## Space & Time Efficient Algorithms for Lipschitz Problems

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## Collection of Some Basic Polynomial Time Problems

 Longest Increasing Subsequence [Schensted, 1961]

tation

- String Edit Distance [Levenshtein, 19
- Context Free Gr Dynamic Programming parser, CYK, 1960-70]
- Language Edit Distance [Aho & Peterson, 1972]
- RNA Folding [Nussinov, Jacobson, 1980]

## 1. Longest Increasing Subsequence [Schensted, 1961]

 Given a sequence of integers s[1], s[2],..,s[n], find a subsequence 1≤ i<sub>1</sub>≤i<sub>2</sub>≤.... ≤ i<sub>k</sub>≤ n such that s[i<sub>1</sub>] < s[i<sub>2</sub>] < .....<s[i<sub>k</sub>] and k is maximized.

• Example

#### 12 3 8 1 9 5 11 10

• The longest increasing subsequence has length 4

#### **1. Longest Increasing Subsequence** [Schensted, 1961]

- Dynamic Programming
  - LIS[1]=1
  - $LIS[i] = max_{j < l:s[j] < s[i]} LIS[j] + 1$



#### **1. Longest Increasing Subsequence** [Schensted, 1961]

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 More sophisticated dynamic programming with time complexity O(n log n) and O(n) space exists.

#### 2. String Edit Distance [Levenshtein, 1965]

- Given two strings s and t what is the minimum number of edits (insertion, deletion, substitution) needed to transform s to t?
  - Example



Edit distance is 3

#### 2. String Edit Distance [Levenshtein, 1965]

- Dynamic Programming
  - Edit[0,i]=Edit[i,0]=i
  - Edit[i,j]=min[1+Edit(i-1,j), 1+Edit(i,j-1), cost(s[i],t[j])+Edit(i-1,j-1)]



Time Complexity=O(n<sup>2</sup>) Space Complexity=O(n<sup>2</sup>)

#### 2. String Edit Distance [Levenshtein, 1965]

- Dynamic Programming
  - Edit[0,i]=Edit[i,0]=i

G

3

3

2

2

1

2

2

Α

A

С

G

G

G

4

5

5

6

- Edit[i,j]=min[1+Edit(i-1,j), 1+Edit(i,j-1), cost(s[i],t[j])+Edit(i-1,j-1)]



- Assuming Strong Exponential Time Hypothesis no truly subquadratic algorithm exists for the exact computation [Backurs, Indyk, STOC'15]
- Even shaving arbitrary polylog factor is seemingly hard [Abboud, Dueholm, V Williams, Williams, STOC'16]

**3. Context Free Grammar Parsing** [Earley's parser, CYK 1968-70]

• Given a grammar G and a string s, can s be parsed according to rules of G?



3. Context Free Grammar Parsing [Earley's parser, CYK 1968-70]

 Given a grammar G and a string s, can s be parsed according to rules of G?



## **4. Language Edit Distance** [Aho & Peterson, 1972]

• Given a grammar G and a string s, find the minimum number of edits required in s to be able to parse the edited string according to the rules of G.



**5.** RNA Folding [Nussinov, Jacobson, 1980] Nucleotides in RNA form complementary base pairs to form the RNA secondary structure: *C* pairs with *G* and *A* pairs with *U*.





## 5. RNA Folding [Nussinov, Jackobson, 1980]

- Dynamic Programming
  - RNA[i,i]=0, RNA[i,j]=0 if j < i</p>
  - $RNA[i,j] = max( R[i,j], max_{i \le l \le j} RNA[i,l] + RNA[l+1,j] )$ 
    - R(i,j)=0 if s[i] does not pair with s[j]
    - R(i,j)=2+R(i+1,j-1) if s[i] pairs with s[j]



What is common among these Dynamic Programming Problems?

Longest Increasing Subsequence

#### **String Edit Distance**

Context Free Grammar Parsing Language Edit Distance

**RNA Folding** 

They all exhibit the property of bounded difference What is common among these Dynamic Programming Problems?



#### What is the main difference?

Looks at many subproblems at a time

Longest Increasing Subsequence

Context Free Grammar Parsing Language Edit Distance RNA Folding Looks at a constant number of subproblems at a time

#### **String Edit Distance**

## What is the main difference?

ake at a

Looks at many

#### Longest Increasing Subsequence

Context Free Grammar Parsing Language Edit Distance RNA Folding

can improve both space and time complexity using amnesic dynamic programming can improve space complexity using amnesic dynamic programming

#### **String Edit Distance**

onstant number problems a time

#### **Results: Language Edit Distance**

#### – Previously Known

- Conditional Lower Bound: No combinatorial subcubic algorithm exists even for any nontrivial multiplicative approximation. [Abboud, Backurs, V. Williams, FOCS'2015]
- Upper Bound:
  - Combinatorial: O(n<sup>3</sup>) time complexity, O(n<sup>2</sup>) space [Aho & Peterson, 1972, Myers, 1985,..]
  - Using Fast Matrix Multiplication: O(n<sup>2.8244</sup>) time complexity, O(n<sup>2</sup>) space [Bringmann, Grandoni, Saha, V. Williams, FOCS 2016]
  - Using Fast Matrix Multiplication:  $O(n^{\omega}/\epsilon^4)$  time complexity,  $O(n^2)$  space randomized algorithm for multiplicative (1+ $\epsilon$ )-approximation [Saha, FOCS 2015]

#### - What we show [Saha, FOCS'17]

- Combinatorial & Deterministic algorithm with time complexity  $O(n^2/\epsilon)$ , space  $O(n/\epsilon)$ ,  $\epsilon$ n-additive approximation
- Sublinear space:  $O(n^{2/3}/\epsilon^{4/3})$  space for  $\epsilon n$ -additive approximation
- Implies same bound for approximate membership checking for context free grammars

## **Results: RNA Folding**

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  - Using Fast Matrix Multiplication:  $O(n^{\omega}/\epsilon^4)$  time complexity,  $O(n^2)$  space randomized algorithm for  $\epsilon$ n-approximation [Saha, FOCS 2015]
- What we show [Saha, FOCS'17]
  - Combinatorial & Deterministic algorithm with time complexity  $O(n^2/\epsilon)$ , space  $O(n/\epsilon)$ ,  $\epsilon n$ -additive approximation
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## Further Results: String Edit Distance, Linear Grammar, Map Reduce & More

- New result
  - Linear grammar edit distance which generalizes string edit distance
    - Better space vs approximation trade offs: O(n<sup>2/3</sup>/  $\epsilon^{2/3}$ ) space for  $\epsilon n$  additive approximation
  - Map Reduce and multi-pass streaming algorithms for Language Edit Distance, RNA Folding, String Edit distance
  - Single pass streaming algorithm for string edit distance in asymmetric setting
    - Previously  $O(n^{1/2l}/\epsilon^{1/2})$  space [Saks and Seshadri, SODA'13]
    - This paper:  $O(n^{1/2}/\epsilon)$  space for  $\epsilon$ n-additive approximation



## Dynamic Programming Amnesic Dynamic Programming

- A technique to forget DP states systematically to allow for fast running time
  - (1) Sample only part of the DP table for computation
  - (2) For computing DP(i,j) consider fewer subproblems





- Dynamic Programming
  - LIS[1]=1
  - $LIS[i] = max_{j < l:s[j] < s[i]} LIS[j] + 1$



- Dynamic Programming
  - LIS[1]=1
  - -LIS[i]=max<sub>j<l:s[j]<s[i]</sub>LIS[j]+1

1

1

12 3 8 1 9 5 11 10

2

2

Create geometrically increasing subintervals starting from i and moving backward



- Dynamic Programming
  - LIS[1]=1
  - $LIS[i] = max_{j < l:s[j] < s[i]} LIS[j] + 1$

1

1

2

2



On a subinterval of length 2<sup>h</sup>k, select 1/2<sup>h</sup> break-points at equal distance



- Dynamic Programming
  - LIS[1]=1
  - -LIS[i]=max<sub>j<l:s[j]<s[i]</sub>LIS[j]+1

1

1

12 3 8 1 9 5 11 10

2

2

Perturb the boundaries slightly such that going from i to i+1 only subsampling is required.





- To show:  $LIS^{approx}[i] \ge LIS[i] \lfloor \frac{i}{k} \rfloor$ 
  - LIS[i]: Optimal LIS sequence for s[1,..i]
  - LIS<sup>approx</sup>[i]: Approximate LIS sequence for s[1,...,i]
  - Cost[i]=i-LIS[i], Cost<sup>approx</sup>[i]=i-LIS<sup>approx</sup>[i]



such that going from i to i+1 only subsampling is required.



# Amnesic DP for LIS $LIS^{approx}[i] \ge LIS[i] - \lfloor \frac{i}{k} \rfloor$

• Proof:

- $cost^{approx}[i] \le cost[i] + \lfloor \frac{i}{k} \rfloor$
- $-i \leq k: LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i]$
- Suppose true for  $i \leq kT$ 
  - 12 3 8 1 9 5 11 10

2

2

Perturb the boundaries slightly such that going from i to i+1 only subsampling is required.



$$\begin{array}{l} \textbf{Amnesic DP}_{LIS^{approx}[i] \geq LIS[i] - \lfloor \frac{i}{k} \rfloor} \quad \textbf{for LIS} \\ cost^{approx}[i] \leq cost[i] + \lfloor \frac{i}{k} \rfloor \\ cost^{approx}[i] \leq cost[i] + \lfloor \frac{i}{k} \rfloor \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = cost[i] \\ \textbf{i} \leq k : LIS^{approx}[i] = LIS[i], cost^{approx}[i] = LIS[i], cost^{a$$

Let l be the optimum break-point considered.



$$cost^{approx}[i] \leq cost[i] + \lfloor rac{i}{k} \rfloor$$

• Proof:

- Take  $i \in [kT + 1, k(T + 1)]$ If  $(i - l + 1) \le k$ :

Perturb the boundaries slightly such that going from i to i+1 only subsampling is required.

Move to LIS[l] and  $LIS^{approx}[l]$ 



$$cost^{approx}[i] \le cost[i] + \lfloor \frac{i}{k} \rfloor$$

• Proof:

Take  $i \in [kT+1, k(T+1)]$ 

#### Let l be the optimum break-point considered. f is the sampled break-point nearest to the left



$$cost^{approx}[i] \le cost[i] + \lfloor \frac{i}{k} \rfloor$$

• Proof: \_\_\_\_\_Take  $i \in [kT+1, k(T+1)]$ 



$$cost^{approx}[i] \le cost[i] + \lfloor \frac{i}{k} \rfloor$$

• Proof:  

$$Take \ i \in [kT + 1, k(T + 1)]$$

$$cost^{approx}[l] \le cost[l] + \lfloor \frac{l}{k} \rfloor$$
But would hold if we randomly sample the points with a rate higher by a log n factor.  

$$LIS^{approx}[l] \le LIS^{approx}[f] + (l - f)$$
From the Lipschitz Property\*
$$2^{a-1} [k2^{a-1}+1, k2^{a}]$$

$$k = 4k = 2k = k$$

$$cost^{approx}[i] \le cost[i] + \lfloor rac{i}{k} \rfloor$$















- Language Edit Distance
  - Amnesic DP: from O(n) subproblems to O(klog(n))

Exact Dynamic Programming

i

Amnesic Dynamic Programming



Sparsified in the middle

#### Long recursion



Cannot make mistake either in the short or in the long substrings

#### **Short Recursion**



Can make mistake on the long substrings but not on the short substrings—too many of them

Long recursion

**Short Recursion** 

Let P(i,j) denote the optimum recursion tree for s(i,i +1,...,j) and P<sup>approx</sup>(i,j) denote the approximate recursion tree computed by us.

Cost(P(i,j)): Total edit cost paid by P(i,j) Cost(P<sup>approx</sup>(i,j)): Total edit cost paid by P<sup>approx</sup>(i,j)

Cannot make mistake either in the short or in the long substrings

Long recursion

#### **Short Recursion**

$$cost(P^{approx}[i,j]) \leq cost(P[i,j]) + 4 \sum_{v \in \text{ internal nodes of } P(i,j)} \min\left(\lfloor\frac{w(v_L)}{k}\rfloor, \lfloor\frac{w(v_R)}{k}\rfloor\right)$$

$$\sum_{v \in \text{ internal nodes of } P(i,j)} \min\left(\lfloor\frac{w(v_L)}{k}\rfloor, \lfloor\frac{w(v_R)}{k}\rfloor\right) \leq \frac{(j-i+1)}{k} \log(j-i+1) \exp\left(\frac{w(v_L)}{k}\rfloor\right)$$

Cannot make mistake either in the short or in the long substrings

Long recursion

**Short Recursion** 

 $cost(P^{approx}[i,j]) \leq cost(P[i,j]) + 4 \sum \min\left(\lfloor \frac{w(v_L)}{k} \rfloor, \lfloor \frac{w(v_R)}{k} \rfloor\right)$ 

**Theorem 6.** Given a parameter  $k \ge 1$ , there exists an algorithm which for any grammar  $G = (\mathcal{N}, \Sigma, \mathcal{P}, S)$ , and  $\sigma \in \Sigma^*$  of  $|\sigma| = n$ , computes an  $O(\frac{n}{k} \log n)$ -additive approximation for LED in  $O(n^2k \log n)$  time and  $O(n^2)$  space.

$$\sum_{v \in \text{ internal nodes of } P(i,j)} \min \left( \lfloor \frac{w(v_L)}{k} \rfloor, \lfloor \frac{w(v_R)}{k} \rfloor \right) \leq \frac{(j-i+1)}{k} \log \left( j-i+1 \right) \text{ many } nodes \text{ for } p(i,j) \leq \frac{(j-i+1)}{k} \log \left( j-i+1 \right) \text{ for } p(i,j) \leq \frac{(j-i+1)}{k} \log \left( j-i+1 \right) \text{ for } p(i,j) \leq \frac{(j-i+1)}{k} \log \left( j-i+1 \right) \text{ for } p(i,j) \leq \frac{(j-i+1)}{k} \log \left( j-i+1 \right) \text{ for } p(i,j) \leq \frac{(j-i+1)}{k} \log \left( j-i+1 \right) \text{ for } p(i,j) \leq \frac{(j-i+1)}{k} \log \left( j-i+1 \right) \text{ for } p(i,j) \leq \frac{(j-i+1)}{k} \log \left( j-i+1 \right) \text{ for } p(i,j) \leq \frac{(j-i+1)}{k} \log \left( j-i+1 \right) \text{ for } p(i,j) \leq \frac{(j-i+1)}{k} \log \left( j-i+1 \right) \text{ for } p(i,j) \leq \frac{(j-i+1)}{k} \log \left( j-i+1 \right) \text{ for } p(i,j) \leq \frac{(j-i+1)}{k} \log \left( j-i+1 \right) \text{ for } p(i,j) \leq \frac{(j-i+1)}{k} \log \left( j-i+1 \right) \text{ for } p(i,j) \leq \frac{(j-i+1)}{k} \log \left( j-i+1 \right) \text{ for } p(i,j) \leq \frac{(j-i+1)}{k} \log \left( j-i+1 \right) \text{ for } p(i,j) \leq \frac{(j-i+1)}{k} \log \left( j-i+1 \right) \text{ for } p(i,j) \leq \frac{(j-i+1)}{k} \log \left( j-i+1 \right) \text{ for } p(i,j) \leq \frac{(j-i+1)}{k} \log \left( j-i+1 \right) \text{ for } p(i,j) \leq \frac{(j-i+1)}{k} \log \left( j-i+1 \right) \text{ for } p(i,j) \leq \frac{(j-i+1)}{k} \log \left( j-i+1 \right) \text{ for } p(i,j) \leq \frac{(j-i+1)}{k} \log \left( j-i+1 \right) \log \left$$

Cannot make mistake either in the short or in the long substrings

#### Amnesic DP: Improving Space Complexity

- Improved time complexity → Improved space complexity
- Few subproblems to look at implies less space complexity
- Locality among subproblems:
  - Store the solution for all subproblems (i,j) of length 2k
  - For (j-i+1)=r>2k: among the subproblems that are accessed to solve for (i,j), keep only those which will be required by (i,j+1) and (i-1,j). Also store all the solutions for length r substrings.
  - Space complexity: O(nk log n)

 Exact dynamic programming computes/stores solutions for every subproblem

Compute/Store solutions for only a subset of the entries

i Break points considered by time and space efficient DP

For small substrings: compute using auxiliary space with the time and space efficient DP

For long substrings: use the nearest DP value that is computed

- Exact dynamic programming computes/stores solutions for every subproblem
  - Compute/Store solutions for only a subset of the entries

Break points considered by time and space efficient DP

Considering break-point p, but solution for (i,p) not stored

Length of (i,p) and (j,p+1) are large: select the  $I_1$  nearest neighbor for which a solution has been computed and use that.

 Exact dynamic programming computes/stores solutions for every subproblem

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Compute/Store solutions for only a subset of the entries

i Break points considered by time and space efficient DP

Considering break-point p, but solution for (i,p) not stored

Length of (i,p) or (j,p+1) is small: Initialize the  $\Delta$  with the nearest computed solutions and then recompute....

- Exact dynamic programming computes/stores solutions for every subproblem
  - Compute/Store solutions for only a subset of the entries

**Theorem 2.** Given two parameters  $\gamma$  and q such that  $\gamma > \sqrt{q} \ge 1$ , there exist efficient algorithms for LED, RNA folding, and approximate CFG recognizer that use space  $O(\max(\frac{n^2}{q}, \frac{\gamma^2 \log n}{\sqrt{q}}))$  and achieve an additive approximation of  $O(\frac{n\sqrt{q}\log n}{\gamma})$ .

#### with the time and space emcient DP

Setting  $\gamma = \frac{\sqrt{q} \log n}{\epsilon}$  we get  $\epsilon n$ -additive approximation in  $\tilde{O}(\frac{n^{2/3}}{\epsilon^{4/3}})$  space

ace

Sublinear space algorithm even for additive approximation  $n^{3/4+\delta}, \delta > 0$ 

## From Sublinear Space to Parallel and Streaming Algorithms

- First Map-Reduce algorithm for Language Edit Distance and RNA Folding
  - Each machine stores only the computed entries of the dynamic programming table
  - Part of input
- Multi-pass streaming algorithm for Language Edit Distance and RNA Folding
- Better space vs approximation trade offs for linear grammar edit distance that generalizes string edit distance
   Single pass algorithm for edit distance in asymmetric setting

## What is the main difference?

ake at a

Looks at many

#### Longest Increasing Subsequence

Context Free Grammar Parsing Language Edit Distance RNA Folding

can improve both space and time complexity using amnesic dynamic programming can improve space complexity using amnesic dynamic programming

#### **String Edit Distance**

onstant number problems a time



## What is the main difference?

#### Looks at many subproblems at a time

can improve both space and time complexity using amnesic dynamic programming via additive approximation

#### Parsing

Language Edit DistanceRNA Folding

Using fast matrix multiplication can beat the dynamic programming

#### Looks at a constant number of subproblems

cannot improve time complexity using amnesic dynamic programming via additive approximation

#### **String Edit Distance**

Conditional hardness rules out better running time

#### From Dynamic Programming to Matrix s→Ac Multiplication j



Use production  $C \rightarrow AB$ 

#### **Compute Transitive Closure**

## To Matrix Multiplication [Saha, FOCS'15]

- Compute Transitive Closure Computation under a Special Matrix Product→(min,+)-product
- The product is nonassociative 
   *computing transitive closure is difficult keeping approximation error low is difficult*

From cubic to O(n<sup>2.327</sup>) time for (1+ε)-approximation LED, APSP, stochastic CFG parsing,...



#### Use production $C \rightarrow AB$

## Can we develop an exact fast algorithm for LED?

- Conditional Lower Bound: A subcubic exact algorithm for LED is weighted APSP hard if we allow only "insertion" as edit operation. [Saha FOCS'15]
- The lower bound breaks down when all three types of edits are allowed!!!

# Can we develop an exact fast algorithm for LED?

- When all three types of edits are allowed, the corresponding (min,+)-product matrices have bounded difference property
  - No of edits required for substring s(i,j) and s(i,j+1) can not differ much—similarly for s(i,j) and s(i+1,j)



# Can we develop an exact fast algorithm for LED?

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(min,+)-matrix product with bounded difference can be computed in truly subcubic time.

[Bringmann, Grandoni, Saha, V. Williams, FOCS'16]

## **Open Problems**

#### Improve the upper bounds

- Amnesic Dynamic Programming---Running time below
   O(n<sup>2</sup>) would give new approximation results even for string edit distance
- Improve the bound for Bounded-difference (min,+)product towards a truly subcubic algorithm for integer APSP
- Is Real APSP >> Integer APSP?
- Higher Dimensional Amnesic DP for Lipschitz problems
- Lower bound for space and time complexity trade-off
- Understand the true complexity of LED

## Towards an Exact fast algorithm for (min,+) product

- Will be a major breakthrough resulting in a huge number of graph and string problems to have faster running time.
- Technique for bounded difference matrices----matrices with integer entries in [1,n] ?

#### How close are we?

- As long as the absolute difference in any one dimension for any one matrix is at most  $n^{3-\omega-\epsilon}$
- To start with there are n<sup>3</sup> triplets (i,k,j) that can contribute to (min,+)-product computation.
- A triplet (i,k,j) is relevant if A(i,k)+B(k,j) ≈ C(i,j) [an approximate value of the (i,j)<sup>th</sup> entry of the product matrix C]
- Even for two arbitrary matrices after subcubic amount of processing, we are only left with subcubic number of relevant triplets which we have not looked at.
- How do we find these few relevant triplets which are yet to be considered?