Probing Fundamental Bounds in Hydrodynamics Using Variational Optimization Methods

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- Charles Doering (University of Michigan)

Agenda

Background: Known Estimates

Regularity Problem for Navier–Stokes Equation Bounds on Rate of Growth of Enstrophy Saturation of Estimates as Optimization Problem

Saturation of Estimates

Instantaneous Bounds for 1D Burgers Problem Finite–Time Bounds for 1D Burgers Problem Instantaneous Bounds for 2D Navier–Stokes Problem

Sharpening KLB Theory of 2D Turbulence

Introduction: Universality in Turbulence Validating KLB via Optimization Results: Full-band Forcing Forcing Consistent with KLB

• Navier–Stokes equation $(\Omega = [0, L]^d, d = 2, 3)$

$$\begin{cases} \frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} + \nabla p - \nu \Delta \mathbf{v} = \mathbf{0}, & \text{in } \Omega \times (0, T] \\ \nabla \cdot \mathbf{v} = 0, & \text{in } \Omega \times (0, T] \\ \mathbf{v} = \mathbf{v}_0 & \text{in } \Omega \text{ at } t = 0 \\ \text{Boundary Condition} & \text{on } \Gamma \times (0, T] \end{cases}$$

2D Case

 Existence Theory Complete — smooth and unique solutions exist for arbitrary times and arbitrarily large data

3D Case

- Weak solutions (possibly nonsmooth) exist for arbitrary times
- Classical (smooth) solutions (possibly nonsmooth) exist for finite times only
- Possibility of "blow-up" (finite-time singularity formation)
- One of the Clay Institute "Millennium Problems" (\$ 1M!) http://www.claymath.org/millennium/Navier-Stokes_Equations

Regularity Problem for Navier–Stokes Equation Bounds on Rate of Growth of Enstrophy Saturation of Estimates as Optimization Problem

What is known? — Available Estimates

$$\mathcal{E}(t) riangleq \int_{\Omega} |oldsymbol{
abla} imes oldsymbol{v}|^2 \, d\Omega \qquad (= \|oldsymbol{
abla} oldsymbol{v}\|_2^2)$$







Can estimate dE(t)/dt using the momentum equation, Sobolev's embeddings, Young and Cauchy–Schwartz inequalities, ...

REMARK: incompressibility not used in these estimates

Regularity Problem for Navier–Stokes Equation Bounds on Rate of Growth of Enstrophy Saturation of Estimates as Optimization Problem

$$rac{d\mathcal{E}(t)}{dt} \leq rac{C^2}{
u}\mathcal{E}(t)^2$$

- Gronwall's lemma and energy equation yield $\forall_t \ \mathcal{E}(t) < \infty$
- smooth solutions exist for all times

3D Case:

$$\frac{d\mathcal{E}(t)}{dt} \leq \frac{27C^2}{128\nu^3}\mathcal{E}(t)^3$$

- corresponding estimate not available
- upper bound on $\mathcal{E}(t)$ blows up in finite time

$$\mathcal{E}(t) \leq rac{\mathcal{E}(0)}{\sqrt{1-4rac{\mathcal{C}\mathcal{E}(0)^2}{
u^3}t}}$$

singularity in finite time cannot be ruled out!

Regularity Problem for Navier–Stokes Equation Bounds on Rate of Growth of Enstrophy Saturation of Estimates as Optimization Problem

Problem of Lu & Doering (2008), I

- Can we actually find solutions which "saturate" a given estimate?
- Estimate $\frac{d\mathcal{E}(t)}{dt} \leq c\mathcal{E}(t)^3$ at a *fixed* instant of time t

$$\max_{\mathbf{v}\in H^{1}(\Omega), \, \nabla \cdot \mathbf{v}=0} \frac{d\mathcal{E}(t)}{dt}$$

subject to $\mathcal{E}(t) = \mathcal{E}_{0}$

where

$$rac{d\mathcal{E}(t)}{dt} = -
u \|\mathbf{\Delta}\mathbf{v}\|_2^2 + \int_\Omega \mathbf{v}\cdot \mathbf{\nabla}\mathbf{v}\cdot \mathbf{\Delta}\mathbf{v}\,d\Omega$$

- \mathcal{E}_0 is a parameter
- Solution using a gradient-based descent method

Regularity Problem for Navier–Stokes Equation Bounds on Rate of Growth of Enstrophy Saturation of Estimates as Optimization Problem

Problem of Lu & Doering (2008), II

Enstrophy Growth Rate vs Enstrophy - Lower Branch Upper Branch 10³ Enstrophy Growth Rate 10² 10¹ 10⁰ 10^{2} 10 Enstrophy $\left[\frac{d\mathcal{E}(t)}{dt}\right]_{max} = 8.97 \times 10^{-4} \ \mathcal{E}_0^{2.997}$



vorticity field (top branch)

Regularity Problem for Navier–Stokes Equation Bounds on Rate of Growth of Enstrophy Saturation of Estimates as Optimization Problem

► How about solutions which saturate <u>dt</u> ≤ cE(t)³ over a <u>finite</u> time window [0, T]?

$$\max_{\mathbf{v}_0 \in H^1(\Omega), \, \nabla \cdot \mathbf{v} = 0} \begin{bmatrix} \max_{t \in [0, T]} \mathcal{E}(t) \\ \text{subject to } \mathcal{E}(t) = \mathcal{E}_0 \end{bmatrix}$$

where

$$\mathcal{E}(t) = \int_0^t rac{d\mathcal{E}(au)}{d au} \, d au + \mathcal{E}_0$$

• \mathcal{E}_0 is a parameter

- ► $\max_{t \in [0,T]} \mathcal{E}(t)$ nondifferentiable w.r.t initial condition \implies non-smooth optimization problem
- ▶ In principle doable, but will try something simpler first ...

Instantaneous Bounds for 1D Burgers Problem Finite–Time Bounds for 1D Burgers Problem Instantaneous Bounds for 2D Navier–Stokes Problem

PROBLEM I

INSTANTANEOUS AND FINITE-TIME BOUNDS FOR GROWTH OF ENSTROPHY IN 1D BURGERS PROBLEM

joint work with Diego Ayala (McMaster)

Instantaneous Bounds for 1D Burgers Problem Finite–Time Bounds for 1D Burgers Problem Instantaneous Bounds for 2D Navier–Stokes Problem

• Burgers equation $(\Omega = [0, 1], u : \mathbb{R}^+ \times \Omega \to \mathbb{R})$

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} - \nu \frac{\partial^2 u}{\partial x^2} = 0 \qquad \text{in } \Omega$$
$$u(x) = \phi(x) \qquad \text{at } t = 0$$

Periodic B.C.

Enstrophy : $\mathcal{E}(t) = \frac{1}{2} \int_0^1 |u_x(x, t)|^2 dx$

Solutions smooth for all times

Questions of sharpness of enstrophy estimates still relevant

$$\frac{d\mathcal{E}(t)}{dt} \leq \frac{3}{2} \left(\frac{1}{\pi^2 \nu}\right)^{1/3} \mathcal{E}(t)^{5/3}$$

Best available finite-time estimate

$$\max_{t \in [0,T]} \mathcal{E}(t) \leq \left[\mathcal{E}_0^{1/3} + \left(\frac{L}{4}\right)^2 \left(\frac{1}{\pi^2 \nu}\right)^{4/3} \mathcal{E}_0 \right]^3 \underset{\mathcal{E}_0 \to \infty}{\longrightarrow} C_2 \mathcal{E}_0^3$$

Instantaneous Bounds for 1D Burgers Problem Finite–Time Bounds for 1D Burgers Problem Instantaneous Bounds for 2D Navier–Stokes Problem

"Small" Problem of Lu & Doering (2008), I

• Estimate $\frac{d\mathcal{E}(t)}{dt} \leq c\mathcal{E}(t)^{5/3}$ at a *fixed* instant of time t

$$\max_{u \in H^{1}(\Omega)} \frac{d\mathcal{E}(t)}{dt}$$

subject to $\mathcal{E}(t) = \mathcal{E}_{0}$

where

$$\frac{d\mathcal{E}(t)}{dt} = -\nu \left\| \frac{\partial^2 u}{\partial x^2} \right\|_2^2 + \frac{1}{2} \int_0^1 \left(\frac{\partial u}{\partial x} \right)^3 \, d\Omega$$

• \mathcal{E}_0 is a parameter

 Solution (maximizing field) found analytically! (in terms of elliptic integrals and Jacobi elliptic functions)

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"Small" Problem of Lu & Doering (2008), II



instantaneous estimate is sharp



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Finite–Time Optimization Problem (I)

Statement

 $\max_{\phi\in H^1(\Omega)}\mathcal{E}(\mathcal{T}) \ ext{subject to } \mathcal{E}(t)=\mathcal{E}_0$

T, \mathcal{E}_0 — parameters

Optimality Condition

$$\forall_{\phi'\in H^1} \qquad \mathcal{J}'_{\lambda}(\phi;\phi') = -\int_0^1 \frac{\partial^2 u}{\partial x^2}\Big|_{t=T} u'\Big|_{t=T} dx - \lambda \int_0^1 \frac{\partial^2 \phi}{\partial x^2}\Big|_{t=0} u'\Big|_{t=0} dx$$

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Finite–Time Optimization Problem (II)

Gradient Descent

$$\phi^{(n+1)} = \phi^{(n)} - \tau^{(n)} \nabla \mathcal{J}(\phi^{(n)}), \qquad n = 1, \dots,$$

$$\phi^{(0)} = \phi_0,$$

where $\nabla \mathcal{J}$ determined from *adjoint system* via H^1 Sobolev preconditioning

$$-\frac{\partial u^*}{\partial t} - u\frac{\partial u^*}{\partial x} - \nu\frac{\partial^2 u^*}{\partial x^2} = 0 \quad \text{in } \Omega$$
$$u^*(x) = -\frac{\partial^2 u}{\partial x^2}(x) \text{ at } t = 7$$

Periodic B.C.





• Two parameters:
$$T$$
, \mathcal{E}_0 $(
u = 10^{-3})$

 Optimal initial conditions corresponding to initial guess with wavenumber m = 1 (local maximizers)



10 10⁴ 10 E^{ree} 10 10 10 $\max_{t \in [0, T]} \mathcal{E}(t) \text{ versus } T$ 10⁰ '⊢ 10 $\underset{t \in [0, T]}{\overset{_{10}^{-1}}{\text{argmax}}} \overset{_{10}^{-1}}{\mathcal{E}}(t)^{\overset{_{10}^{-1}}{\text{versus}}} \overset{_{10}^{-1}}{\mathcal{E}}_{0}^{^{10}}$ $\operatorname{argmax}_{t\in[0,T]}\mathcal{E}(t)\sim \mathcal{CE}_0^{-0.5}$ Instantaneous Bounds for 1D Burgers Problem Finite-Time Bounds for 1D Burgers Problem Instantaneous Bounds for 2D Navier-Stokes Problem



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Probing Fundamental Bounds in Hydrodynamics

Background: Known Estimates Saturation of Estimates Sharpening KLB Theory of 2D Turbulence Sharpening KLB Theory of 2D Turbulence

► Sol'ns found with initial guesses $\phi^{(m)}(x) = \sin(2\pi m x), m = 1, 2, ...$



► Change of variables leaving Burgers equation invariant (L ∈ Z⁺):

$$\begin{aligned} x &= L\xi, \ (x \in [0,1], \ \xi \in [0,1/L]), \qquad \tau = t/L^2 \\ v(\tau,\xi) &= Lu(x(\xi),t(\tau)), \qquad \qquad \mathcal{E}_v(\tau) = L^4 \mathcal{E}_u\left(\frac{t}{L^2}\right) \end{aligned}$$

 Background: Known Estimates
 Instantaneous Bounds for 1D Burgers Problem

 Saturation of Estimates
 Finite-Time Bounds for 1D Burgers Problem

 Sharpening KLB Theory of 2D Turbulence
 Instantaneous Bounds for 2D Navier-Stokes Problem

Solutions for m = 1 and m = 2, after rescaling



▶ Using initial guess: $\phi^{(0)}(x) = \sin(2\pi mx)$, m = 1, or m = 2 $\phi^{(0)}(x) = \epsilon \sin(2\pi mx) + (1 - \epsilon) \sin(2\pi nx)$, $m \neq n$, $\epsilon > 0$



Background: Known Estimates Saturation of Estimates Sharpening KLB Theory of 2D Turbulence Sharpening KLB Theory of 2D Turbulence

Location of Singularities in $\mathbb C$ from the Fourier spectrum



Instantaneous Bounds for 1D Burgers Problem Finite-Time Bounds for 1D Burgers Problem Instantaneous Bounds for 2D Navier-Stokes Problem



- RED instantaneously optimal (Lu & Doering, 2008)
- BOLD BLUE finite-time optimal (T = 0.1)
- DASHED BLUE finite-time optimal (T = 1)

Instantaneous Bounds for 1D Burgers Problem Finite-Time Bounds for 1D Burgers Problem Instantaneous Bounds for 2D Navier-Stokes Problem

Summary & Conclusions (I)

- Some evidence that optimizers found are in fact *global*
- ▶ Exponents in $\max_{t \in [0,T]} \mathcal{E}(t) = C \mathcal{E}_0^{\alpha}$ as $\mathcal{E}_0 \to \infty$

	theoretical estimate	optimal (instantaneous) [Lu & Doering, 2008]	optimal (finite–time) [present study]
α	3	1	3/2

- more rapid enstrophy build-up in finite-time optimizers than in instantaneous optimizers
- ► theoretical estimate not sharp ⇒ finite-time optimizers offer insights re: refinements required (work in progress)
- Finite-time maximizers (almost) saturate Poincaré's inequality (largest kinetic energy for a given enstrophy)

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PROBLEM II

Instantaneous Bounds for Growth of Palinstrophy in 2D Navier–Stokes Problem

joint work with Diego Ayala (McMaster)

Instantaneous Bounds for 1D Burgers Problem Finite-Time Bounds for 1D Burgers Problem Instantaneous Bounds for 2D Navier-Stokes Problem

▶ 2D vorticity equation in a periodic box $(\omega = \mathbf{e}_z \cdot \boldsymbol{\omega})$

$$\begin{aligned} \frac{\partial \omega}{\partial t} + J(\omega, \psi) &= \nu \Delta \omega \quad \text{where } J(f, g) = f_x g_y - f_y g_x \\ - \Delta \psi &= \omega \end{aligned}$$

Enstrophy uninteresting in 2D flows (w/o boundaries)

$$\frac{1}{2}\frac{d}{dt}\int_{\Omega}\omega^{2}\,d\Omega=-\nu\,\int_{\Omega}(\boldsymbol{\nabla}\omega)^{2}\,d\Omega<0$$

• Evolution equation for the vorticity gradient $abla \omega$

$$\frac{\partial \boldsymbol{\nabla} \boldsymbol{\omega}}{\partial t} + (\mathbf{u} \cdot \boldsymbol{\nabla}) \boldsymbol{\nabla} \boldsymbol{\omega} = \nu \Delta \boldsymbol{\nabla} \boldsymbol{\omega} + \underbrace{\boldsymbol{\nabla} \boldsymbol{\omega} \cdot \boldsymbol{\nabla} \mathbf{u}}_{\text{"STRETCHING" TERM}}$$

Palinstrophy

$$\mathcal{P}(t) riangleq \int_{\Omega} (oldsymbol{
abla} \omega(t, \mathbf{x}))^2 \, d\Omega = \int_{\Omega} (oldsymbol{
abla} \Delta \psi(t, \mathbf{x}))^2 \, d\Omega$$

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Estimates for the Rate of Growth of Palinstrophy

$$\frac{d\mathcal{P}(t)}{dt} = \int_{\Omega} J(\Delta\psi,\psi) \Delta^2\psi \, d\Omega - \nu \, \int_{\Omega} (\Delta^2\psi)^2 \, d\Omega \quad \triangleq \mathcal{R}_{\nu}(\psi)$$

$$\begin{aligned} \frac{d\mathcal{P}(t)}{dt} &\leq \frac{C_1}{\nu} \mathcal{E} \,\mathcal{P} \qquad \text{(Doering \& Lunasin, 2011)} \\ \frac{d\mathcal{P}(t)}{dt} &\leq \frac{C_2}{\nu} \mathcal{K}^{1/2} \,\mathcal{P}^{3/2} \quad \text{(Ayala, 2012)} \end{aligned}$$

Using Poincaré's inequality (may not be sharp)

$$\frac{d\mathcal{P}(t)}{dt} \leq \frac{C}{\nu}\mathcal{P}^2,$$

Bound on growth in finite time

$$\max_{t>0} \mathcal{P}(t) \le \mathcal{P}(0) + \frac{C_1}{2\nu^2} \frac{L^4}{16\pi^4} \mathcal{P}(0)^2 \qquad \text{(Doering \& Lunasin, 2011)}$$

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Are the Instantaneous Estimates for $\frac{d\mathcal{P}(t)}{dt}$ Sharp?

Solve the following problem: for ν , \mathcal{E}_0 , $\mathcal{P}_0 > 0$

$$egin{aligned} &\max_{\psi\in H^4(\Omega)}\mathcal{R}_
u(\psi) \ & ext{subject to:} & \int_\Omega (\Delta\psi)^2\,d\Omega = \mathcal{E}_0 \ & \int_\Omega (oldsymbol{
aligned} \Delta\psi)^2\,d\Omega = \mathcal{P}_0 \end{aligned}$$

Instantaneous Bounds for 1D Burgers Problem Finite-Time Bounds for 1D Burgers Problem Instantaneous Bounds for 2D Navier-Stokes Problem

Some Remarks

in 2D flows nonlinearities identically vanish for

 $\psi_0 \triangleq \{ \text{eigenfunction of } \Delta \} \implies J(\Delta \phi_0, \psi_0) = 0, \ \mathcal{R}_{\nu}(\psi_0) < 0$

▶ In the limit $\mathcal{P}_0 = \mathcal{P}(0) \rightarrow 0$ (equivalently, $u \rightarrow \infty$)

$$\max_{\psi \in H^4(\Omega)} \left[-\int_{\Omega} (\Delta^2 \psi)^2 \, d\Omega \right]$$

subject to:
$$\int_{\Omega} (\Delta \psi)^2 \, d\Omega = \mathcal{E}_0$$
$$\int_{\Omega} (\nabla \Delta \psi)^2 \, d\Omega = \mathcal{P}_0$$

Instantaneous Bounds for 1D Burgers Problem Finite-Time Bounds for 1D Burgers Problem Instantaneous Bounds for 2D Navier-Stokes Problem

Simplified Formulation

- Palinstrophy and Enstrophy constraints hard to satisfy exactly require projection on intersection of two manifolds in H⁴(Ω)
- \mathcal{P}_0 constraint + Poincaré's inequality = Upper bound on \mathcal{E}_0

$$\begin{cases} \int_{\Omega} (\boldsymbol{\nabla} \Delta \psi)^2 \, d\Omega = \mathcal{P}_0 \\ \int_{\Omega} \phi^2 \, d\Omega \leq C \, \int_{\Omega} (\boldsymbol{\nabla} \phi)^2 \, d\Omega \end{cases} \implies \int_{\Omega} (\Delta \psi)^2 \, d\Omega \leq C \, \mathcal{P}_0$$

Simpler maximization problem (one constraint)

$$\max_{\psi \in H^4(\Omega)} \mathcal{R}_{
u}(\psi)$$

subject to: $\int_{\Omega} (\boldsymbol{\nabla} \Delta \psi)^2 \, d\Omega = \mathcal{P}_0$

Numerical Solution of Maximization Problem

Discretization of Gradient Flow

$$\begin{aligned} \frac{d\psi}{d\tau} &= -\nabla^{H^4} \mathcal{R}_{\nu}(\psi), \qquad \qquad \psi(0) = \psi_0 \\ \psi^{(n+1)} &= \psi^{(n)} - \Delta \tau^{(n)} \nabla^{H^4} \mathcal{R}_{\nu}(\psi^{(n)}), \qquad \psi^{(0)} = \psi_0 \end{aligned}$$

• Gradient in $H^4(\Omega)$ (via variational techniques)

$$\begin{bmatrix} \mathsf{Id} - L^8 \Delta^4 \end{bmatrix} \nabla^{H^4} \mathcal{R}_{\nu} = \nabla^{L_2} \mathcal{R}_{\nu} \qquad \text{(Periodic BCs)}$$
$$\nabla^{L_2} \mathcal{R}_{\nu}(\psi) = \Delta^2 J(\Delta \psi, \psi) + \Delta J(\psi, \Delta^2 \psi) + J(\Delta^2 \psi, \Delta \psi) - 2\nu \Delta^4 \psi$$

Constraint satisfaction via arc minimization

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Results: small \mathcal{P}_0



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Results: large \mathcal{P}_0



Probing Fundamental Bounds in Hydrodynamics

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Results: Vortex Structure ($\mathcal{P}_0 = 4.6 \cdot 10^5$)



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Open Questions

- The role of the second (enstrophy) constraint
- Presence of other nontrivial branches (found in 3D, but not in 1D case)
- Analytic characterization of the maximizers in the limit $\mathcal{P}_0 \rightarrow \infty$ (via asymptotic analysis)

$$\Delta^3 \left[\Delta^2 J(\Delta \psi, \psi) + \Delta J(\psi, \Delta^2 \psi) + J(\Delta^2 \psi, \Delta \psi) \right] = 0 \quad \text{in } \Omega$$

where $J(f,g) = f_x g_y - f_y g_x$

▶ Next: saturation of finite-time estimates for $\max_{t\geq 0} \mathcal{P}(t)$

Instantaneous Bounds for 1D Burgers Problem Finite-Time Bounds for 1D Burgers Problem Instantaneous Bounds for 2D Navier-Stokes Problem

Summary & Conclusions (II)

Exponents: Analysis vs. Variational Optimization

	Analysis	Optimization
1D Burgers instantaneous [Lu & Doering, 2008]	5/3	5/3
1D Burgers finite–time [Ayala & Protas, 2011]	3	3/2
2D Navier–Stokes instantaneous [Doering & Lunasin, 2011; present study]	2†	5/3
2D Navier–Stokes finite–time [Doering & Lunasin, 2011; present study]	2	?
3D Navier–Stokes instantaneous [Lu & Doering, 2008]	3	3
3D Navier–Stokes finite–time	N/A	???

[†]May not be sharp due to Poincaré's inequality

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PROBLEM III

Sharpening Kraichnan–Leith–Batchelor (KLB) Theory of 2D Turbulence

Joint Work with:

Mohammad Farazmand and Nicholas Kevlahan (McMaster)

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KLB — A Classical Theory for 2D Turbulence

Kraichnan(1967), Leith(1968) and Batchelor(1969)

Forced Navier–Stokes equation

$$\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} = -\nabla p + \nu \Delta \mathbf{u} + \mathbf{f}$$
$$\nabla \cdot \mathbf{u} = 0$$

 Homogeneous, Isotropic, Statistically Stationary Flow

 Existence of two inertial ranges, energy and enstrophy inertial ranges

 ϵ = energy dissipation rate
 η = enstrophy dissipation rate

$$E(k) \propto \begin{cases} \epsilon^{2/3} k^{-5/3} & k_1^e < k < k_2^e \\ \eta^{2/3} k^{-3} & k_1^z < k < k_2^z \end{cases}$$



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Bounds on the Cascade Slopes

P. Constantin, C. Foias & O. Manley, Phys. Fluids 6, 427–429, (1994) C. V. Tran & T. G. Shepherd, Physica D 165, 199-212, (2002)



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Has this theory been confirmed by experimental data?



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An Optimization Approach

- Does forcing consistent with the KLB theory exist?
- Find it with a Variational Optimization Approach

$$\min_{\mathbf{f}\in L_2(0,\mathcal{T};L_2(\Omega))} \mathcal{J}(\mathbf{f})$$

where

$$\begin{aligned} \mathcal{J}(\mathbf{f}) &\triangleq \frac{1}{2} \int_0^T \int_{\mathcal{I}} |E(t,k;\mathbf{f}) - E_0(k)|^2 \, \mathrm{d}k \, \, \mathrm{d}t + \beta^2 \|\mathbf{f}\|_{L_2(0,T;L_2(\Omega))} \\ & E_0(k) \propto \begin{cases} k^{-5/3} & k_1^e < k < k_2^e \\ k^{-3} & k_1^z < k < k_2^z \end{cases} \end{aligned}$$

Solution using adjoint-based methods of PDE-constrained optimization

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Optimal Forcing



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Energy Spectra



Vorticity Fields

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Conventional Forcing

Optimal Forcing

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Energy and Enstrophy "Injection"



Energy/Enstrophy "injection"

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Summary & Conclusions (III)

- KLB scaling is feasible with "appropriate" forcing
- Large-scale energy dissipation (inherent in phenomenological theories) is a part of reconstructed forcing
- The optimal forcing is not robust (Navier–Stokes lacks smooth dependence on the data — inverse problem is ill–posed)



References

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