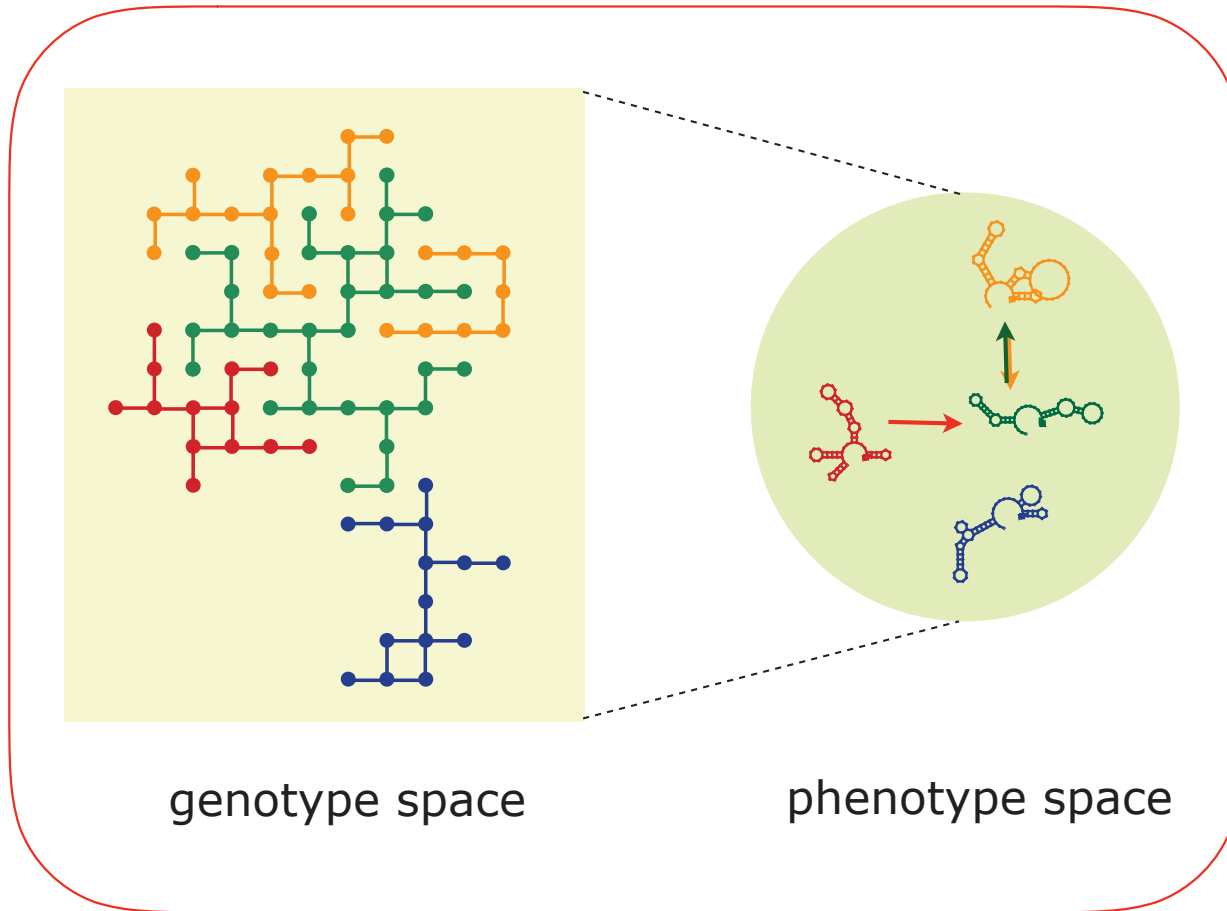


PREVIOUS LECTURES

1. The Topology of the Possible
(La représentation de l'information biologique)

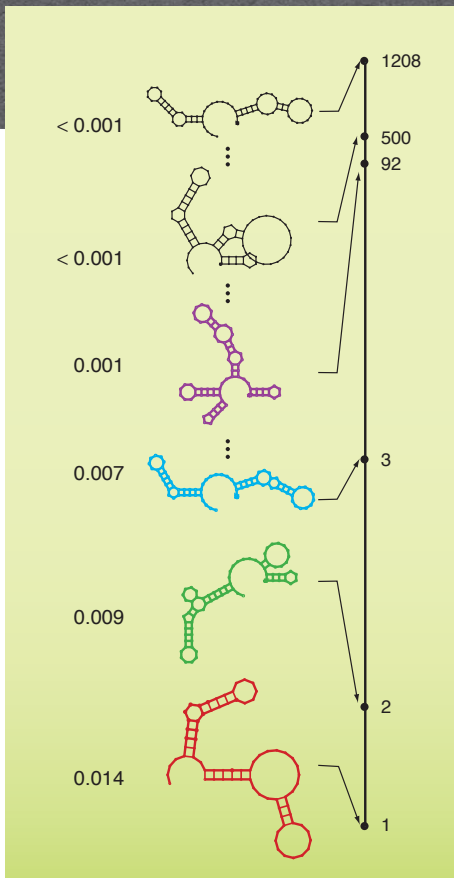
TAKE HOME



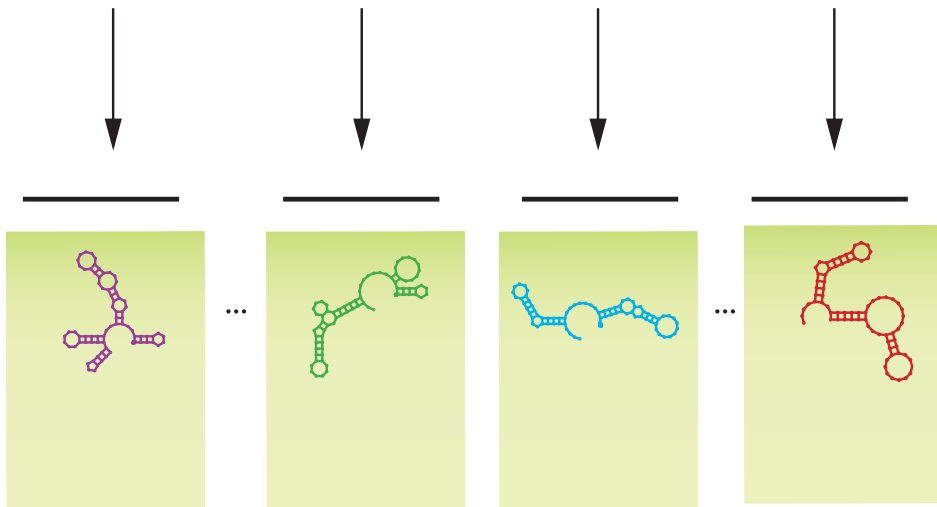
- ▶ “typical shapes”
- ▶ shape space covering
- ▶ neutral networks
- ▶ accessibility

◆ **evolvability**: robustness enables change

◆ **continuity in evolution**: nearness via accessibility



GCUGUUAUCGGCGCUCCGUACUACGCUUAAAAACAGGACAGUUGGGAUACUUGCAAACCAGGUUCAUCUUGUGA



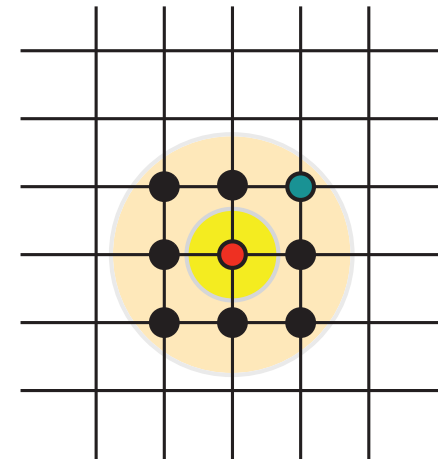
$$\left. \frac{\partial \text{pheno}}{\partial \text{env}} \right|_{\text{geno}}$$

$$\left. \frac{\partial \text{pheno}}{\partial \text{geno}} \right|_{\text{env}}$$

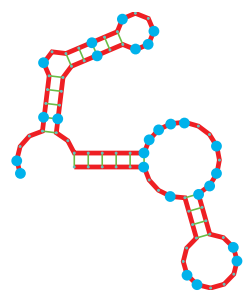
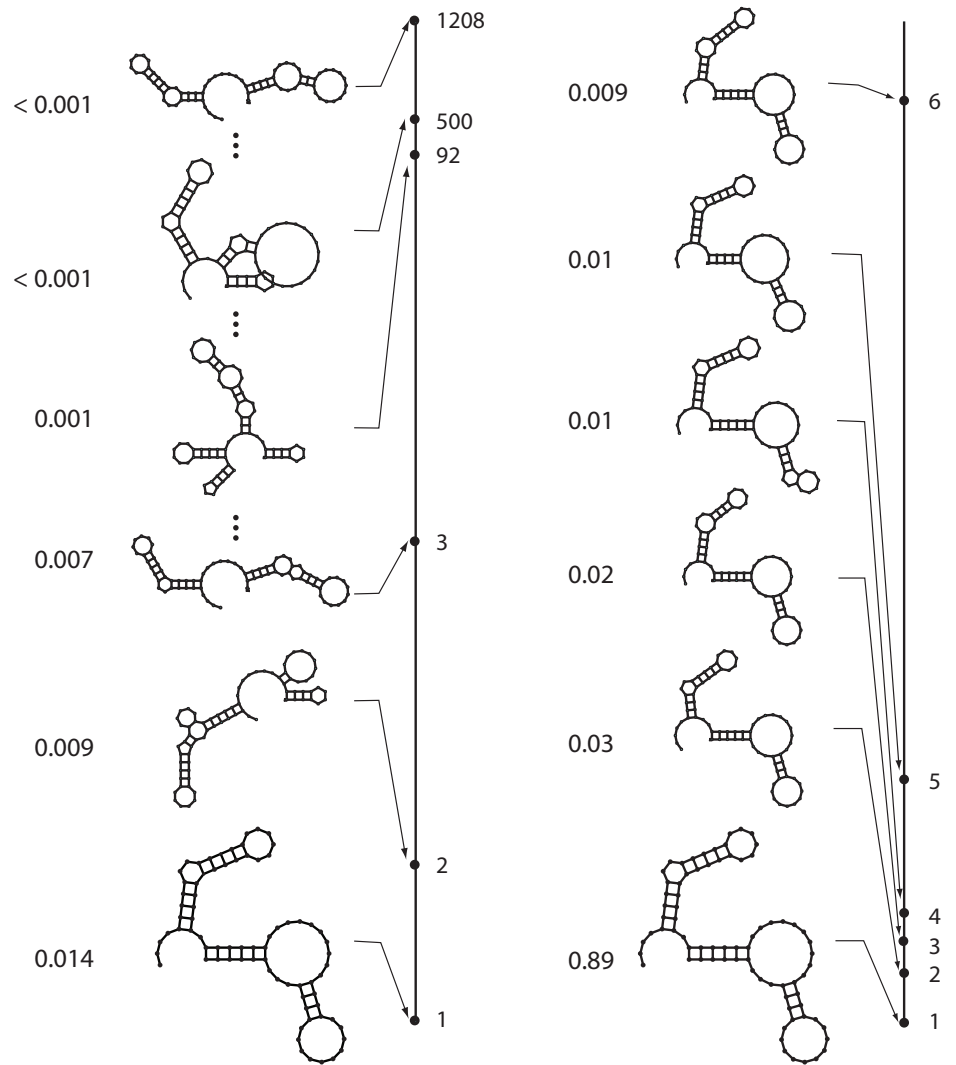


▣ **plasticity mirrors variability**

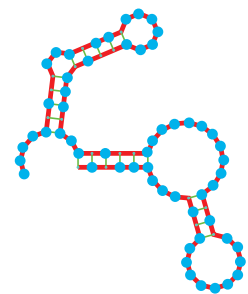
▸ potential speed-up of evolution
(Baldwin effect)



CANALIZATION



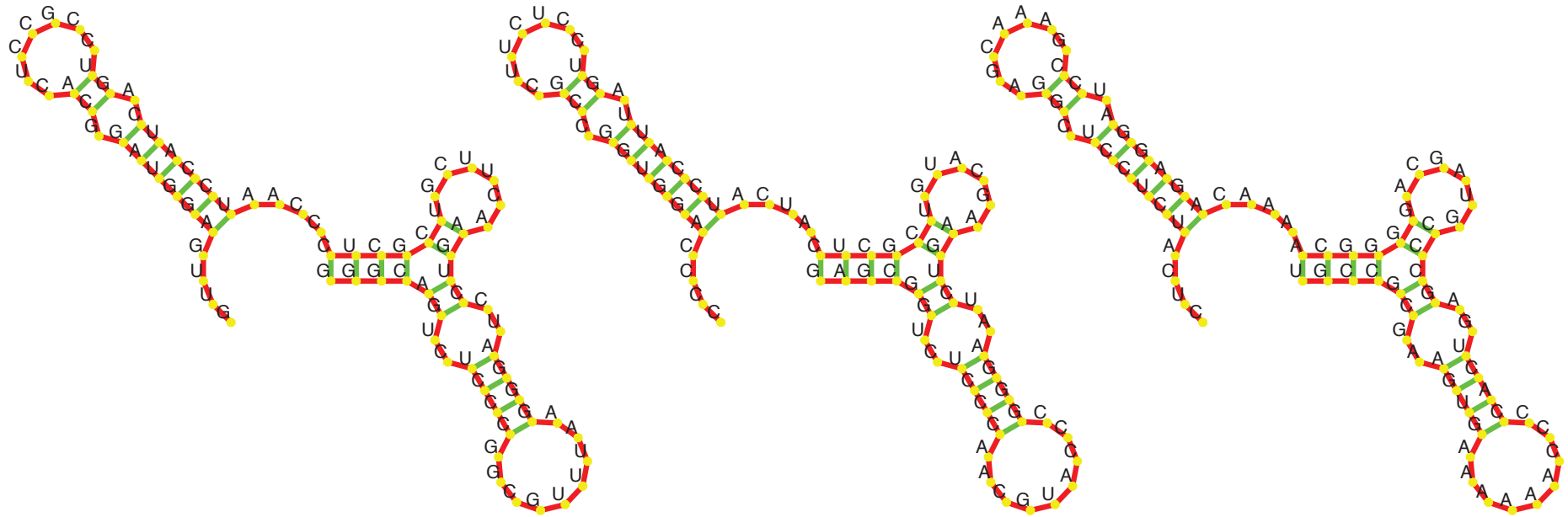
random



evolved

evolutionary reduction of plasticity
in a constant environment

WHICH STRUCTURE IS MODULAR?

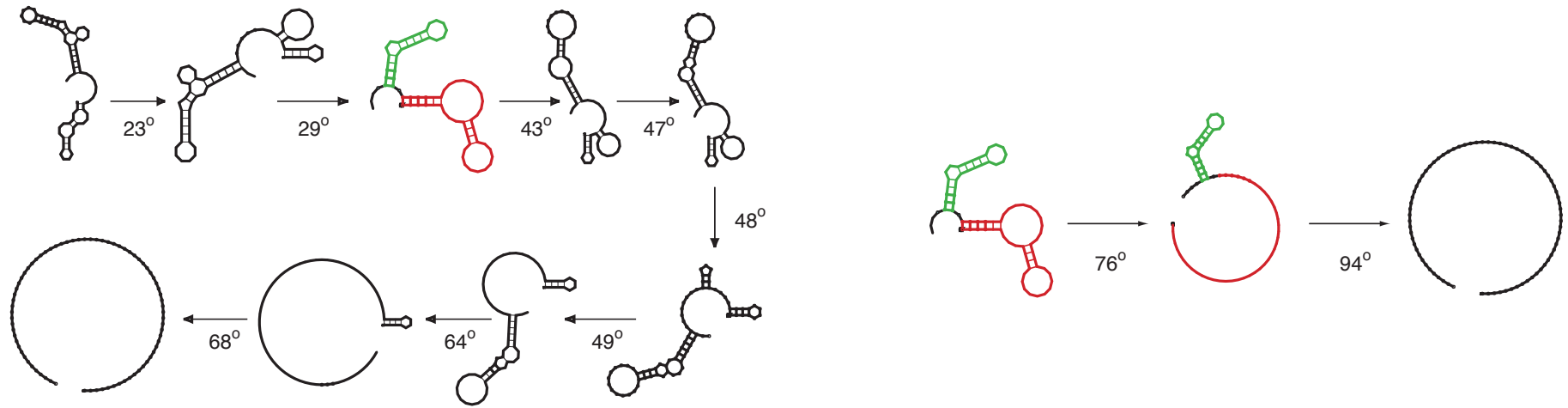


random

neutral evolution

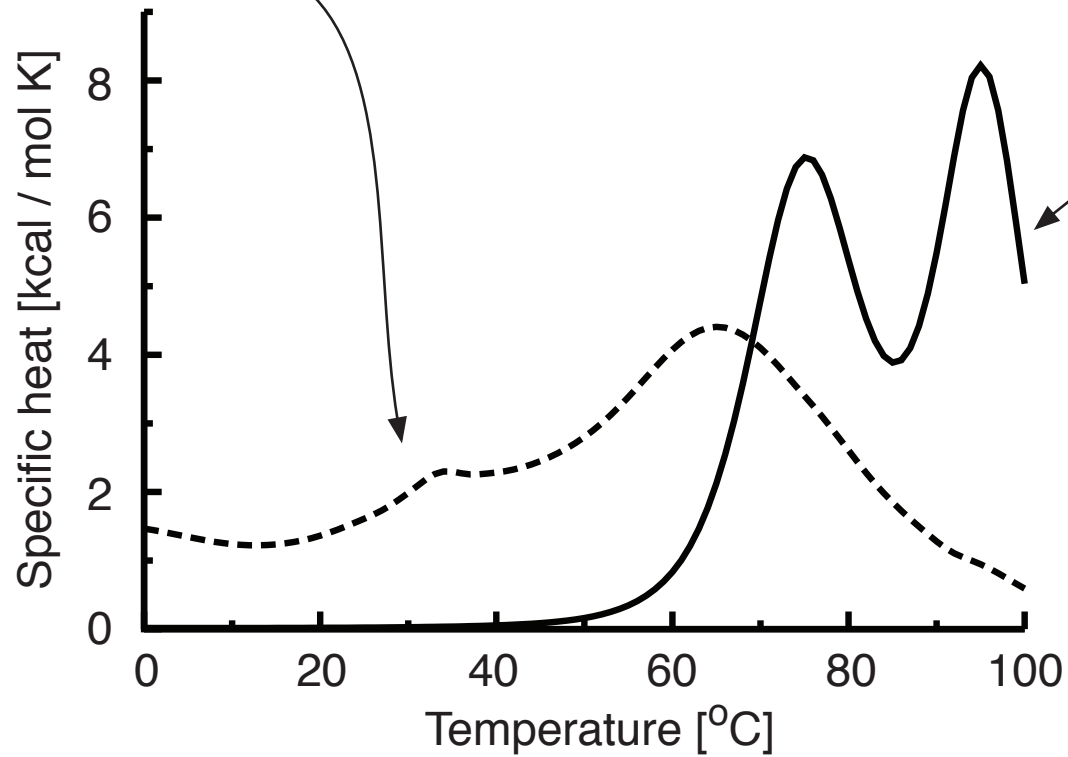
canalized

THERMO-PHYSICAL MODULARITY

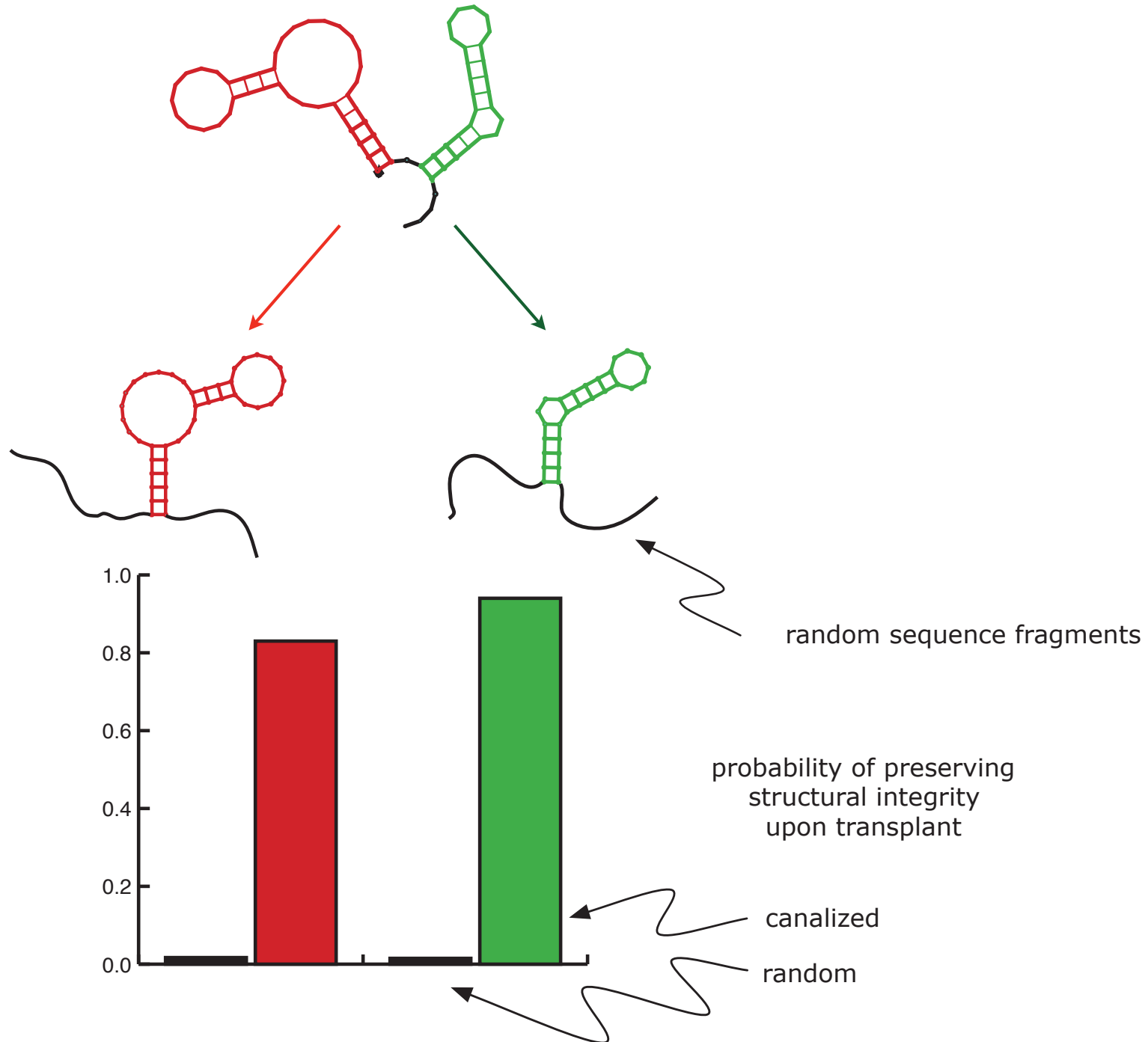


random

canalized



CONTEXT INDEPENDENCE (AUTONOMY)



NEUTRAL EVOLUTION OF THE PREDECESSOR FUNCTION...

$$\mathbf{pred} \equiv \lambda x_1.((x_1) \underbrace{\lambda x_2.((x_2) \lambda x_3.x_3) \lambda x_4.\lambda x_5.((x_2)x_4)(x_4)x_5)}_S \underbrace{\lambda x_6.(x_1) \lambda x_7.\lambda x_8.\lambda x_9.x_9}_A)$$

$$(\mathbf{pred})\mathbf{n} = (S)^n A_n$$

$$\mathbf{n} \equiv 0 \quad A_0 \equiv \mathbf{0} \quad \mathbf{n} > 0 \quad A_{n>0} \equiv A'$$

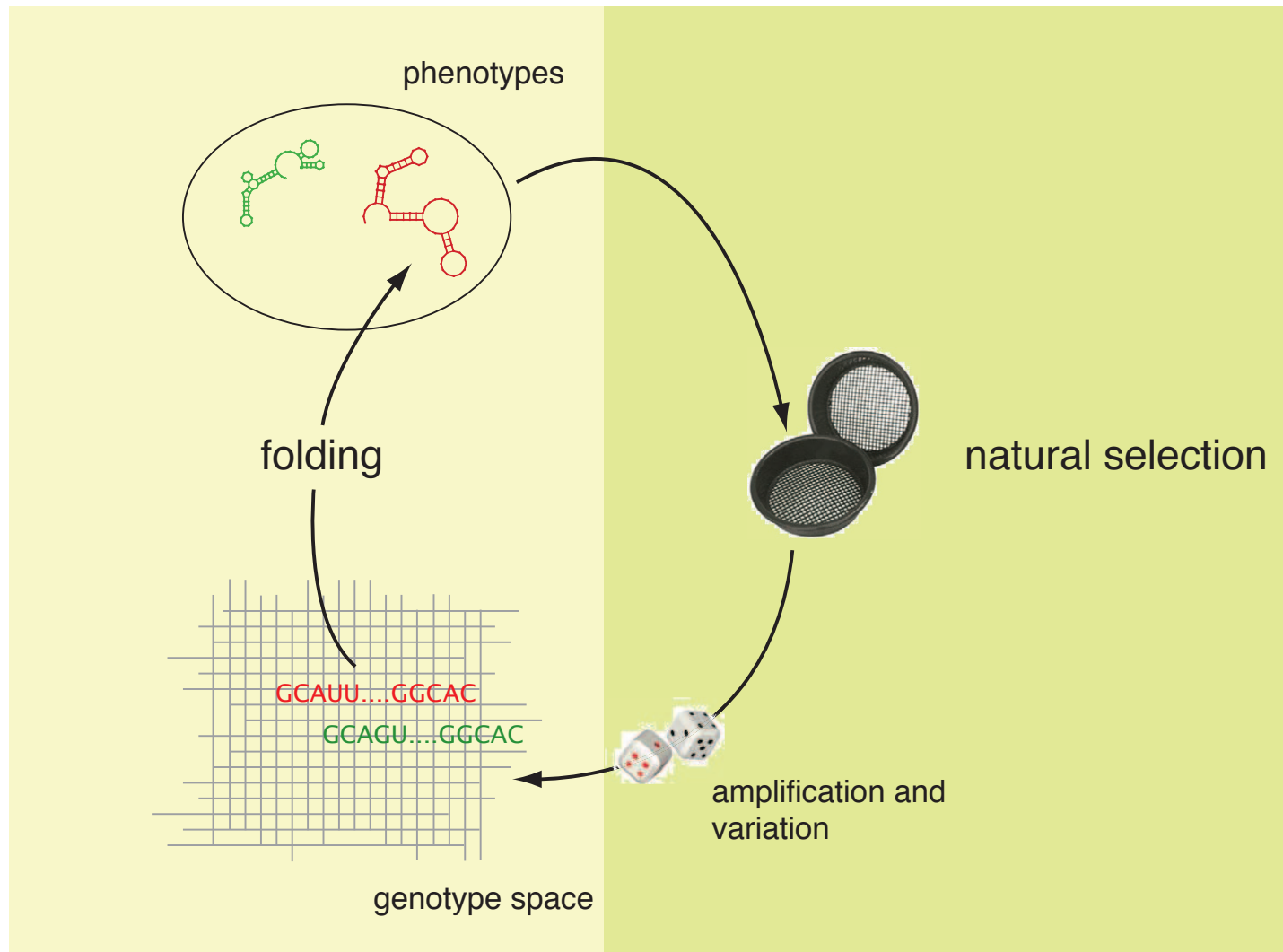
$$(S)A' \equiv \mathbf{0}$$

$$(S)^{n-1}\mathbf{0} \equiv \mathbf{n} - 1$$

2.

The Propagation of Genetic, Phenotypic,
and Molecular information

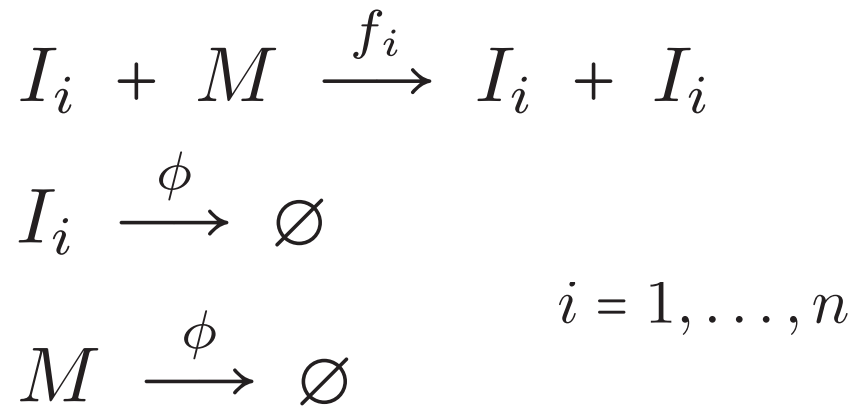
A SMALL SCALE MODEL OF (A CARTOON OF) EVOLUTION



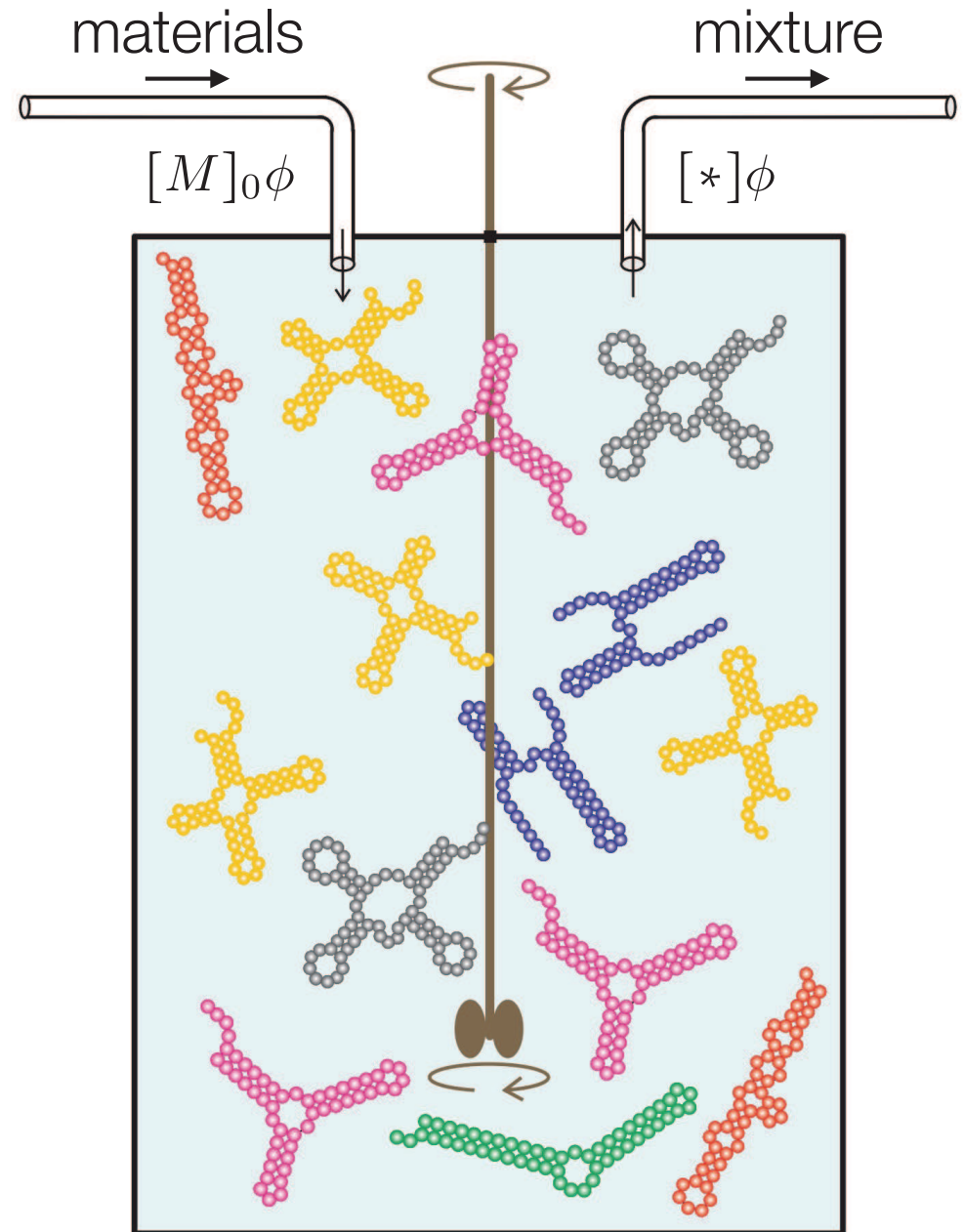
variation

selection

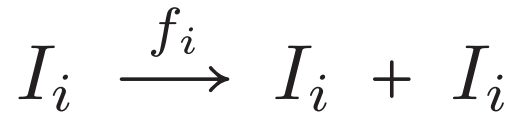
FLOW REACTOR @ "CONSTANT FLOW"



$$\frac{d}{dt}[I_i] = f_i[M][I_i] - \phi[I_i]$$



FLOW REACTOR @ "CONSTANT ORGANIZATION"



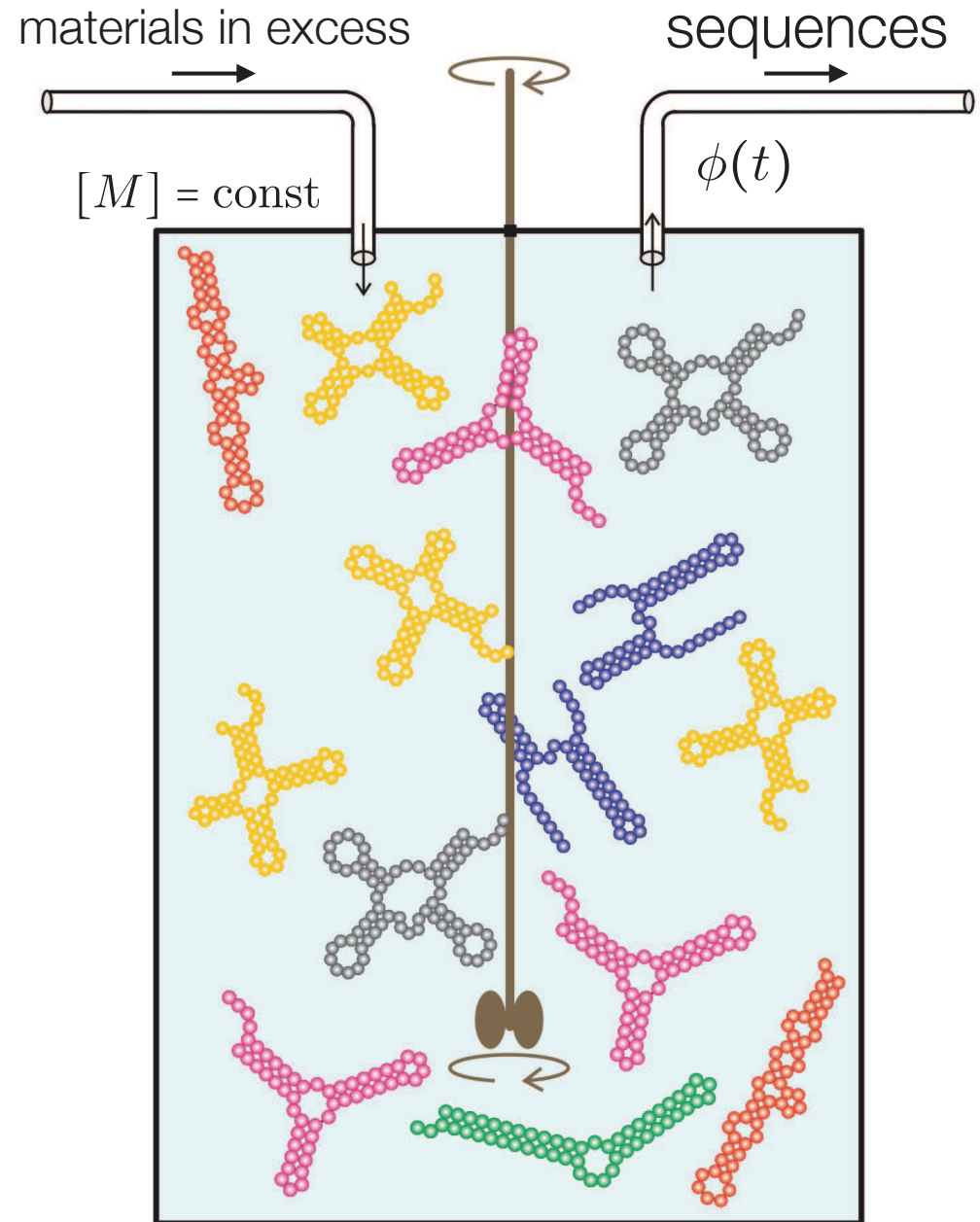
$$\frac{d}{dt}[I_i] = f_i[I_i] - \phi(t)[I_i]$$

$$\sum_i [I_i] = \text{const}$$

$$c_i(t) = [I_i]$$

$$\frac{d}{dt}c_i(t) = f_i c_i(t) - \phi(t)c_i(t)$$

$$\dot{c}_i = f_i c_i - \phi c_i$$



DARWINIAN SELECTION

$$\dot{c}_i = f_i c_i - \phi c_i$$

$$x_i = \frac{c_i}{\sum_{j=1}^n c_j} \quad \text{with} \quad \sum_{j=1}^n x_j = 1$$

$$\dot{x}_i = f_i x_i - \phi x_i$$

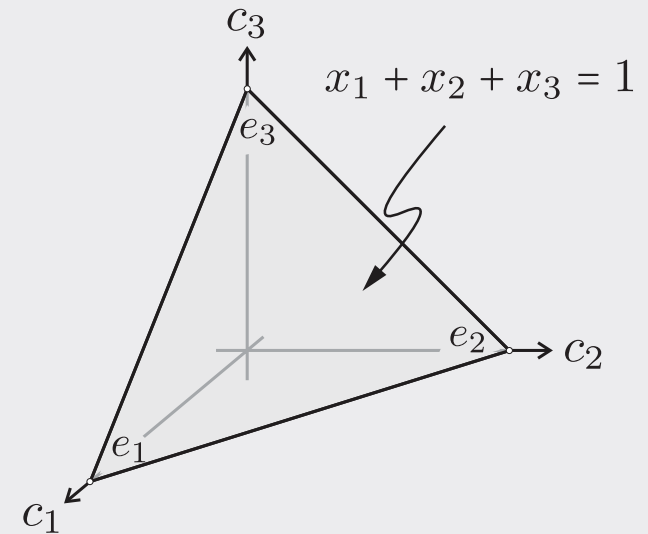
↓

$$\phi = \sum_{j=1}^n f_j x_j = \overline{f(t)}$$

$$\dot{x}_i = f_i x_i - \overline{f(t)} x_i = x_i (f_i - \overline{f(t)})$$

$$\phi(t) \text{ s.t. } \sum_i \dot{c}_i = 0$$

change to
relative concentrations



“Darwinian selection”

DARWINIAN SELECTION

$$\dot{x}_i = f_i x_i - \overline{f(t)} x_i = x_i \left(f_i - \overline{f(t)} \right)$$

$$f_m = \max\{f_i; i = 1, \dots, n\}$$

$$\lim_{t \rightarrow \infty} x_m(t) = 1$$

$$\lim_{t \rightarrow \infty} x_i(t) = 0, \quad \forall i \neq m$$

Note:

$$\begin{aligned} \frac{d}{dt} \phi &= \sum_j f_j \dot{x}_j = \sum_j f_j \left(f_j x_j - x_j \sum_k f_k x_k \right) \\ &= \overline{f^2} - \overline{f}^2 = \text{var}(f) \end{aligned}$$

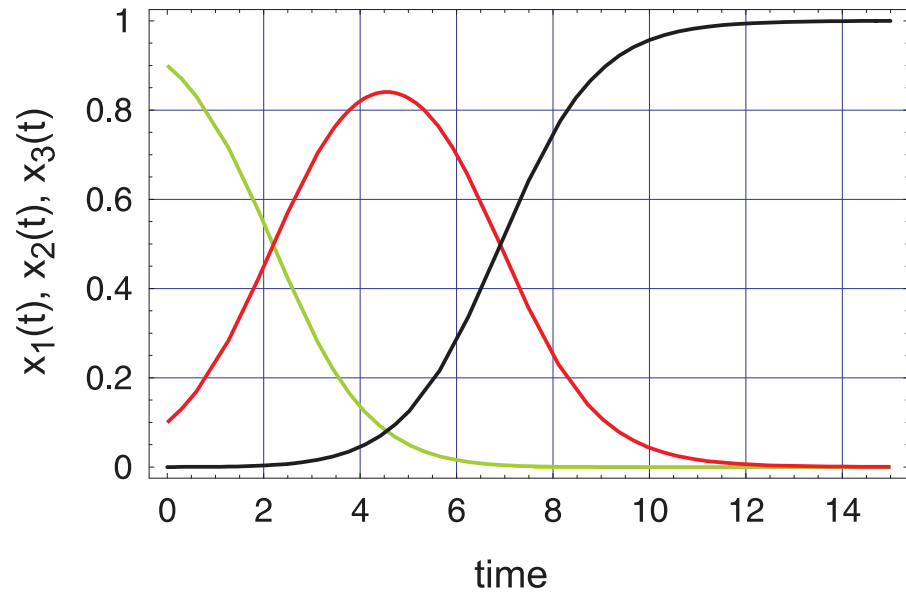
“Darwinian selection”

assume a maximal f_i

asymptotic behavior

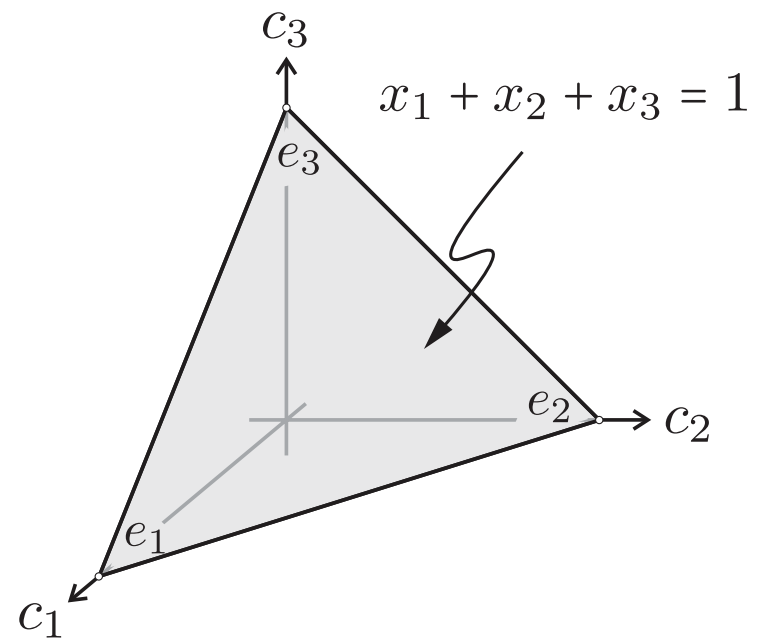
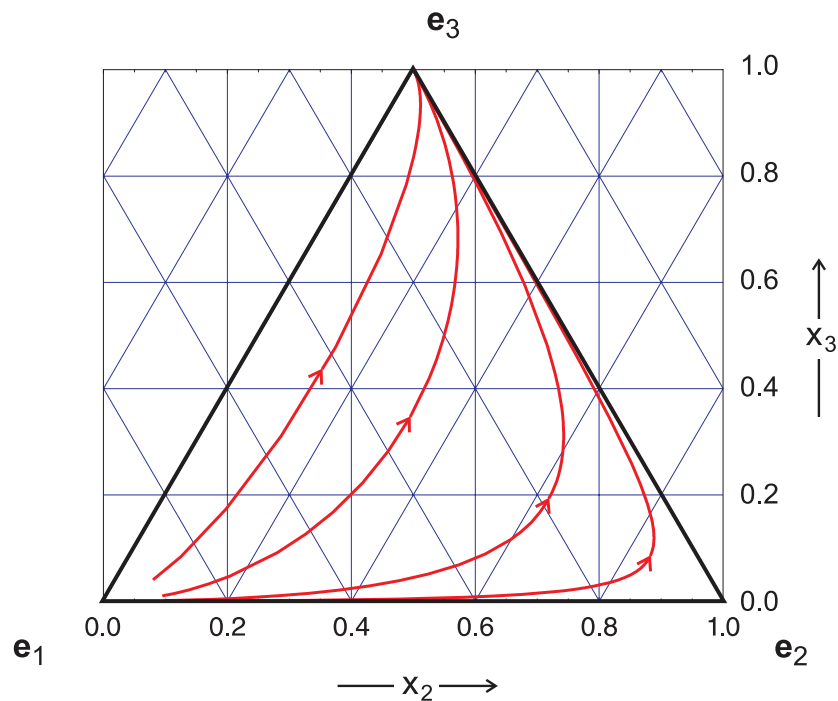
cf. Fisher’s fundamental theorem

DARWINIAN SELECTION



$$f_1 = 1, \quad f_2 = 2, \quad f_3 = 3$$

$$(x_1(0), x_2(0), x_3(0)) = (0.9000, 0.0999, 0.0001)$$

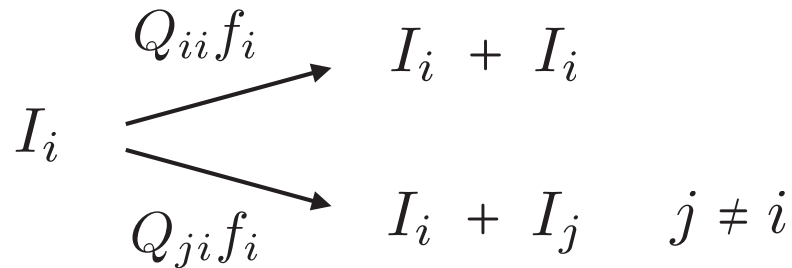


courtesy of Peter Schuster, Vienna

DARWINIAN SELECTION WITH MUTATION

$$\dot{x}_i = f_i x_i - \phi x_i \quad \phi = \sum_{j=1}^n f_j x_j = \overline{f(t)}$$

no mutation



include mutation

Q_{ij} is the rate of production of i from j

$$\text{with } \sum_{i=1}^n Q_{ij} = 1$$

$$\dot{x}_i = \sum_{j=1}^n Q_{ij} f_j x_j - \phi x_i \quad \phi = \sum_{j=1}^n f_j x_j = \overline{f(t)}$$

$$Q = \begin{pmatrix} Q_{11} & Q_{12} & \dots & Q_{1n} \\ Q_{21} & Q_{22} & \dots & Q_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ Q_{n1} & Q_{n2} & \dots & Q_{nn} \end{pmatrix}$$

nonlinear transform (integrating factor)

$$z_i(t) = x_i(t) \exp\left(\int_0^t \phi(\tau) d\tau\right)$$

$$\dot{z}_i = \sum_{j=1}^n Q_{ij} f_j z_j$$

coupled *linear* system

DARWINIAN SELECTION WITH MUTATION

$$\dot{z}_i = \sum_{j=1}^n Q_{ij} f_j z_j$$

$$\dot{\mathbf{z}} = \mathbf{W} \mathbf{z}$$

$$\mathbf{L}^{-1} \mathbf{W} \mathbf{L} = \mathbf{\Lambda}$$

$$\zeta(t) = \mathbf{L}^{-1} \mathbf{z}(t) \quad \mathbf{z}(t) = \mathbf{L} \zeta(t)$$

$$\mathbf{L}^{-1} \dot{\mathbf{z}} = \mathbf{L}^{-1} \mathbf{W} \mathbf{z} = \mathbf{L}^{-1} \mathbf{W} \mathbf{L} \zeta$$

$$\dot{\zeta} = \mathbf{\Lambda} \zeta$$

$$\zeta_k t = \zeta_k(0) \exp(\lambda_k t)$$

diagonal
 $\mathbf{W} = \mathbf{Q}\mathbf{F}$
positive off-diagonal elements

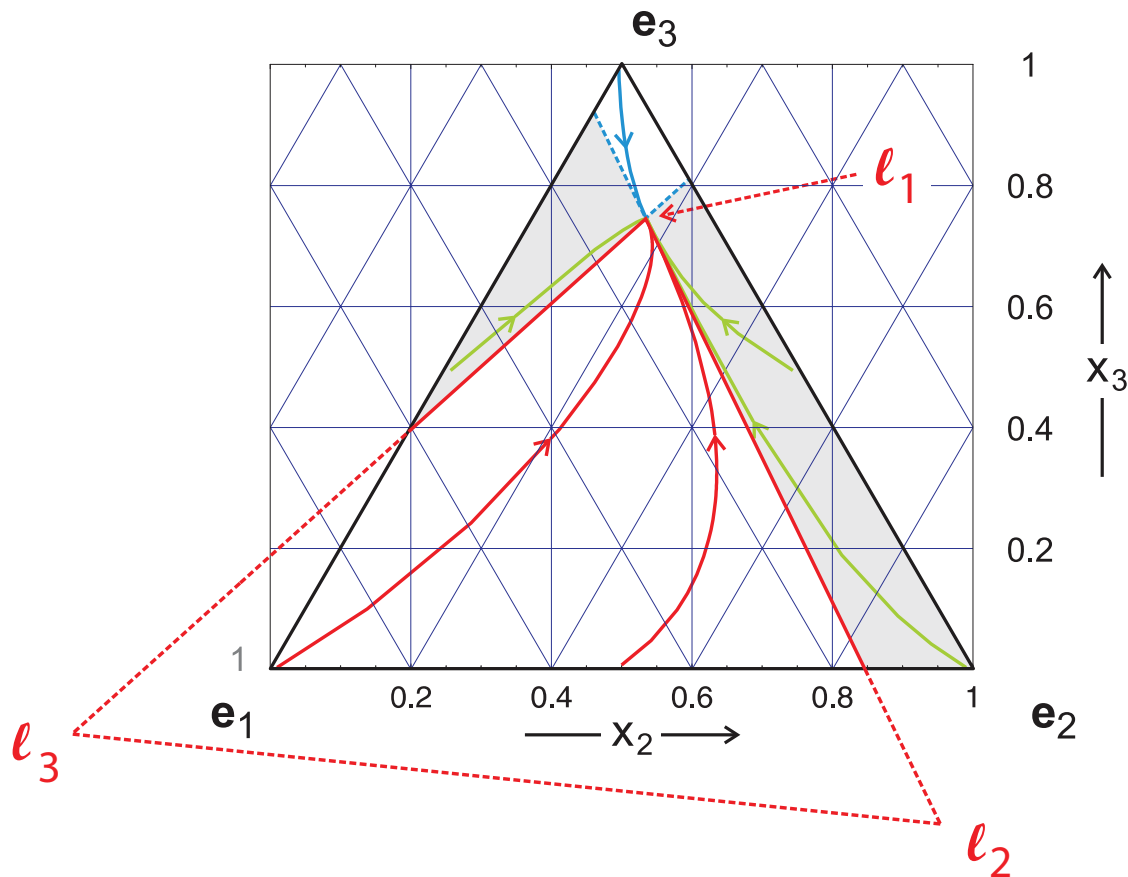
standard linear algebra

Perron-Frobenius applies

THE QUASISPECIES

$$\mathbf{x}(t) = \sum_{i=1}^n x_i(t) \mathbf{e}_i = \sum_{k=1}^n \xi_k(t) \mathbf{l}_k$$

$$\dot{\xi}_k = \xi_k (\lambda_k - \phi) \quad \phi = \sum_k \lambda_k \xi_k = \bar{\lambda}$$



$$f_1 = 1.9, f_2 = 2.0, f_3 = 2.1 \quad Q_{ii} = 0.98, Q_{ij} = 0.01$$

change of coordinates
eigenvectors of \mathbf{W}

same form as before

$$\text{and also } \frac{d}{dt} \phi = \bar{\lambda}^2 - \bar{\lambda}^2$$

\mathbf{l}_1 — the “quasi-species”

white/red — increasing \bar{f}

white/blue — non-increasing \bar{f}

grey/green — possibly
non-monotonic \bar{f}

ERROR THRESHOLD

$$\dot{x}_i = \sum_{j=1}^n Q_{ij} f_j x_j - \phi x_i \quad \phi = \sum_{j=1}^n f_j x_j = \overline{f(t)}$$

$$\dot{x}_m = Q_{mm} f_m x_m - \phi x_m = (Q_{mm} f_m - \phi) x_m$$

$$\dot{x}_{j \neq m} = Q_{jj} f_j x_j + Q_{jm} f_m x_m - \phi x_j$$

$$\phi = f_m x_m + f \sum_{j \neq m} x_j = f_m x_m + f(1 - x_m)$$

$$\dot{x}_m = 0 \Rightarrow \phi = Q_{mm} f_m$$

$$\bar{x}_m = \frac{Q_{mm} \sigma_m - 1}{\sigma_m - 1} \quad \text{with} \quad \sigma_m = \frac{f_m}{f}$$

$$\bar{x}_m > 0 \Rightarrow Q_{mm} \sigma_m > 1$$

neglect “backflow”

$$\sum_{i \neq m} Q_{mi} f_i x_i \stackrel{!}{=} 0$$

“single-peak” landscape

$$f_m > f_i = f \quad \forall i \neq m$$

solve

σ_m superiority of master

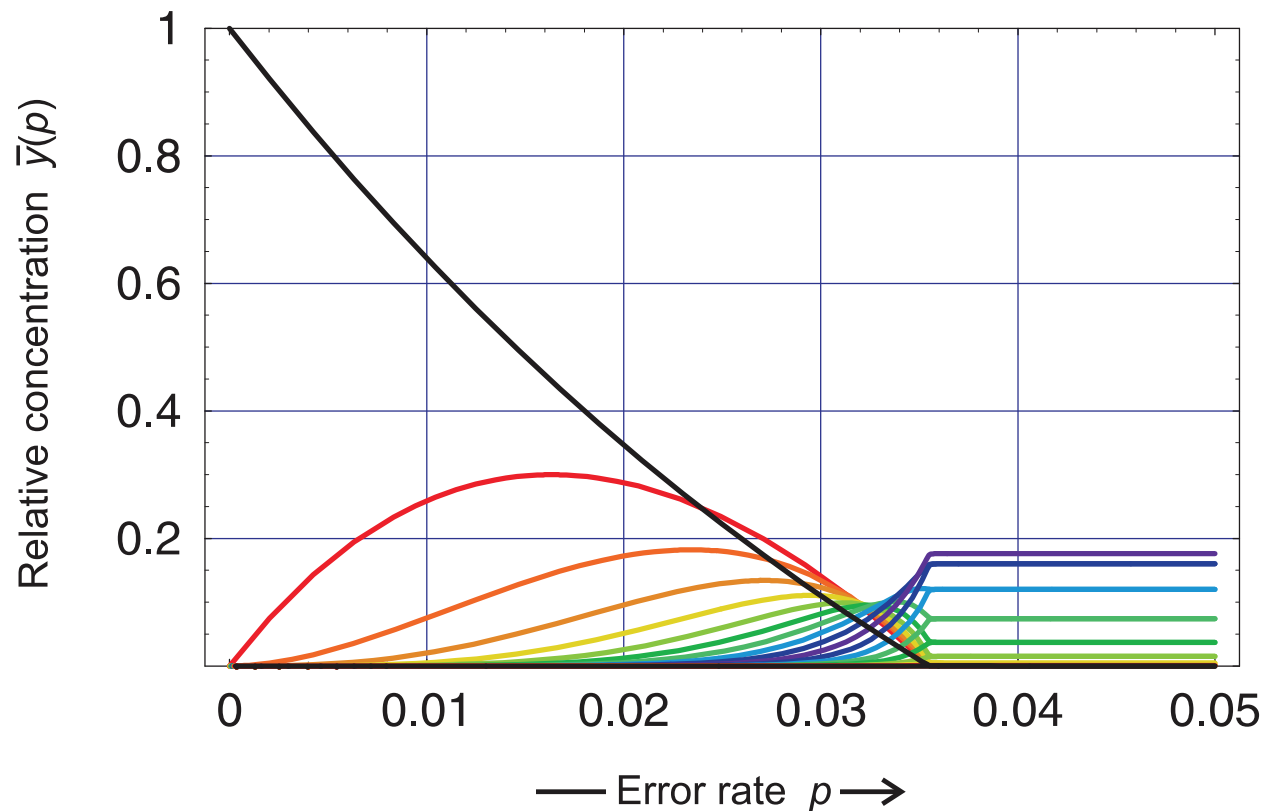
“error threshold”

ERROR THRESHOLD

$$\bar{x}_m > 0 \Rightarrow Q_{mm}\sigma_m > 1$$

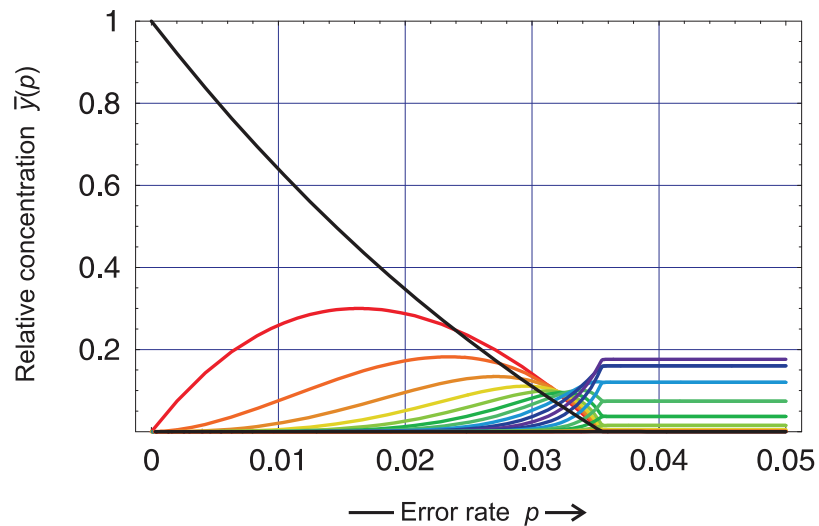
$$\text{uniform error model: } Q_{mm} = (1 - p)^l$$

$$p_c = 1 - \sigma_m^{-\frac{1}{l}} \approx \frac{\ln \sigma_m}{l} \quad \text{or} \quad l_{\max} = \frac{\ln \sigma_m}{p}$$

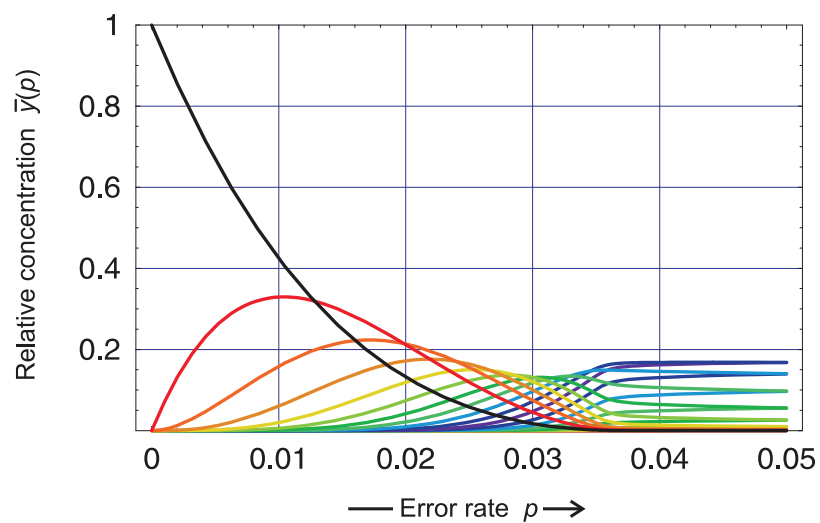


ERROR THRESHOLDS ON LANDSCAPES

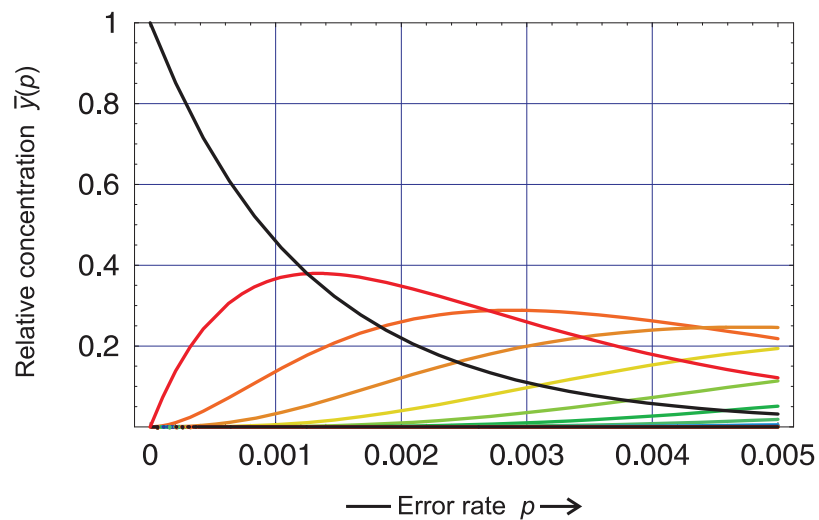
single-peak



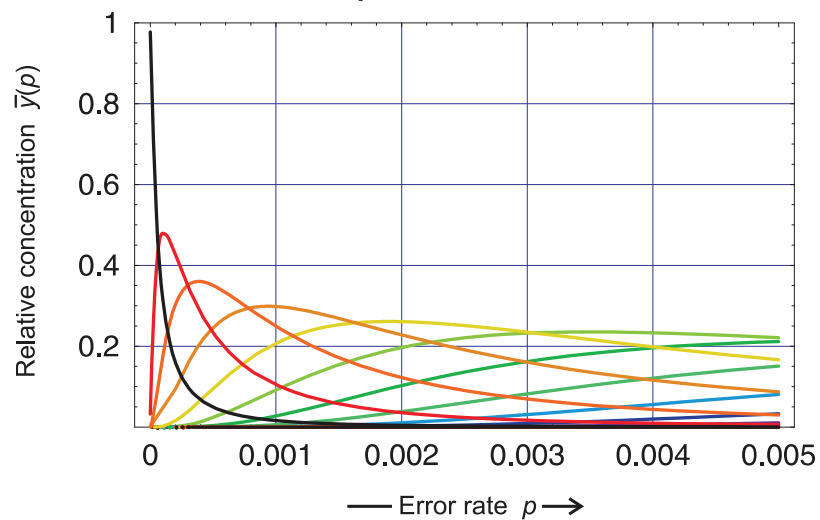
hyperbolic



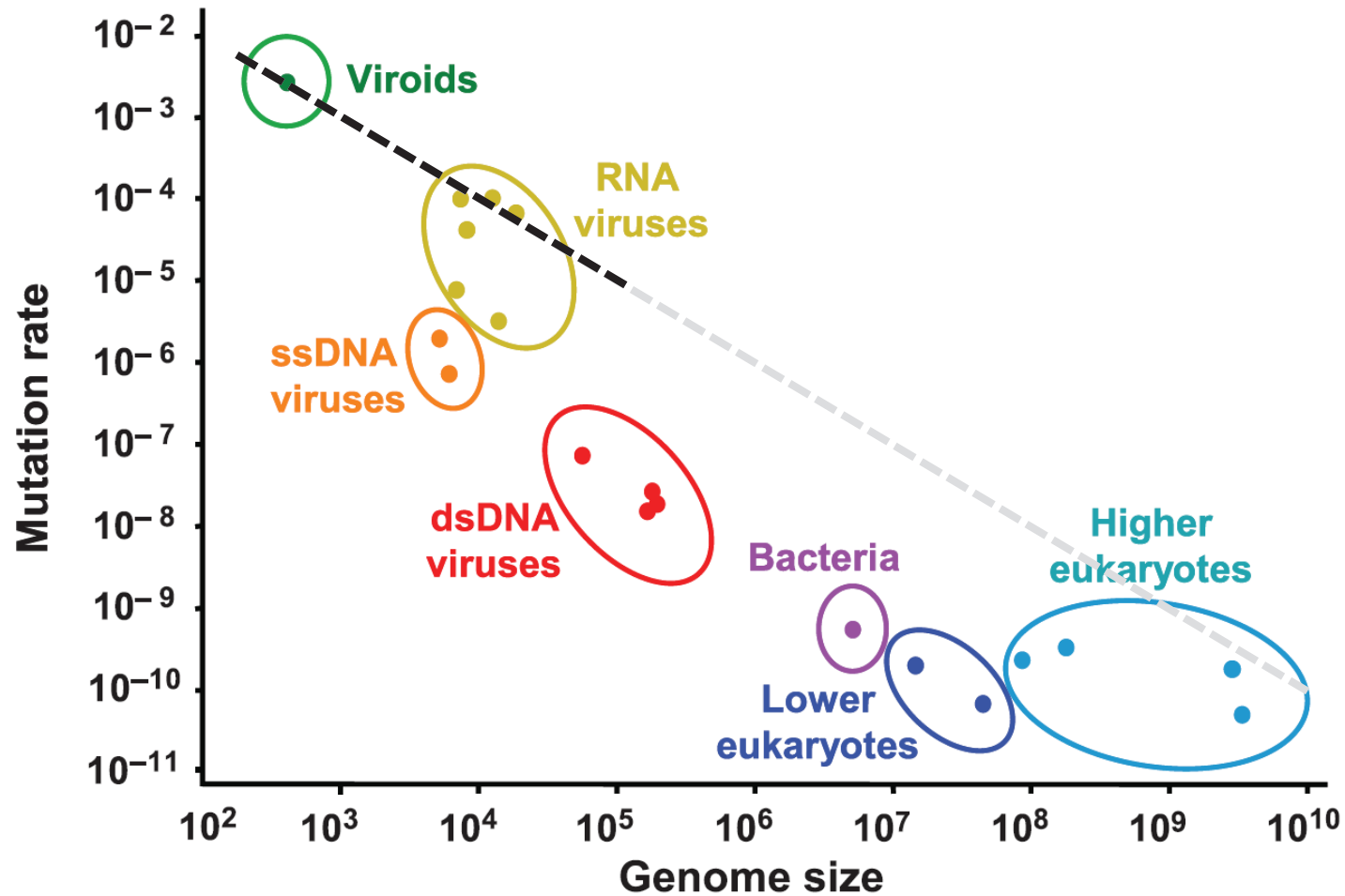
linear



quadratic



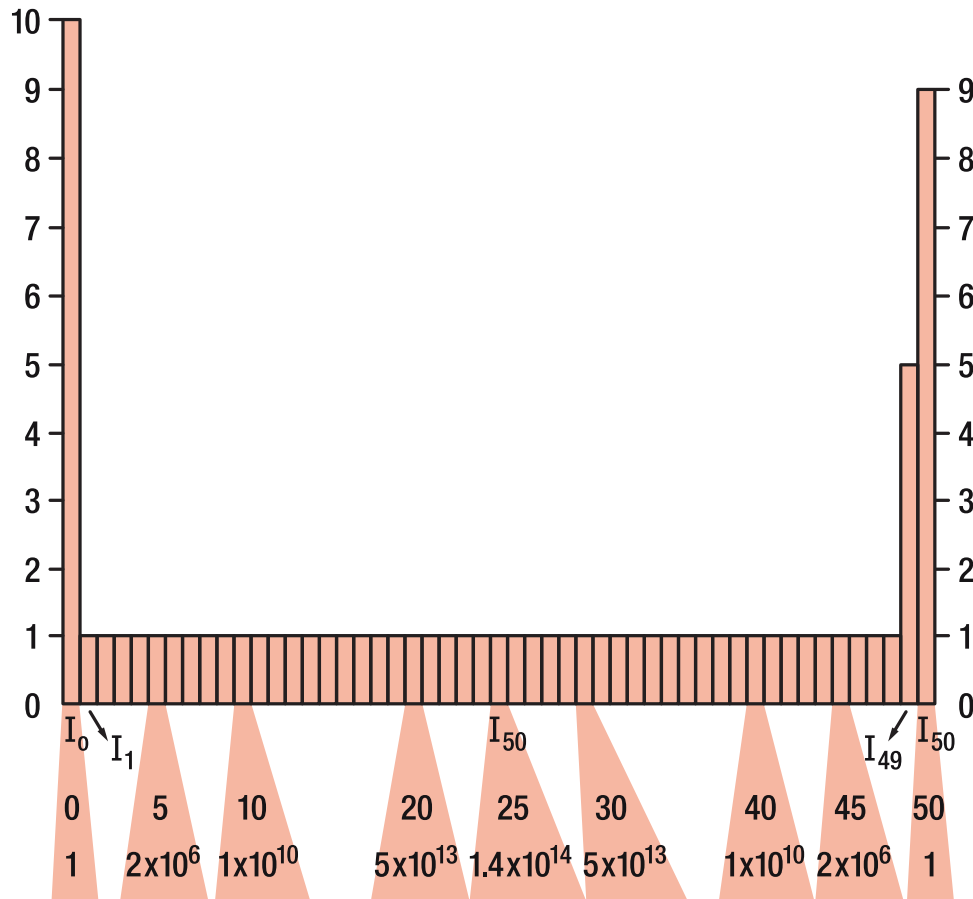
MUTATION RATES AND GENOME SIZE



Selma Gago, Santiago F. Elena, Ricardo Flores, Rafael Sanjuán. 2009, Extremely high mutation rate of a hammerhead viroid. *Science* **323**:1308

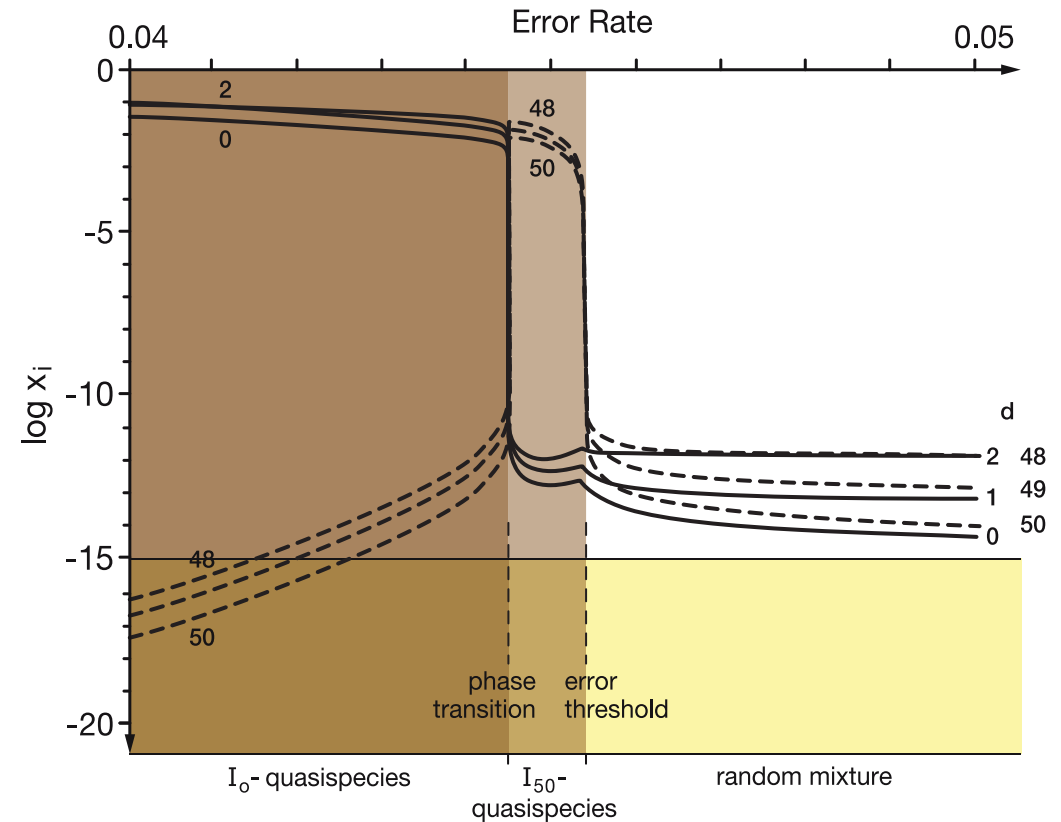
THE QUASISPECIES IS THE UNIT OF SELECTION

two-peak landscape



error class

stationary distributions



QUASISPECIES AND POPULATION GENETICS

quasispecies

$$\dot{x}_i = \sum_{j=1}^n Q_{ij} f_j x_j - \overline{f(t)} x_i$$

$$\dot{x}_i = (f_i - \overline{f(t)}) x_i + \sum_{j=1}^n \mu_{ij} x_j$$

$$\dot{\mathbf{x}} = (\mathbf{W} - \overline{f(t)}) \mathbf{x}$$

$\mathbf{W} = \mathbf{QF}$

$\mathbf{W} = \boldsymbol{\mu} + \mathbf{F}$

selection-mutation model

PHENOTYPIC ERROR THRESHOLD

$$\dot{x}_i = \sum_{j=1}^n Q_{ij} f_j x_j - \phi x_i \quad \phi = \sum_{j=1}^n f_j x_j = \overline{f(t)}$$

neglect “backflow”

$$\sum_{i \neq m} Q_{mi} f_i x_i \stackrel{!}{=} 0$$

$$\downarrow$$

$$\dot{x}_m = Q_{mm} f_m x_m - \phi x_m = (Q_{mm} f_m - \phi) x_m$$

“single-peak” landscape

$$f_m > f_i = f \quad \forall i \neq m$$

$$\eta_m = \sum_{i=1}^k x_i \quad i = 1, \dots, k$$

equivalence classes

$$\dot{\eta}_m = \sum_{i=1}^k \dot{x}_i = ((Q_{kk} + \lambda_m (1 - Q_{kk})) f_m - \phi) \eta_m$$

include mutational
flow within neutral network

fraction of neutral mutants
(all equally accessible)

$$p_c = 1 - \left(\frac{1 - \lambda_m \sigma_m}{(1 - \lambda_m) \sigma_m} \right)^{1/l}$$

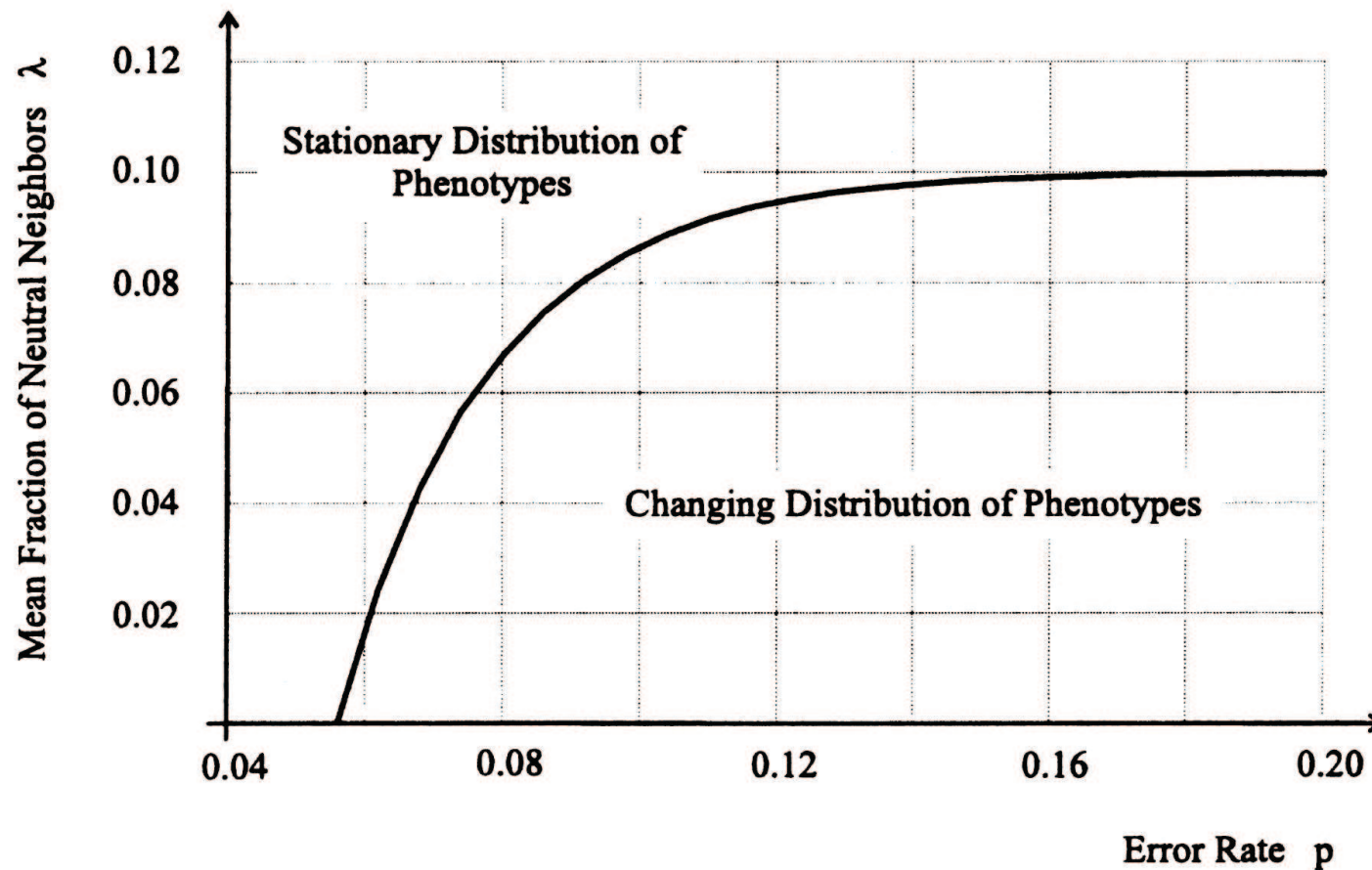
“phenotypic error threshold”

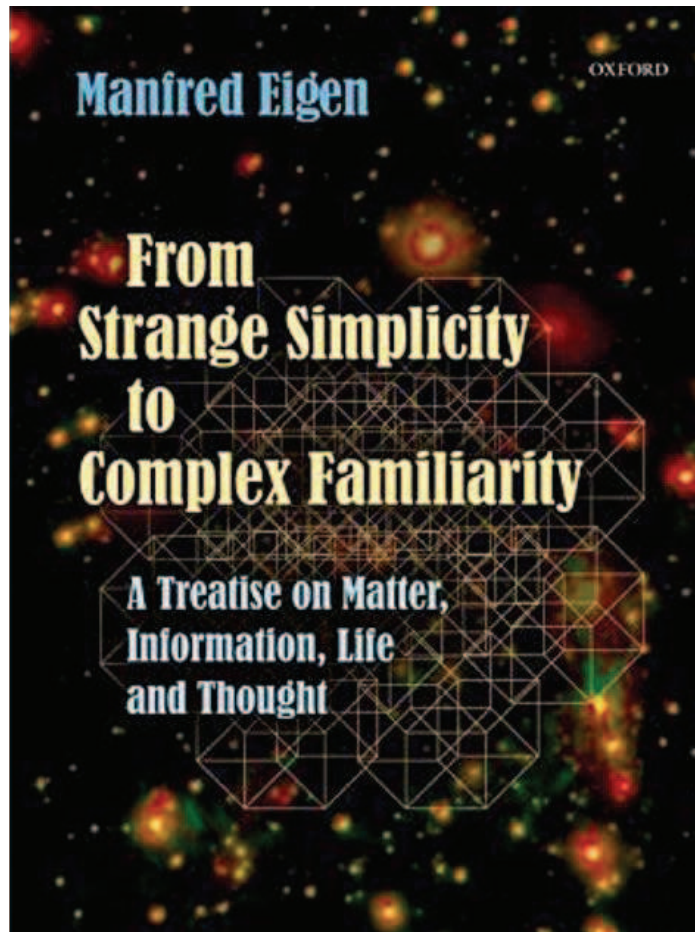
PHENOTYPIC ERROR THRESHOLD

$$p_c = 1 - \left(\frac{1 - \lambda_m \sigma_m}{(1 - \lambda_m) \sigma_m} \right)^{1/l}$$

sequence length
superiority of master network
fraction of neutral mutants

P. Schuster, W. Fontana / Physica D 133 (1999) 427–452



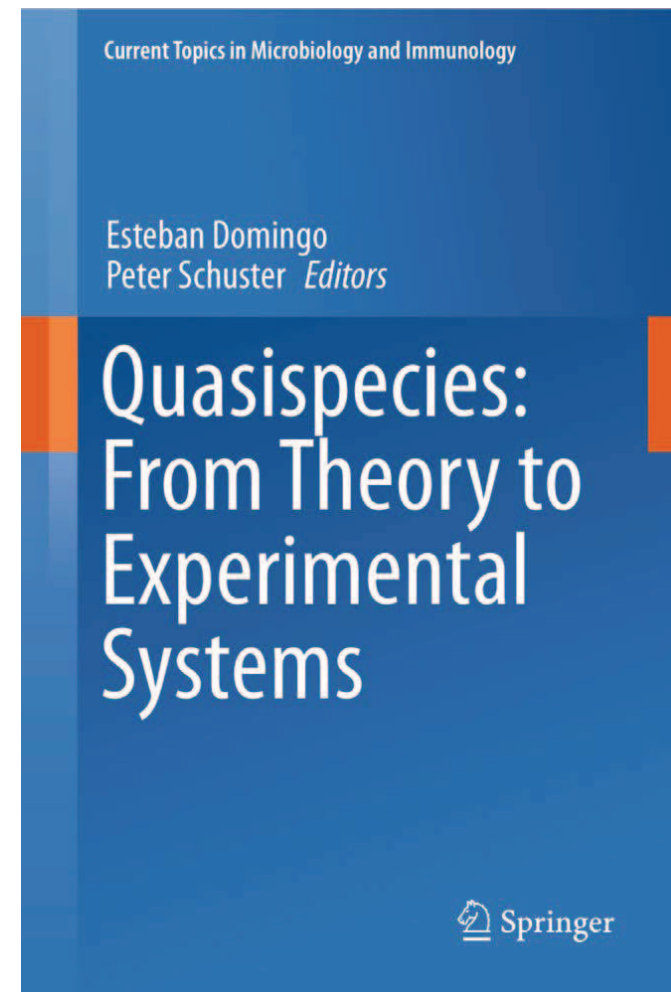


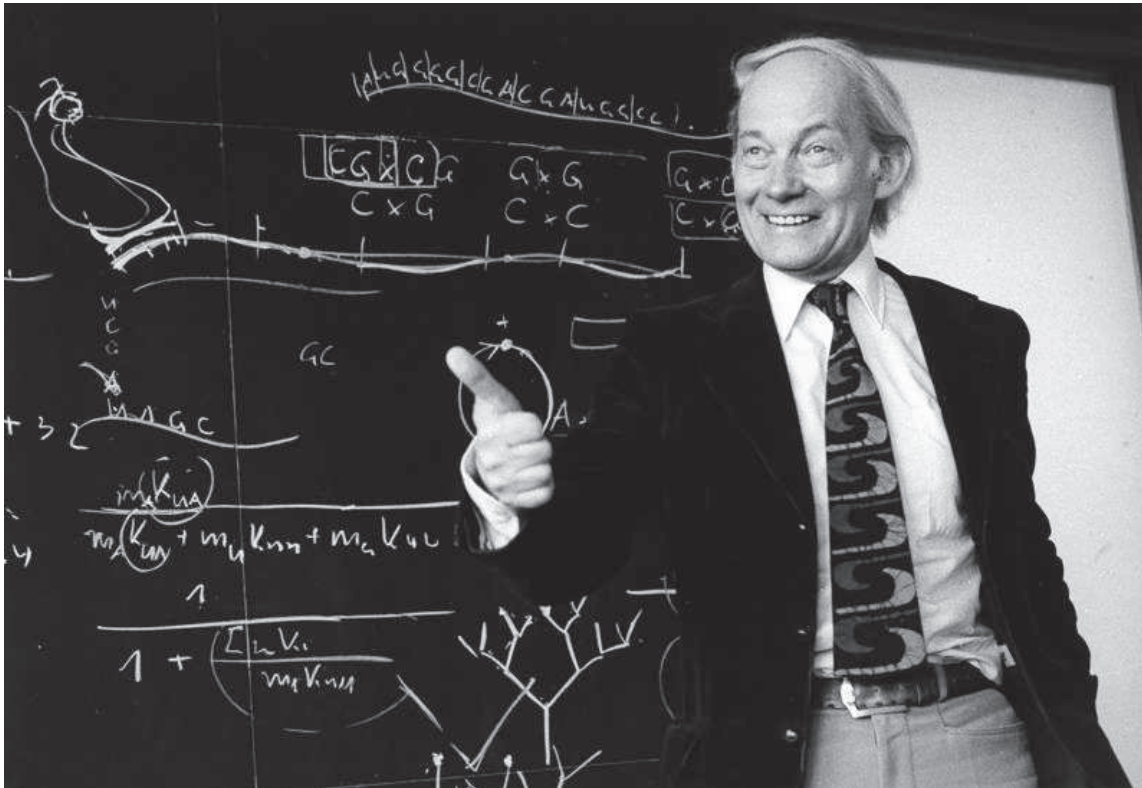
Peter Schuster, *“The Mathematics of Darwinian Systems”*, Appendix in

Manfred Eigen *“From Strange Simplicity to Complex Familiarity: A Treatise on Matter, Information, Life and Thought”*, OUP, 2013

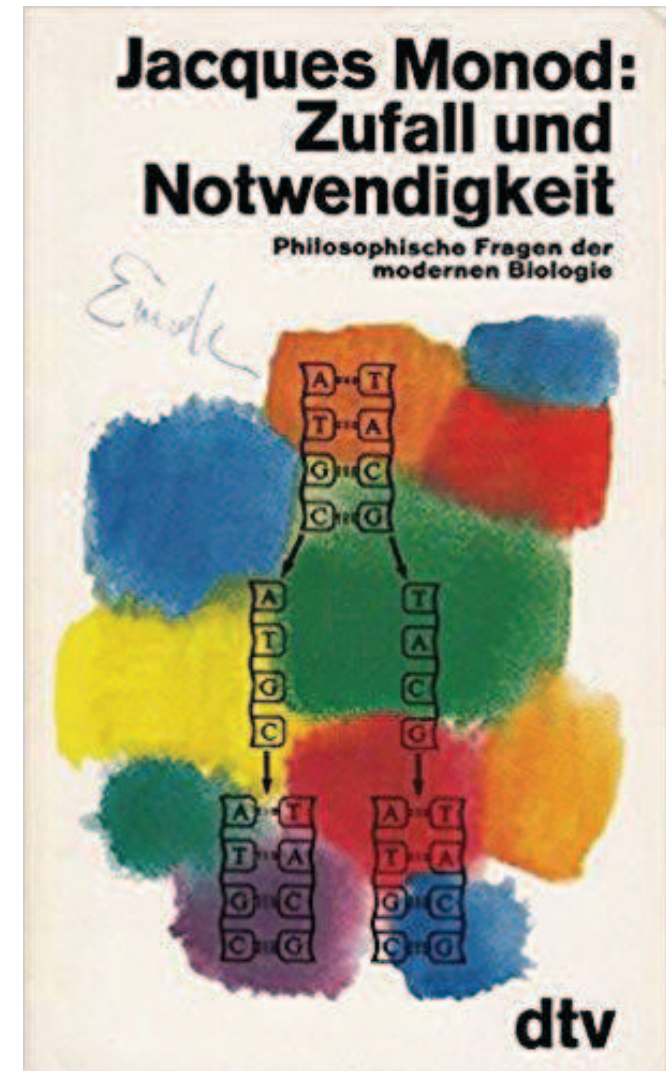
2016

especially chapters 1 and 4



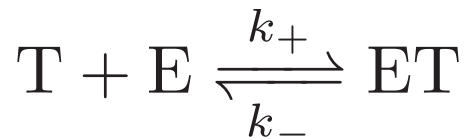
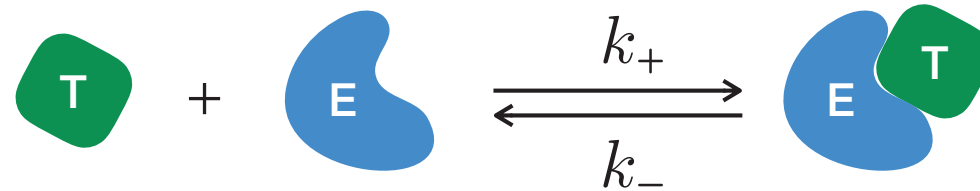


Manfred Eigen (1927-2019)



1971 German edition
preface by Manfred Eigen

BASICS



$v_+ = v_-$ kinetic equilibrium thermodynamic equilibrium $\Delta G = 0$

$$v_+ = k_+[E][T]$$

$$v_- = k_-[ET]$$

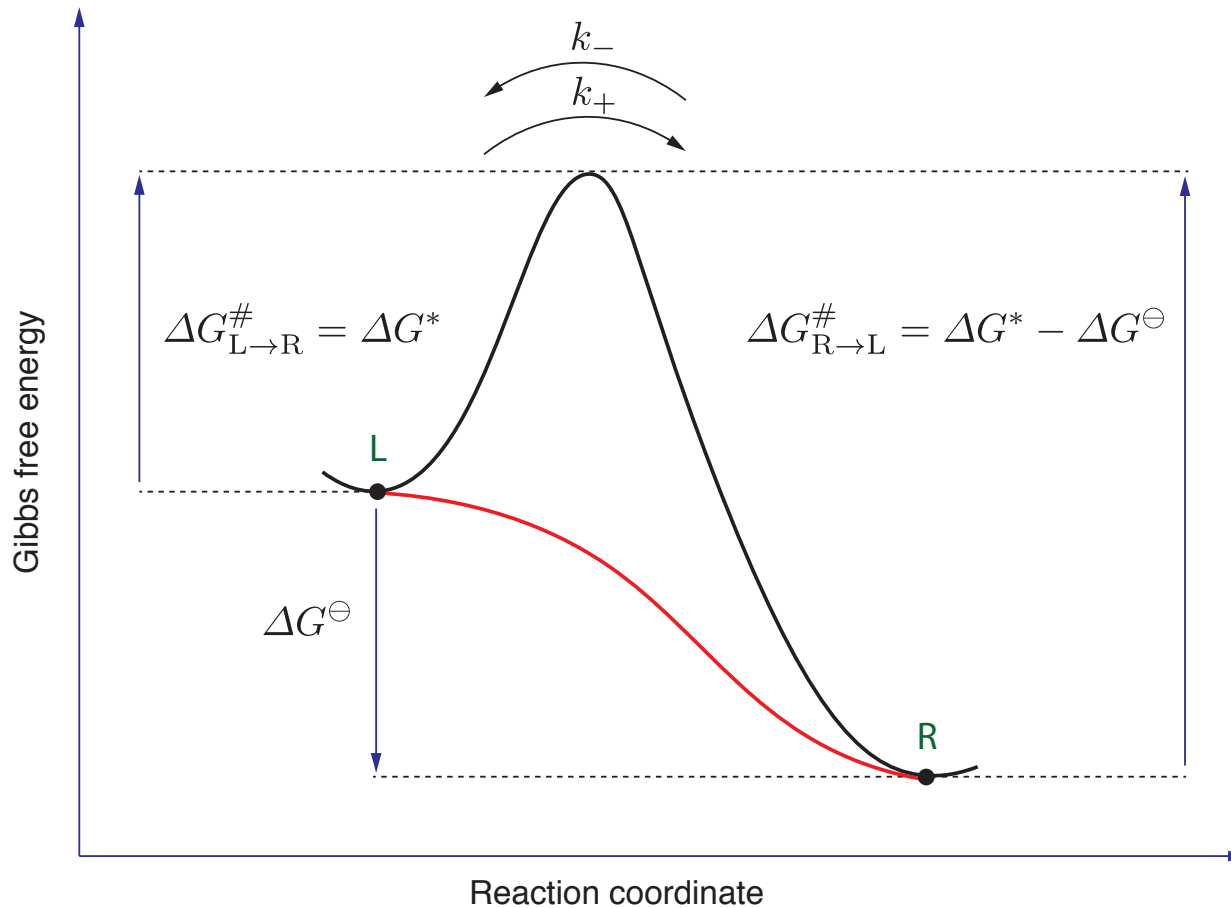
$$\frac{k_+}{k_-} = \underbrace{\frac{[ET]_{eq}}{[E]_{eq}[T]_{eq}}}_K = \exp\left(-\frac{\Delta G^\ominus}{RT}\right)$$

reaction velocity (flux)

equilibrium constant

connects energetics with kinetics

BASICS

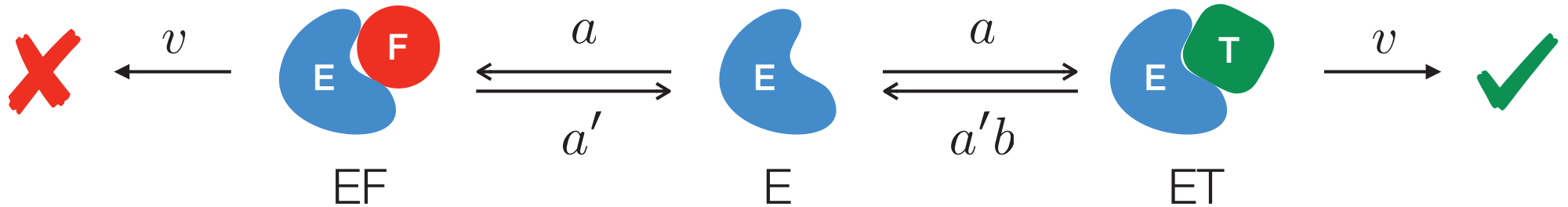


$$k = \omega \exp(-\Delta G^{\#} / RT)$$

$$k_+ = \omega \exp(-\Delta G^* / RT) = \omega'$$

$$k_- = \omega \exp(-\Delta G^* / RT) \exp(\Delta G^{\ominus} / RT) = \omega' \exp(\Delta G^{\ominus} / RT)$$

KINETIC PROOFREADING PROBLEM



assume

$$a \equiv k_+[F] = k_+[T]$$

discriminating factor

$$b = \exp\left(-(\Delta G_F^\ominus - \Delta G_T^\ominus)\right) \stackrel{!}{=} \exp\left(-\Delta G_{FT}^\ominus\right)$$

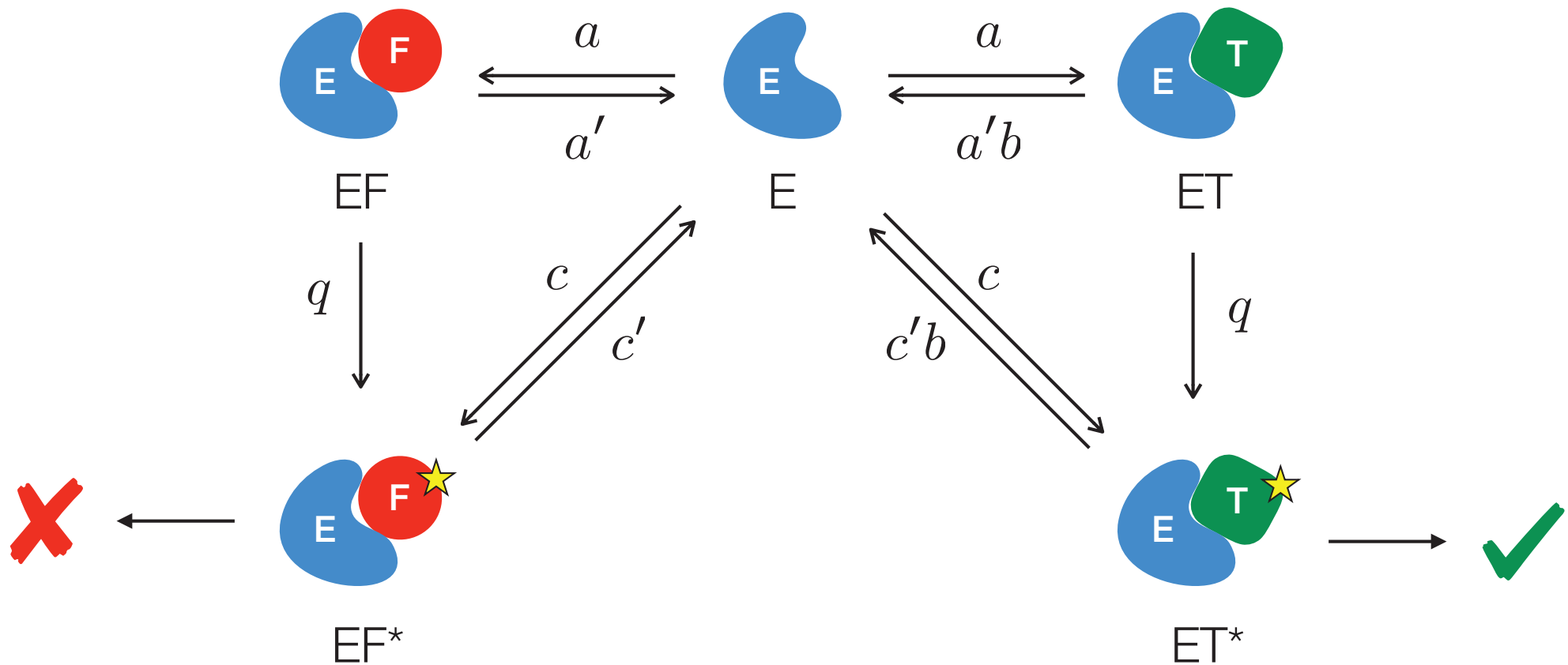
at steady-state

$$[ET] = \frac{a[E]}{a'b + v} \quad \text{and} \quad [EW] = \frac{a[E]}{a' + v}$$

error rate

$$\eta = \frac{v[EW]}{v[ET]} = \frac{[EW]}{[ET]} = \frac{a'b + v}{a' + v}$$

KINETIC PROOFREADING SCHEME



$$\eta = \frac{[EF^*]}{[ET^*]} = \frac{b(a'b + q)(a'c + (a + c)q)}{(a' + q)(a'bc + (a + c)q)}$$