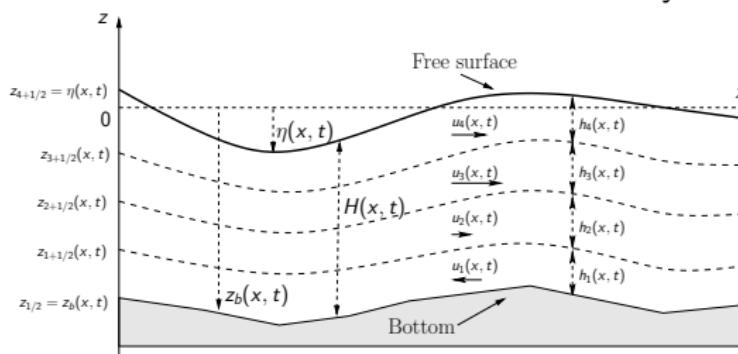
$$\begin{aligned} H &= \sum_{\alpha=1}^N h_\alpha, \quad h_\alpha(x, t) = l_\alpha H(x, t) \\ u(x, z, t) &= \sum_{\alpha=1}^N 1_{z \in h_\alpha}(z) u_\alpha(x, t) \end{aligned}$$

Derivation of the (new) multilayer system

Starting point

$$\text{(Euler hydro)} \quad \left\{ \begin{array}{l} \frac{\partial u}{\partial x} + \frac{\partial w}{\partial z} = 0 \\ \frac{\partial u}{\partial t} + \frac{\partial u^2}{\partial x} + \frac{\partial uw}{\partial z} + \frac{\partial p}{\partial x} = 0 \\ \frac{\partial p}{\partial z} = -g \end{array} \right.$$

+ two kinematic boundary conditions

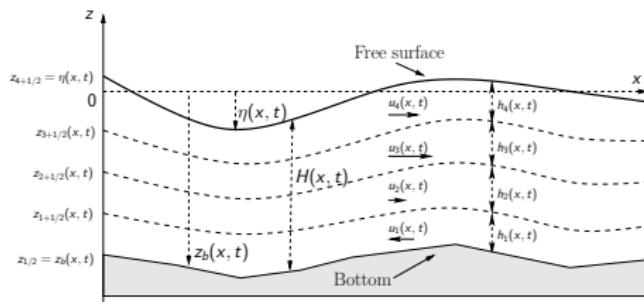


- Viscous terms neglected in the presentation
- Discretization in z of the velocities u, w
- Also done in 3D

Derivation of the (new) multilayer system

Starting point

$$\text{(Euler hydro)} \quad \left\{ \begin{array}{l} \frac{\partial u}{\partial x} + \frac{\partial w}{\partial z} = 0 \\ \frac{\partial u}{\partial t} + \frac{\partial u^2}{\partial x} + \frac{\partial uw}{\partial z} + \frac{\partial p}{\partial x} = 0 \\ \frac{\partial p}{\partial z} = -g \end{array} \right.$$



$$u(x, z, t) = \sum_{\alpha=1}^N 1_{z \in h_\alpha}(z) u_\alpha(x, t)$$

- Integration on each layer of the continuity equation

$$\frac{\partial h_\alpha}{\partial t} + \frac{\partial h_\alpha u_\alpha}{\partial x} = G_{\alpha+1/2} - G_{\alpha-1/2}$$

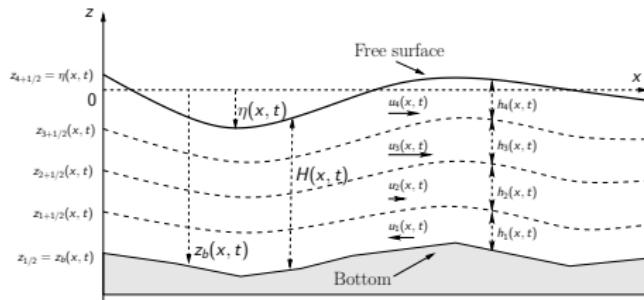
$$G_{\alpha+1/2} = \frac{\partial z_{\alpha+1/2}}{\partial t} + u_{\alpha+1/2} \frac{\partial z_{\alpha+1/2}}{\partial x} - w_{\alpha+1/2},$$

$$G_{1/2} = G_{N+1/2} = 0 \text{ (kinematic boundary conditions)}$$

Derivation of the (new) multilayer system

Starting point

$$\text{(Euler hydro)} \quad \left\{ \begin{array}{l} \frac{\partial u}{\partial x} + \frac{\partial w}{\partial z} = 0 \\ \frac{\partial u}{\partial t} + \frac{\partial u^2}{\partial x} + \frac{\partial uw}{\partial z} + \frac{\partial p}{\partial x} = 0 \\ \frac{\partial p}{\partial z} = -g \end{array} \right.$$



$$u(x, z, t) = \sum_{\alpha=1}^N 1_{z \in h_\alpha}(z) u_\alpha(x, t)$$

- Integration on each layer of the momentum equation

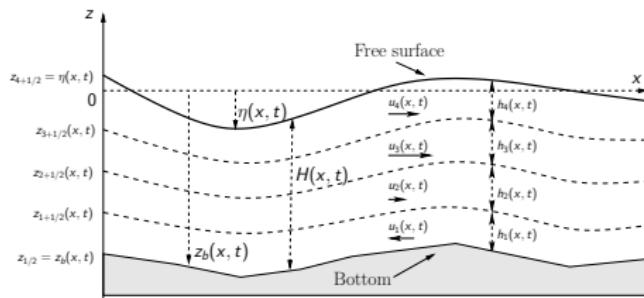
$$\frac{\partial(h_\alpha u_\alpha)}{\partial t} + \frac{\partial}{\partial x} \left(h_\alpha u_\alpha^2 + gh_\alpha \left[\frac{h_\alpha}{2} + \sum_{j=\alpha+1}^N h_j \right] \right) = F_{\alpha+1/2} - F_{\alpha-1/2},$$

with $F_{\alpha+1/2} = u_{\alpha+1/2} G_{\alpha+1/2} + \left(\sum_{j=\alpha+1}^N g h_j \right) \frac{\partial z_{\alpha+1/2}}{\partial x}$,

Derivation of the (new) multilayer system

Starting point

$$\text{(Euler hydro)} \quad \left\{ \begin{array}{l} \frac{\partial u}{\partial x} + \frac{\partial w}{\partial z} = 0 \\ \frac{\partial u}{\partial t} + \frac{\partial u^2}{\partial x} + \frac{\partial uw}{\partial z} + \frac{\partial p}{\partial x} = 0 \\ \frac{\partial p}{\partial z} = -g \end{array} \right.$$



$$u(x, z, t) = \sum_{\alpha=1}^N 1_{z \in h_\alpha}(z) u_\alpha(x, t)$$

- Integration on each layer of the momentum equation ($\times u$)

$$\frac{\partial}{\partial t} E_\alpha + \frac{\partial}{\partial x} \left(u_\alpha \left(E_\alpha + gh_\alpha \left(\frac{h_\alpha}{2} + \sum_{j=\alpha+1}^N h_j \right) \right) \right) = E_{\alpha+1/2} - E_{\alpha-1/2}$$

with $E_\alpha = \frac{h_\alpha u_\alpha^2}{2} + \frac{g(z_{\alpha+1/2}^2 - z_{\alpha-1/2}^2)}{2}$

$$E_{\alpha+1/2} = \frac{u_{\alpha+1/2}^2}{2} G_{\alpha+1/2} + \left(\sum_{j=\alpha+1}^N g h_j \right) \frac{\partial z_{\alpha+1/2}}{\partial x}$$

Energy equality

For the multilayer system

$$\frac{\partial}{\partial t} \left(\sum_{\alpha=1}^N E_\alpha \right) + \frac{\partial}{\partial x} \left(\sum_{\alpha=1}^N u_\alpha \left(E_\alpha + \frac{g}{2} h_\alpha f(\{h_j\}_{j \leq \alpha}) - 4\mu h_\alpha \frac{\partial u_\alpha}{\partial x} \right) \right) = \\ -\kappa(\bar{\mathbf{v}}, H) u_1^2 - \frac{\mu}{h_\alpha} \sum_{\alpha=1}^{N-1} (u_{\alpha+1/2} - u_{\alpha-1/2})^2 - 4\mu \sum_{\alpha=1}^N h_\alpha \left(\frac{\partial u_\alpha}{\partial x} \right)^2,$$

with $E_\alpha = \frac{h_\alpha u_\alpha^2}{2} + \frac{g(z_{\alpha+1/2}^2 - z_{\alpha-1/2}^2)}{2}$

For the 2D Navier-Stokes eq.

$$\frac{\partial}{\partial t} \int_{z_b}^\eta \left(\frac{u^2}{2} + gz \right) dz + \frac{\partial}{\partial x} \left(u \left(\int_{z_b}^\eta \left(\frac{u^2}{2} + gz \right) dz + p \right) \right) = -\kappa u^2$$

Complete formulation

Proposition (Audusse, Bristeau, Perthame, JSM 2009)

The multilayer Saint-Venant system

$$\left\{ \begin{array}{l} \frac{\partial H}{\partial t} + \sum_{\alpha=1}^N \frac{\partial}{\partial x} (h_\alpha u_\alpha) = 0 \\ \frac{\partial(h_\alpha u_\alpha)}{\partial t} + \frac{\partial}{\partial x} \left(h_\alpha u_\alpha^2 + \frac{g}{2} h_\alpha f(\{h_j\}_{j \geq \alpha}) \right) = F_{\alpha+1/2} - F_{\alpha-1/2} \\ \frac{\partial E_\alpha}{\partial t} + \frac{\partial}{\partial x} \left(u_\alpha \left(E_\alpha + \frac{g}{2} h_\alpha H \right) \right) = E_{\alpha+1/2} - E_{\alpha-1/2} \end{array} \right.$$

results in an approximation in $\mathcal{O}(1/N)$ of the Euler (Navier-Stokes) equations ($h_\alpha = H/N$).

- Only one “global” continuity eq.
- Exchange terms $G_{\alpha+1/2}$, $F_{\alpha+1/2} = u_{\alpha+1/2} G_{\alpha+1/2} + P_{\alpha+1/2}$,
 $E_{\alpha+1/2} = \frac{u_{\alpha+1/2}^2}{2} G_{\alpha+1/2} + u_{\alpha+1/2} P_{\alpha+1/2}$
- If $G_{\alpha+1/2} = 0$, non-miscible fluids

The multilayer system is hyperbolic

The multilayer system reads

$$M(U)\dot{U} + F(U) \frac{\partial U}{\partial x} = 0,$$

with $U = (h_1, \dots, h_N, u_1, \dots, u_N)^T$

- For $N = 2$, eigenvalues $\lambda_1, \lambda_2, \lambda_3$ satisfy

$$\lambda_1 \leq u_1 - \sqrt{gH} < \lambda_2 < u_2 + \sqrt{gH} \leq \lambda_3$$

- For $N > 2$, interlacing of the eigenvalues but **only** numerical proof (arrow matrices)
- Most finite volume schemes fail
- Velocity discretization (more complex)

$$u(x, z, t) = \sum_{\alpha=1}^N P_\alpha(z) u_\alpha(x, t), \quad \text{with} \quad \deg(P_\alpha) = k$$

Kinetic interpretation (Lions, Perthame, Tadmor, Souganidis)

- Gibbs equilibrium $M(x, t, \xi) = \frac{H}{c} \chi\left(\frac{\xi - \bar{u}}{c}\right)$ with $c = \sqrt{gH}$
where $\chi(\omega) = \chi(-\omega)$, $\text{supp}(\chi) \subset \Omega$, $\int_{\mathbb{R}} \chi(\omega) = \int_{\mathbb{R}} \omega^2 \chi(\omega) = 1$

Proposition (classical Saint-Venant)

The functions $(H, \bar{u}, E)(t, x)$ are strong solutions of the Saint-Venant system if and only if $M(t; x; \xi)$ is solution of the kinetic equation

$$(\mathcal{B}), \quad \frac{\partial M}{\partial t} + \xi \frac{\partial M}{\partial x} - g \frac{\partial z_b}{\partial x} \frac{\partial M}{\partial \xi} = Q(x, t, \xi)$$

where $Q(t, x, \xi)$ is a “collision term”.

- Proof : $\int_{\mathbb{R}} (1, \xi, |\xi|^2/2)(\mathcal{B}) d\xi$
- See Audusse *et al.*

Kinetic interpretation for the multilayer system

■ Gibbs equilibrium

- $M_\alpha(x, t, \xi) = \frac{h_\alpha}{c_\alpha} \chi\left(\frac{\xi - u_\alpha}{c_\alpha}\right), \quad \text{with } c_\alpha = \sqrt{gf(\{h_j\}_{j \geq \alpha})}$
- $N_{\alpha+1/2}(x, t, \xi) = G_{\alpha+1/2} \delta(\xi - u_{\alpha+1/2}),$

Proposition (Audusse, Bristeau, Perthame, JSM 2009)

The functions $(h_\alpha, u_\alpha, E_\alpha)(t, x)$ are strong solutions of the multilayer Saint-Venant system if and only if the set $\{M_j(t; x; \xi)\}_{j=1}^N$ is solution of the kinetic equations

$$\frac{\partial M_\alpha}{\partial t} + \xi \frac{\partial M_\alpha}{\partial x} - N_{\alpha+1/2} + N_{\alpha-1/2} = Q_\alpha(x, t, \xi)$$

■ Pressure terms omitted

- more complex kinetic interpretation
- hydrostatic reconstruction (Audusse *et al.*)

2nd order finite volume

Properties

- Positive scheme (CFL=1 but more complex)
- 2nd order scheme (space)
- Well balanced (hyd. reconst., cf. Audusse *et al.* 2004, 2005)
- (Discrete entropy)
- Heun scheme (Runge-Kutta_N, 2nd order in time)

$$H_j^{n+1} = H_j^n - \sigma_j^n \sum_{\alpha=1}^N \left(\mathcal{F}_{\alpha,j+1/2}^n - \mathcal{F}_{\alpha,j-1/2}^n \right),$$

and for each layer α

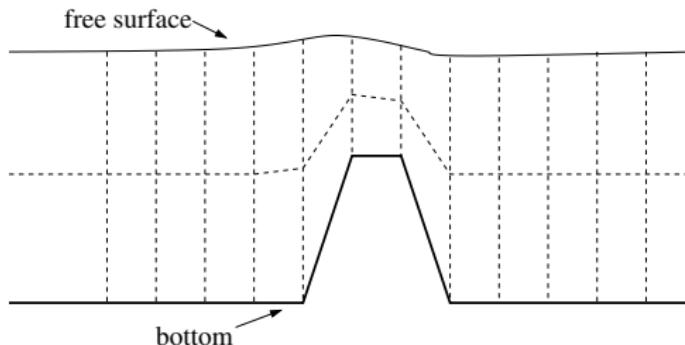
$$\begin{aligned} Q_{\alpha,j}^{n+1} = Q_{\alpha,j}^n & - \sigma_j^n \left(\mathcal{Q}_{\alpha,j+1/2}^n - \mathcal{Q}_{\alpha,j-1/2}^n \right. \\ & \left. + N_{\alpha+1/2}^{n+1/2} - N_{\alpha-1/2}^{n+1/2} \right) \end{aligned}$$

upwinding of $u_{\alpha+1/2}$ and $u_{\alpha-1/2}$

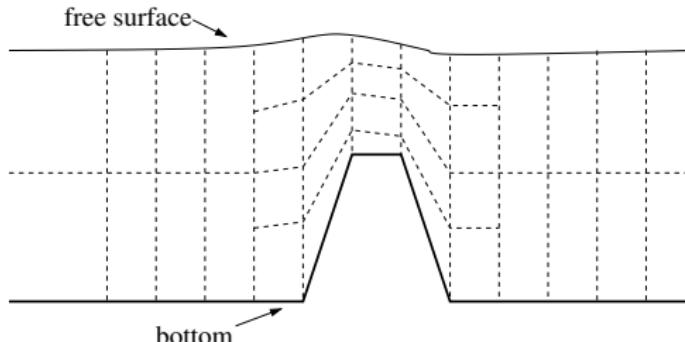
- Numerical cost $\mathcal{O}(N \times 1)$

Mesh considerations

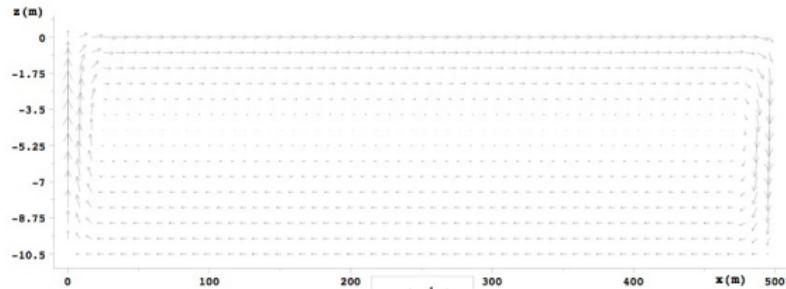
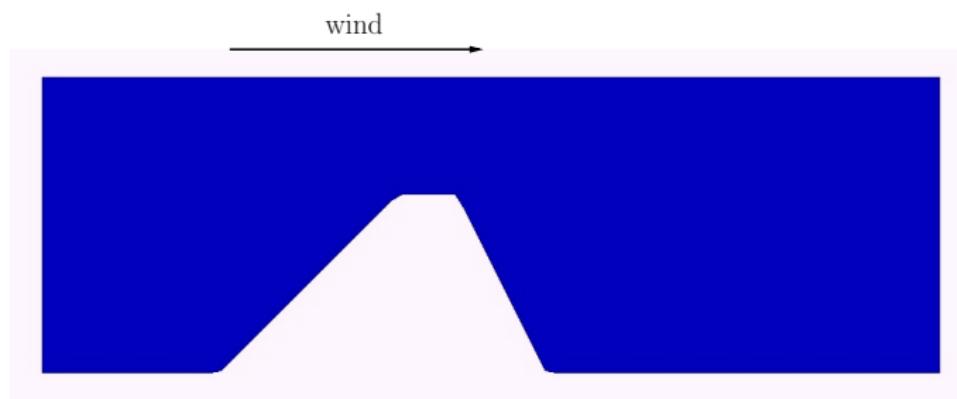
■ This version



■ Improvement



Wind effects (stratified velocities)



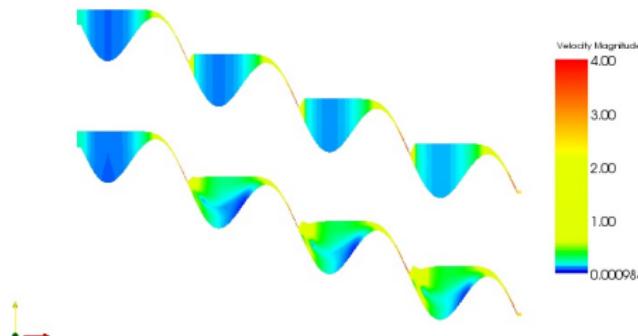
TELEMAC3D
(3D hydrostatic Navier-Stokes)

Courtesy of A. Decoene



Simulations

- With 1 and 5 layers
- $Q_{in} = 2.749 \cdot 10^{-2} \text{ m}^2 \cdot \text{s}^{-1}$, $\mu = 0.001$, Strickler 40.0
- Rain $0.00687 \text{ m} \cdot \text{s}^{-1}$



Transport of a passive pollutant

- 2D Euler (Navier-Stokes) with pollutant

$$\begin{cases} \operatorname{div} \underline{u} = 0 \\ \dot{\underline{u}} + (\underline{u} \cdot \nabla)(\underline{u}) + \nabla p = G \\ \dot{T} + \operatorname{div}(T\underline{u}) = \frac{\partial}{\partial z} (\mu T \frac{\partial T}{\partial z}) \end{cases}$$

- Discretized by layer

$$\begin{cases} \frac{\partial}{\partial t} \sum_{\alpha=1}^N h_\alpha + \frac{\partial}{\partial x} \sum_{\alpha=1}^N h_\alpha u_\alpha = 0, \\ \frac{\partial(h_\alpha u_\alpha)}{\partial t} + \frac{\partial}{\partial x} \left(h_\alpha u_\alpha^2 + gh_\alpha \left[\frac{h_\alpha}{2} + \sum_{j=\alpha+1}^N h_j \right] \right) = F_{\alpha+1/2} - F_{\alpha-1/2}, \\ \frac{\partial(h_\alpha T_\alpha)}{\partial t} + \frac{\partial}{\partial x} (h_\alpha u_\alpha T_\alpha) = T_{\alpha+1/2} G_{\alpha+1/2} - T_{\alpha-1/2} G_{\alpha-1/2}, \end{cases}$$

with $G_{\alpha+1/2} = \frac{\partial z_{\alpha+1/2}}{\partial t} + u_{\alpha+1/2} \frac{\partial z_{\alpha+1/2}}{\partial x} - w_{\alpha+1/2}$

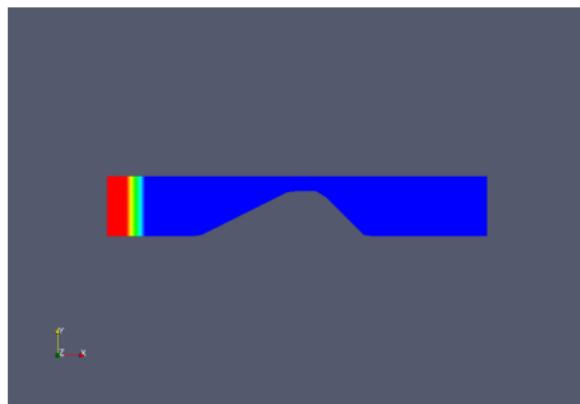
and $F_{\alpha+1/2} = u_{\alpha+1/2} G_{\alpha+1/2} + \left(\sum_{j=\alpha+1}^N g h_j \right) \frac{\partial z_{\alpha+1/2}}{\partial x}$,

Transport of a passive pollutant

- 2D Euler (Navier-Stokes) with pollutant

$$\begin{cases} \operatorname{div} \underline{\mathbf{u}} = 0 \\ \dot{\underline{\mathbf{u}}} + (\underline{\mathbf{u}} \cdot \nabla)(\underline{\mathbf{u}}) + \nabla p = G \\ \dot{T} + \operatorname{div}(T \underline{\mathbf{u}}) = \frac{\partial}{\partial z} (\mu_T \frac{\partial T}{\partial z}) \end{cases}$$

- Also kinetic interpretation
- Same numerical scheme as previously



Pollutant in 3D

Multilayer with variable density

3D Euler/Navier-Stokes (hydrostatic) with variable density

$$\begin{cases} \dot{\rho} + \operatorname{div}(\rho \underline{\mathbf{u}}) = 0, \\ \dot{\rho} \underline{\mathbf{u}} + (\underline{\mathbf{u}} \cdot \nabla)(\rho \underline{\mathbf{u}}) + \nabla p = \rho \mathbf{G}, \\ \frac{\partial}{\partial z} T_j + \operatorname{div}(\rho T_j \underline{\mathbf{u}}) = \frac{\partial}{\partial z} \left(\mu_T \frac{\partial T_j}{\partial z} \right), \quad j = 1, \dots, p \\ \rho = \rho(\{T_j\}_{j=1}^p) = \rho(\mathcal{H}, \{T_j\}_{j=i}^p) \end{cases}$$

■ Discretized by layer

$$\begin{cases} \frac{\partial}{\partial t} \sum_{\alpha=1}^N (\rho_\alpha h_\alpha) + \sum_{\alpha=1}^N \frac{\partial}{\partial x} (\rho_\alpha h_\alpha u_\alpha) = 0, \\ \frac{\partial(\rho_\alpha h_\alpha u_\alpha)}{\partial t} + \frac{\partial}{\partial x} \left(\rho_\alpha h_\alpha u_\alpha^2 + \frac{g}{2} h_\alpha f(\{\rho_j h_j\}_{j \geq \alpha}) \right) = \\ \quad + u_{\alpha+1/2} G_{\alpha+1/2} - u_{\alpha-1/2} G_{\alpha-1/2} + \text{Sc. Terms}, \\ \frac{\partial(\rho_\alpha h_\alpha T_\alpha)}{\partial t} + \frac{\partial}{\partial x} (\rho_\alpha h_\alpha u_\alpha T_\alpha) \\ \quad + T_{\alpha+1/2} G_{\alpha+1/2} - T_{\alpha-1/2} G_{\alpha-1/2}, \end{cases}$$

Multilayer with variable density

■ Gibbs equilibrium

- $M_\alpha(x, t, \xi) = \frac{\rho_\alpha h_\alpha}{c_\alpha} \chi\left(\frac{\xi - u_\alpha}{c_\alpha}\right), \quad \text{with } c_\alpha = \sqrt{gf(\{\rho_j h_j\}_{j \geq \alpha})}$
- $N_{\alpha+1/2}(x, t, \xi) = G_{\alpha+1/2} \delta(\xi - u_{\alpha+1/2}),$

Proposition

The functions $(\rho_\alpha, h_\alpha, u_\alpha, T_\alpha, E_\alpha)(t, x)$ are strong solutions of the multilayer Saint-Venant system with variable density if and only if the set $\{M_j(t; x; \xi)\}_{j=1}^N$ is solution of the kinetic equations

$$\frac{\partial M_\alpha}{\partial t} + \xi \frac{\partial M_\alpha}{\partial x} - N_{\alpha+1/2} + N_{\alpha-1/2} = Q_\alpha(x, t, \xi)$$

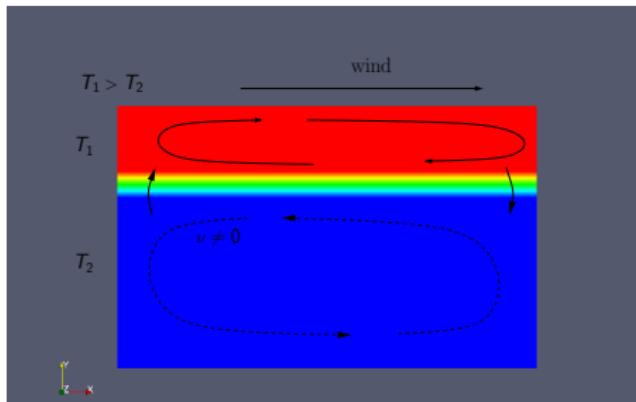
■ Numerical scheme

- maximum principle for T , positivity of T , ...
- no more explicit, more complex and costly

Multilayer with variable density

3D compressible Euler/Navier-Stokes (hydrostatic)

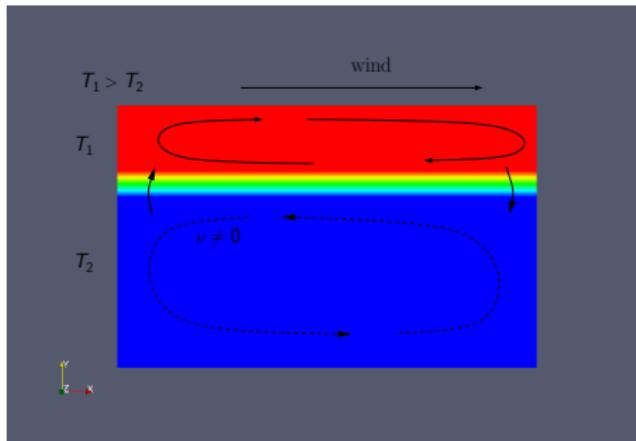
$$\begin{cases} \dot{\rho} + \operatorname{div}(\rho \underline{\mathbf{u}}) = 0, \\ \dot{\rho \underline{\mathbf{u}}} + (\underline{\mathbf{u}} \cdot \nabla)(\rho \underline{\mathbf{u}}) + \nabla p = \rho G, \\ \dot{\rho T_j} + \operatorname{div}(\rho T_j \underline{\mathbf{u}}) = 0, \quad j = 1, \dots, p \\ \rho = \rho(\{T_j\}_{j=1}^p) = \rho(\mathcal{H}, \{T_j\}_{j=i}^p) \end{cases}$$



Multilayer with variable density

3D hydrostatic Euler/Navier-Stokes (constant density)

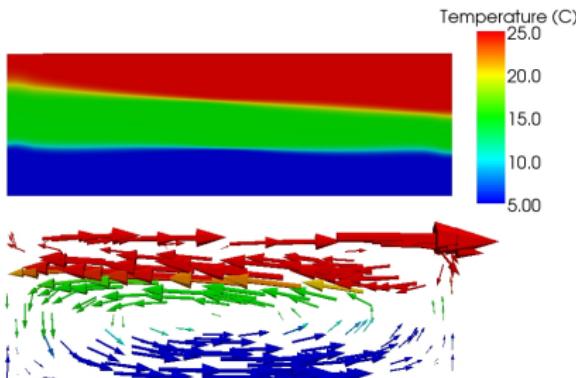
$$\begin{cases} \operatorname{div}(\underline{\mathbf{u}}) = 0, \\ \dot{\underline{\mathbf{u}}} + (\underline{\mathbf{u}} \cdot \nabla)(\underline{\mathbf{u}}) + \nabla p = G, \\ \overline{T_j} + \operatorname{div}(T_j \underline{\mathbf{u}}) = 0, \quad j = 1, \dots, p \end{cases}$$



Multilayer with variable density

3D compressible hydrostatic Navier-Stokes

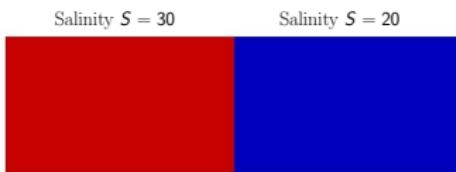
$$\begin{cases} \dot{\rho} + \operatorname{div}(\rho \underline{\mathbf{u}}) = 0, \\ \dot{\rho \underline{\mathbf{u}}} + (\underline{\mathbf{u}} \cdot \nabla)(\rho \underline{\mathbf{u}}) + \nabla p = \rho G, \\ \dot{\rho T_j} + \operatorname{div}(\rho T_j \underline{\mathbf{u}}) = 0, \quad j = 1, \dots, p \\ \rho = \rho(\{T_j\}_{j=i}^p) = \rho(H, \{T_j\}_{j=i}^p) \end{cases}$$



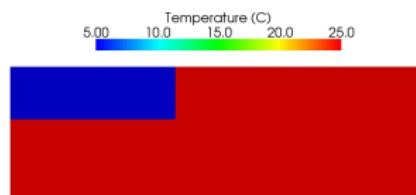
Archimedes' principle

■ Limitations for hydrostatic systems

- Re-ordering



- Behaviour (hot/cold water)



$$\left\{ \begin{array}{l} \frac{\partial \rho}{\partial t} + \frac{\partial \rho u}{\partial x} + \frac{\partial \rho w}{\partial z} = 0 \\ \frac{\partial \rho u}{\partial t} + \frac{\partial \rho u^2}{\partial x} + \frac{\partial \rho uw}{\partial z} + \frac{\partial p}{\partial x} = 0 \\ \frac{\partial \rho w}{\partial t} + \frac{\partial \rho uw}{\partial x} + \frac{\partial \rho w^2}{\partial z} + \frac{\partial p}{\partial z} = -\rho g \end{array} \right.$$

- Static equilibrium stable if $\frac{\partial \rho}{\partial z} \geq 0$

Gravity waves

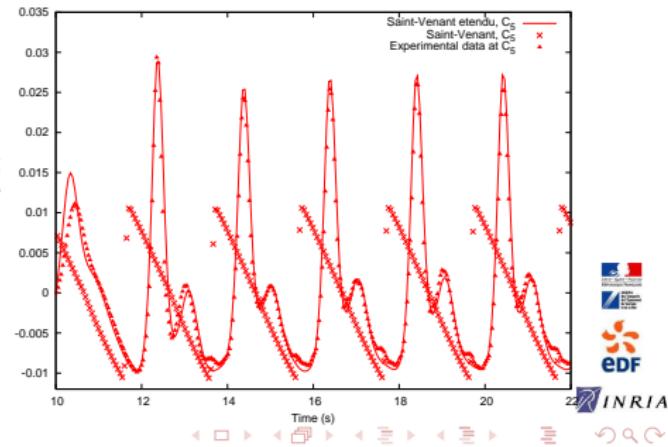
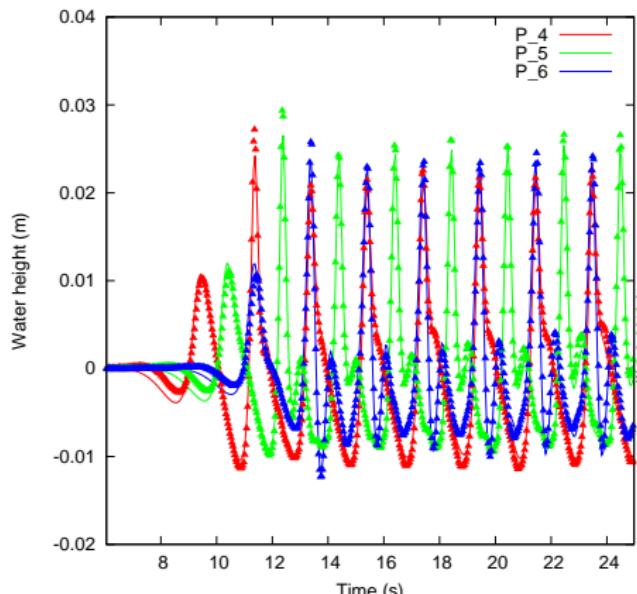
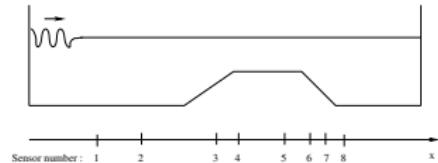
Non-hydrostatic

$$u(x, z, t) = \bar{u}(x, t) + \mathcal{O}(\varepsilon), \quad \frac{\partial w}{\partial t} + \frac{\partial p}{\partial z} = -g$$
$$\left\{ \begin{array}{l} \frac{\partial H}{\partial t} + \frac{\partial(H\bar{u})}{\partial x} = 0, \\ \frac{\partial(H\bar{u})}{\partial t} + \frac{\partial}{\partial x} \left(H\bar{u}^2 + \frac{g}{2}H^2 \right) + \mathcal{D}(H) \frac{\partial^3 \bar{u}}{\partial^2 x \partial t} = -H \frac{\partial z_b}{\partial x} - \kappa(\bar{u}) \end{array} \right.$$

- Peregrine 1957, BBM 1972, Bristeau-JSM 2008
- Kinetic type interpretation & scheme
- Implementation in Mascaret (©EDF-MEEDDAT)
- Other approach : irrotational velocity field (Bona, Saut, Lannes)
 - often ill-posed problems

Experimental validation

- Dinguemans experiments
- Animation
- Comparisons (sensors 4, 5 and 6)



General outlook

- From Saint-Venant to Navier-Stokes
 - multilayer system (vertical dicretization)
 - variable density
 - kinetic interpretation, associated numerical scheme
- Mathematical works (compressible case)
- Convective terms (to be added)

$$\frac{\partial w}{\partial t} + \frac{\partial uw}{\partial x} + \frac{\partial w^2}{\partial z} + \frac{\partial p}{\partial z} = -g$$

- Boltzmann type equations but with reaction terms
- Exprimental validations needed
- Biology/hydrodynamics coupling
- Inverse problems (data assimilation) using kinetic type interpretations

Comparison (flat bottom)

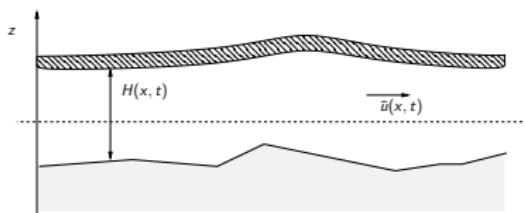
■ Audusse formulation ($h_1 + h_2 = H$)

$$\left\{ \begin{array}{l} \frac{\partial h_1}{\partial t} + \frac{\partial(h_1 u_1)}{\partial x} = 0, \quad \frac{\partial h_2}{\partial t} + \frac{\partial(h_2 u_2)}{\partial x} = 0, \\ \frac{\partial(h_1 u_1)}{\partial t} + \frac{\partial}{\partial x} (h_1 u_1^2 + gh_1(h_1 + h_2)) = \frac{g(h_1+h_2)^2}{2} \frac{\partial}{\partial x} \frac{h_1}{h_1+h_2}, \\ \frac{\partial(h_2 u_2)}{\partial t} + \frac{\partial}{\partial x} (h_2 u_2^2 + gh_2(h_1 + h_2)) = \frac{g(h_1+h_2)^2}{2} \frac{\partial}{\partial x} \frac{h_2}{h_1+h_2}, \end{array} \right.$$

■ New formulation ($h_1 = \alpha H$, $h_2 = (1 - \alpha)H$ and $\alpha \in (0, 1)$)

$$\left\{ \begin{array}{l} \frac{\partial H}{\partial t} + \frac{\partial(h_1 u_1)}{\partial x} + \frac{\partial(h_2 u_2)}{\partial x} = 0, \\ \frac{\partial(h_1 u_1)}{\partial t} + \frac{\partial}{\partial x} (h_1 u_1^2 + \frac{g}{2}(2h_2^2 + h_1^2)) = u_{3/2} \left(\frac{\partial h_1}{\partial x} + \frac{\partial(h_1 u_1)}{\partial x} \right), \\ \frac{\partial(h_2 u_2)}{\partial t} + \frac{\partial}{\partial x} (h_2 u_2^2 + \frac{g}{2}h_2^2) = -u_{3/2} \left(\frac{\partial h_1}{\partial x} + \frac{\partial(h_1 u_1)}{\partial x} \right), \end{array} \right.$$

Flows without free surface



- Flow with deformable tip

$$\begin{aligned}\frac{\partial H}{\partial t} + \frac{\partial H \bar{u}}{\partial x} &= 0 \\ \frac{\partial H \bar{u}}{\partial t} + \frac{\partial}{\partial x} \left(H \bar{u}^2 + \frac{g}{2} H^2 + H p_S \right) &= -gH \frac{\partial z_b}{\partial x} - p_S \frac{\partial H}{\partial x}\end{aligned}$$

- Kinetic interpretation
 - Gibbs equilibrium

$$M(x, t, \xi) = \frac{H}{c} \chi \left(\frac{\xi - \bar{u}}{c} \right) \quad \text{with } c = \sqrt{gH + p_S}$$

- Solution of

$$(\mathcal{B}), \quad \frac{\partial M}{\partial t} + \xi \frac{\partial M}{\partial x} - g \frac{\partial z_b}{\partial x} \frac{\partial M}{\partial \xi} = Q(x, t, \xi)$$

Source terms - two writings

Incompressible case i.e. $p = g(\eta - z)$

$$\int_{z_{\alpha-1/2}}^{z_{\alpha+1/2}} \frac{\partial p}{\partial x} dx = \int_{z_{\alpha-1/2}}^{z_{\alpha+1/2}} g \frac{\partial \eta}{\partial x} dx = \frac{\partial}{\partial x} \left(\frac{g}{2} h_\alpha H \right) + gh_\alpha \frac{\partial z_b}{\partial x}$$

Compressible case i.e. $p = \int_z^\eta \rho g dz$

$$\int_{z_{\alpha-1/2}}^{z_{\alpha+1/2}} \frac{\partial p}{\partial x} dx = \frac{\partial}{\partial x} \left(\int_z^\eta \rho g dz \right) - \frac{\partial z_{\alpha+1/2}}{\partial x} p_{\alpha+1/2} + \frac{\partial z_{\alpha-1/2}}{\partial x} p_{\alpha-1/2}$$

- Extension of Audusse, Bouchut, Klein, Perthame 2005
- Well balanced, 2nd order in space . . . rather tricky