# EFFECT HANDLERS &

## **MATHEMATICALLY** INSPIRED LANGUAGE **CONSTRUCTS**

Matija Pretnar



#### This seminar series has covered the past 75 years of control structures

 $\begin{array}{c} 08 \\ FÉV \rightarrow MAR \\ 2024 \end{array} \xrightarrow{} 2024 \end{array}$ 

Q

#### COLLÈGE DE FRANCE ------ 1530 ------

#### SÉMINAIRE

Structures de contrôle : de « *goto* » aux effets algébriques

< Partager 🗸

Du jeudi 8 février au jeudi 14 mars 2024

#### Voir aussi :

- Cours associé
- Xavier Leroy



#### How will the **next seminar series** in 75 years be titled?

 $\begin{array}{c} 05 \\ FÉV \rightarrow MAR \\ _{2099} \end{array} \xrightarrow[2099]{} 12 \\ MAR \\ _{2099} \end{array}$ 

Q

#### SÉMINAIRE

Structures de contrôle : des effets algébriques au « ??? »

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- Xavier Leroy



HANDLERS

HANDLERS









#### Moggi recognised **monads** in the **semantics** of effectful computations

Computational lambda-calculus and monads

Eugenio Moggi<sup>\*</sup> Lab. for Found. of Comp. Sci. University of Edinburgh EH9 3JZ Edinburgh, UK On leave from Univ. di Pisa

#### Abstract

The  $\lambda$ -calculus is considered an useful mathematical tool in the study of programming languages. However, if one uses  $\beta\eta$ -conversion to prove equivalence of programs, then a gross simplification<sup>1</sup> is introduced. We give a calculus based on a categorical semantics for computations, which provides a correct basis for proving equivalence of programs, independent from any

#### Introduction

This paper is about logics for reasoning about programs, in particular for proving equivalence of programs. Following a consolidated tradition in theoretical computer science we identify programs with the closed  $\lambda$ -terms, possibly containing extra constants, corresponding to some features of the programming language under consideration. There are three approaches to proving equivalence of programs:

• The operational approach starts from an operational semantics, e.g. a partial function mapping every program (i.e. closed term) to its resulting value (if any), which induces a congruence relation on open terms called operational equivalence (see e.g. [10]). Then the problem is to prove that two terms are operationally equivalent.

• The **denotational** approach gives an interpretation of the (programming) language in a mathematical structure, the **intended model**. Then the problem is to prove that two terms denote the same object in the intended model.

\*Research partially supported by EEC Joint Collaboration Contract # ST2J-0374-C(EDB).

 $^{1}\mathrm{Programs}$  are identified with total functions from values to .

• The logical approach gives a class of possible models for the language. Then the problem is to prove that two terms denotes the same object in

The operational and denotational approaches give only a theory (the operational equivalence  $\approx$  and the set Thof formulas valid in the intended model respectively), and they (especially the operational approach) deal with programming languages on a rather case-by-case basis. On the other hand, the logical approach gives a consequence relation  $\vdash (Ax \vdash A \text{ iff the formula } A \text{ is})$ true in all models of the set of formulas Ax), which can deal with different programming languages (e.g. functional, imperative, non-deterministic) in a rather uniform way, by simply changing the set of axioms Ax, and possibly extending the language with new constants. Moreover, the relation  $\vdash$  is often semidecidable, so it is possible to give a sound and complete formal system for it, while Th and  $\approx$  are semidecidable

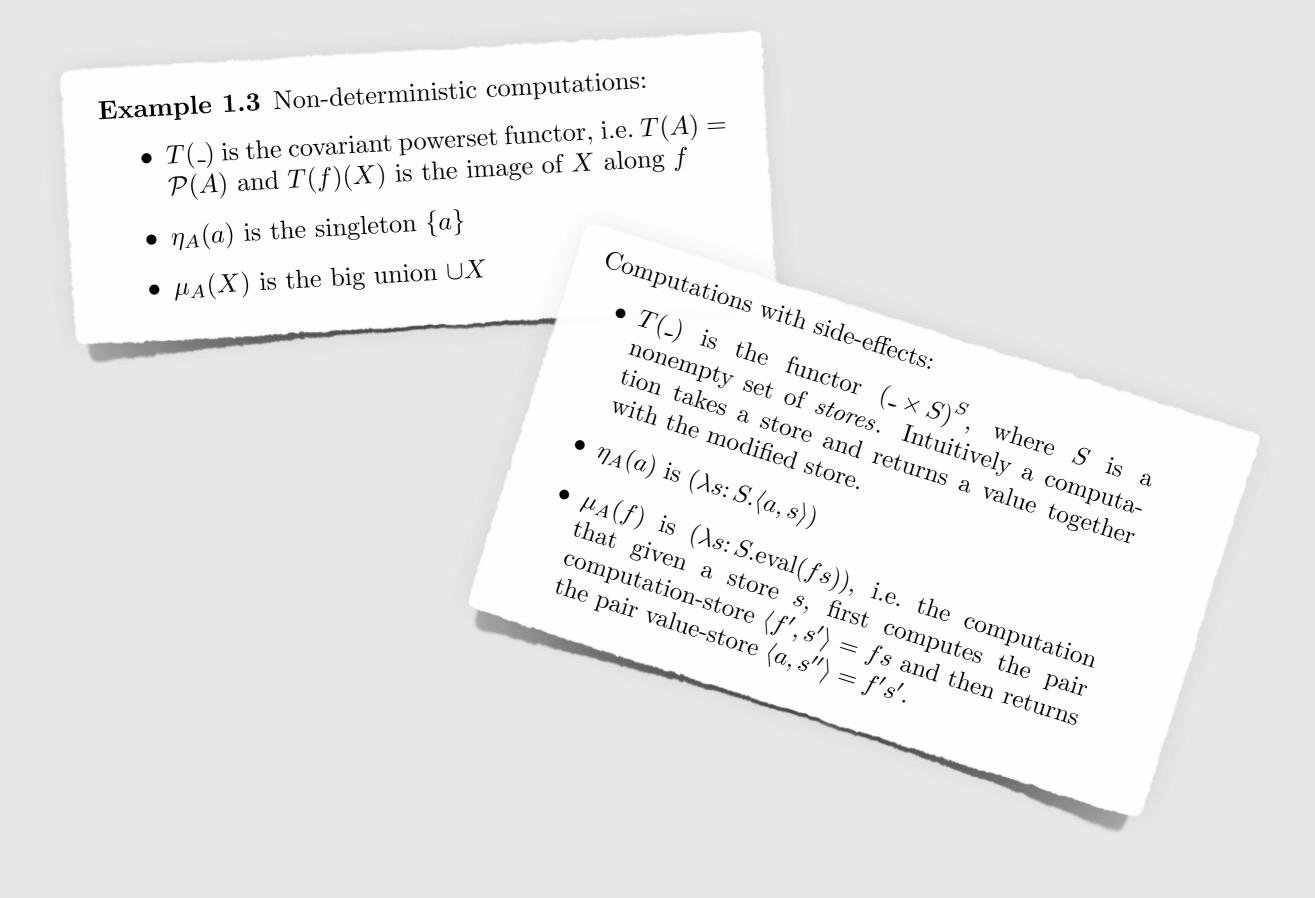
We do not take as a starting point for proving equivalence of programs the theory of  $\beta\eta$ -conversion, which identifies the denotation of a program (procedure) of type  $A \to B$  with a total function from A to B, since this identification wipes out completely behaviours like non-termination, non-determinism or side-effects, that can be exhibited by real programs. Instead, we pro-

1. We take category theory as a general theory of functions and develop on top a categorical semantics of computations based on monads.

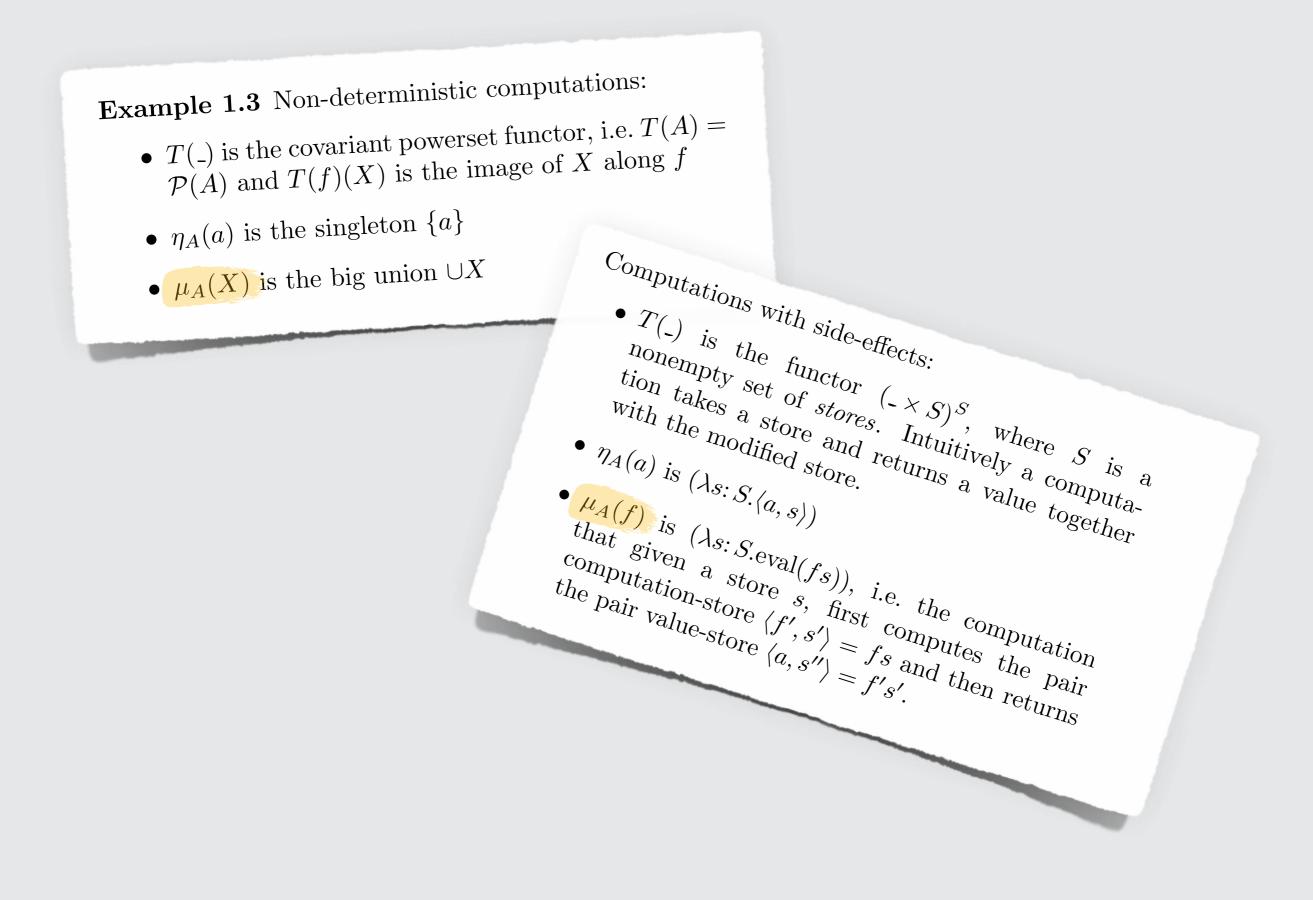
2. We consider how the categorical semantics should be extended to interpret  $\lambda$ -calculus.

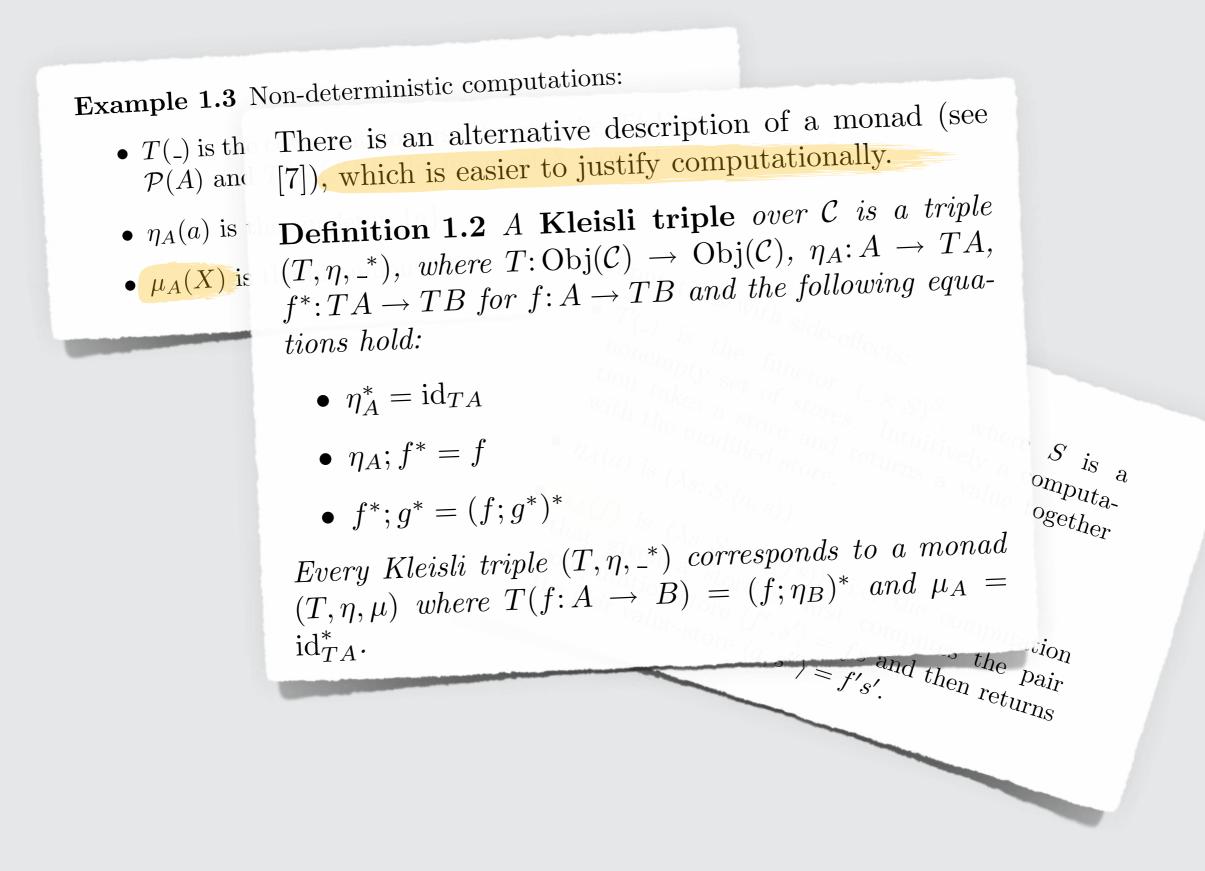
At the end we get a formal system, the computational lambda-calculus ( $\lambda_c$ -calculus for short), for proving equivalence of programs, which is sound and complete w.r.t. the categorical semantics of computations.

#### The initial specification was taken to be **mathematically** more natural



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#### In his subsequent work, a **computationally natural** approach was taken

INFORMATION AND COMPUTATION 93, 55–92 (1991)

#### Notions of Computation and Monads

#### Eugenio Moggi\*

Department of Computer Science, University of Edinburgh, Edinburgh EH9 3JZ, UK

The z-calculus is considered a useful mathematical tool in the study of programming languages, since programs can be *identified* with  $\lambda$ -terms. However, if one goes further and uses  $\beta\eta$ -conversion to prove equivalence of programs, then a gross simplification is introduced (programs are identified with total functions from values to values) that may jeopardise the applicability of theoretical results. In this paper we introduce calculi, based on a categorical semantics for computations, that provide a correct basis for proving equivalence of programs for a wide range of

#### INTRODUCTION

This paper is about logics for reasoning about programs, in particular for proving equivalence of programs. Following a consolidated tradition in theoretical computer science we identify programs with the closed  $\lambda$ -terms, possibly containing extra constants, corresponding to some features of the programming language under consideration. There are three semanticsbased approaches to proving equivalence of programs:

• The operational approach starts from an operational semantics,

e.g., a partial function mapping every program (i.e., closed term) to its resulting value (if any), which induces a congruence relation on open terms called operational equivalence (see e.g. Plotkin (1975)). Then the problem is to prove that two terms are operationally equivalent.

• The denotational approach gives an interpretation of the (programming) language in a mathematical structure, the intended model.

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• The logical approach gives a class of possible models for the (programming) language. Then the problem is to prove that two terms denote the same object in all possible models.

The operational and denotational approaches give only a theory: the

operational equivalence  $\approx$  or the set Th of formulas valid in the intended model, respectively. On the other hand, the logical approach gives a conse-Research partially supported by EEC Joint Collaboration Contract ST2J-0374-C(EDB).

0890-5401/91 \$3.00 Constight an 1991 by Academic Press. Inc. rights of reproduction in any form reserved. All rights of

#### In his subsequent work, a **computationally natural** approach was taken

DEFINITION 1.2 (Manes, 1976). A Kleisli triple over a category & is a triple  $(T, \eta, -*)$ , where  $T: Obj(\mathscr{C}) \to Obj(\mathscr{C}), \eta_A: A \to TA$  for  $A \in Obj(\mathscr{C}),$  $f^*: TA \to TB$  for  $f: A \to TB$  and the following equations hold: •  $\eta_A; f^* = f \text{ for } f: A \to TB$ •  $f^*; g^* = (f; g^*)^*$  for  $f: A \to TB$  and  $g: B \to TC$ . for proving equivalence EXAMPLE 1.4. We go through the notions of computation given in terms, of the Example 1.1 and show that they are indeed part of suitable Kleisli triples. nticstics. ) its partiality  $TA = A_{\perp}(=A + \{\perp\})$ rms h is  $\eta_A$  is the inclusion of A into  $A_{\perp}$ if  $f: A \to TB$ , then  $f^*(\bot) = \bot$  and  $f^*(a) = f(a)$  (when  $a \in A$ ) • nondeterminism  $TA = \mathscr{P}_{fin}(A)$  $\eta_A$  is the singleton map  $a \mapsto \{a\}$ if  $f: A \to TB$  and  $c \in TA$ , then  $f^*(c) = \bigcup_{x \in c} f(x)$ • side-effects  $TA = (A \times S)^S$  $\eta_A$  is the map  $a \mapsto (\lambda s: S, \langle a, s \rangle)$ if  $f: A \to TB$  and  $c \in TA$ , then  $f^*(c) = \lambda s$ : S.(let  $\langle a, s' \rangle = c(s)$  in f(a)(s'))

#### Comprehending Monads

Philip Wadler University of Glasgow

#### Abstract

Category theorists invented monads in the 1960's to concisely express certain aspects of universal algebra. Functional programmers invented *list comprehensions* in the 1970's to concisely express certain programs involving lists. This paper shows how list comprehensions may be generalised to an arbitrary monad, and how the resulting programming feature can concisely express in a pure functional language some programs that manipulate state, handle exceptions, parse text, or invoke continuations. A new solution to the old problem of destructive array update is also presented. No knowledge of category theory is assumed.

#### 1 Introduction

Is there a way to combine the indulgences of impurity with the blessings of purity? Impure, strict functional languages such as Standard ML [Mil84, HMT88] and Scheme [RC86] support a wide variety of features, such as assigning to state, handling exceptions, and invoking continuations. Pure, lazy functional languages such as Haskell [HPW91] or Miranda<sup>1</sup> [Tur85] eschew such features, because they are incompatible with the advantages of lazy evaluation and equational reasoning, advantages that have been described

Purity has its regrets, and all programmers in pure functional languages will recall

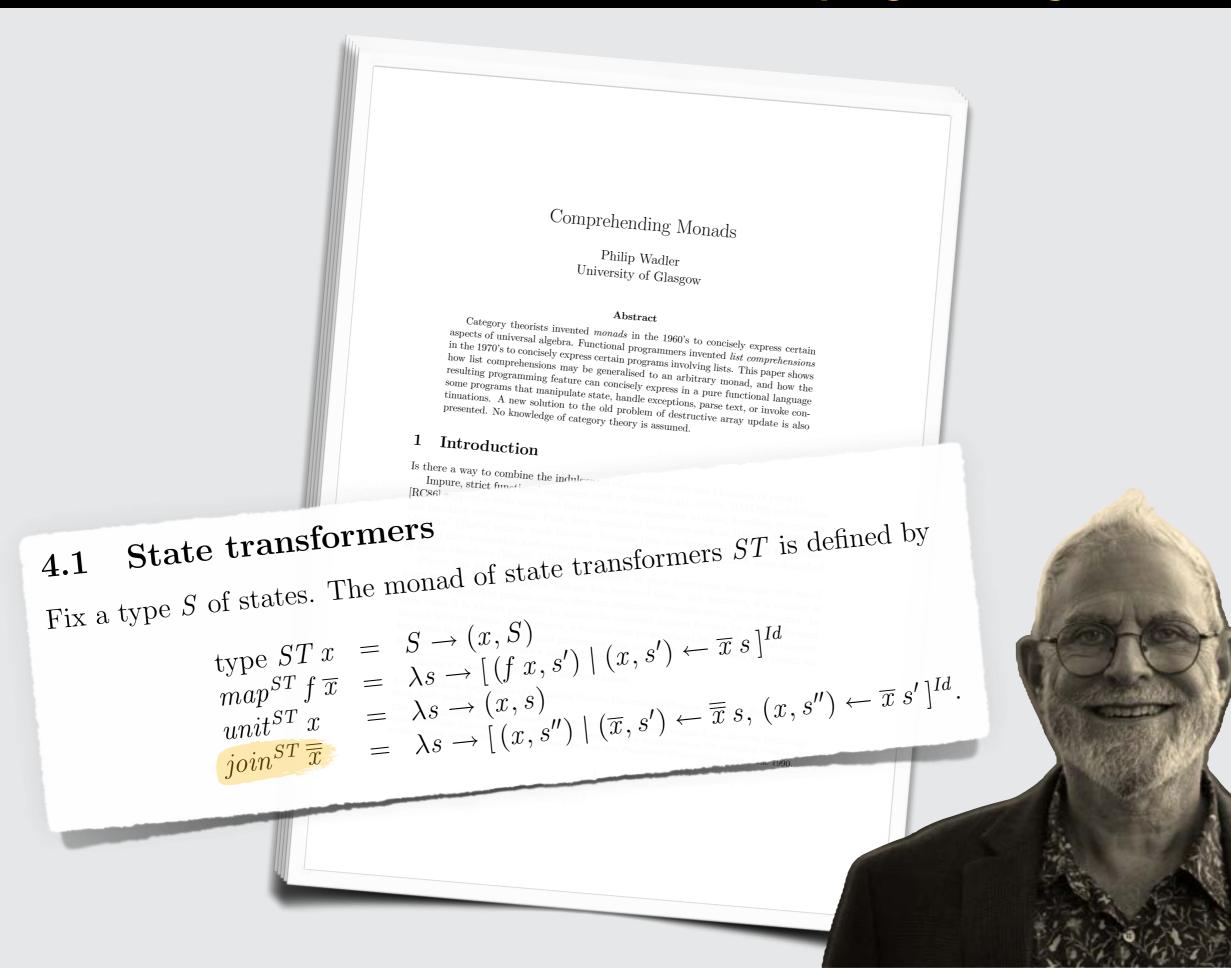
some moment when an impure feature has tempted them. For instance, if a counter is required to generate unique names, then an assignable variable seems just the ticket. In such cases it is always possible to mimic the required impure feature by straightforward though tedious means. For instance, a counter can be simulated by modifying the relevant functions to accept an additional parameter (the counter's current value) and return an

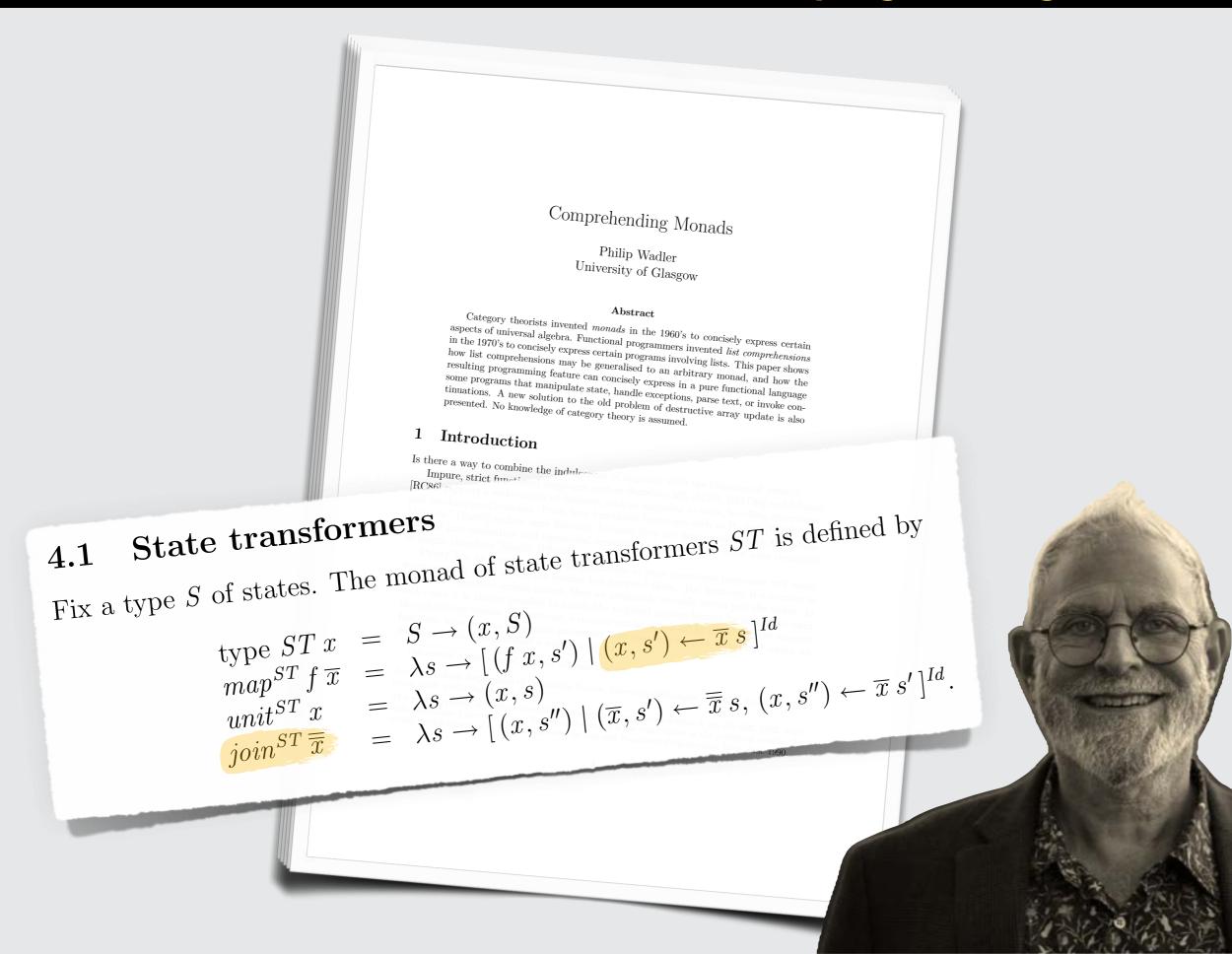
<sup>1</sup>Miranda is a trademark of Research Software Limited.

tronic mail: wadler@cs.glasgow.ac.uk.

Author's address: Department of Computing Science, University of Glasgow, G12 8QQ, Scotland. Elec-

This paper appeared in Mathematical Structures in Computer Science volume 2, pp. 461–493, 1992; copyrins paper appeared in *automatical on actures in compact occure* volume 2, pp. 407–430, 1332, copy-right Cambridge University Press. This version corrects a few small errors in the published version. An earlier version appeared in ACM Conference on Lisp and Functional Programming, Nice, June 1990.





7.1 Parsers The monad of parsers is given by  $\begin{array}{l} \stackrel{type \ Parse \ x}{map \ Parse \ f \ \overline{x}} &= \ String \rightarrow List\left(x, String\right) \\ \stackrel{unit \ Parse \ x}{i \rightarrow [(f \ x, i') \mid (x, i') \leftarrow \overline{x} \ i]^{List}} \\ \stackrel{join \ Parse \ \overline{x}}{\overline{x}} &= \ \lambda i \rightarrow [(x, i)]^{List} \\ \stackrel{\iota(x, i'') \mid (\overline{x}, i') \leftarrow \overline{x} \ i, (x, i'') \leftarrow \overline{x} \ i']^{I}} \end{array}$ Fix a type S of states. The monad of state transformers ST is defined by State transformers 

#### An effect is specified with a monad and additional operations

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monad  $TX = \mathscr{P}X$  $\eta(x) = \{x\}$  $c \gg k = \bigcup k(c)$  $x \in C$ 

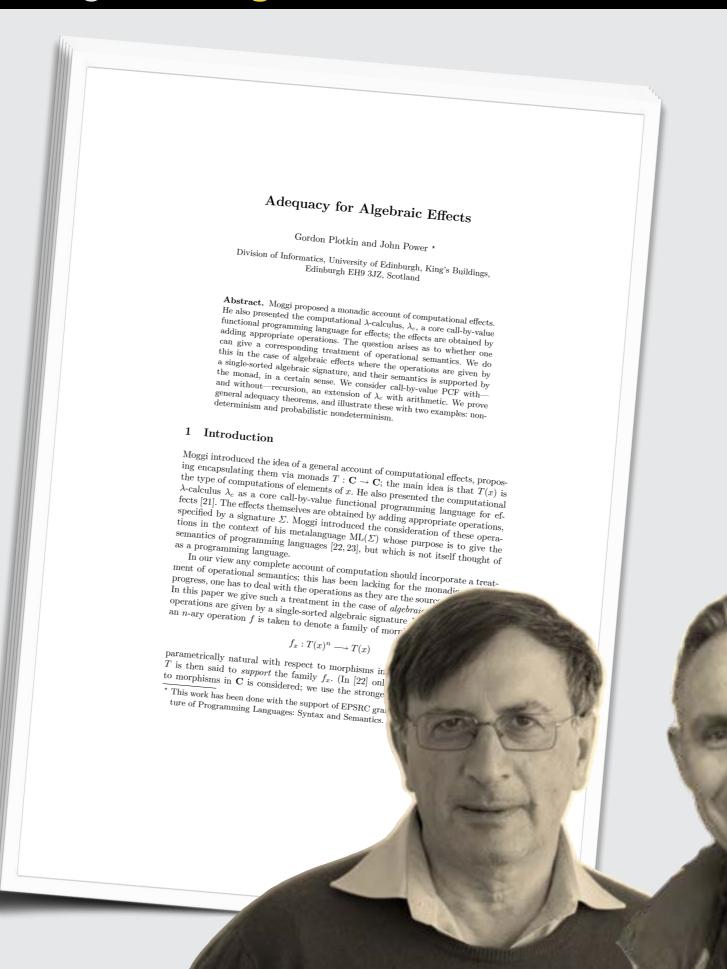
#### An effect is specified with a monad and additional operations

monad  

$$TX = \mathscr{P}X$$
  
 $\eta(x) = \{x\}$   
 $c \gg k = \bigcup_{x \in c} k(c)$ 

 $\begin{array}{l} \textbf{effect-specific operations}\\ \texttt{fail}:TX\\ \texttt{fail}=\{\}\\ \texttt{choose}:TX\times TX \rightarrow TX\\ \texttt{choose}(c_1,c_2)=c_1 \cup c_2 \end{array}$ 

#### Plotkin & Power recognised algebraic theories as sources of effects



## An effect is specified with **operations** and **equations**

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## operations fail:0 choose:2

## operations fail:0

choose: 2

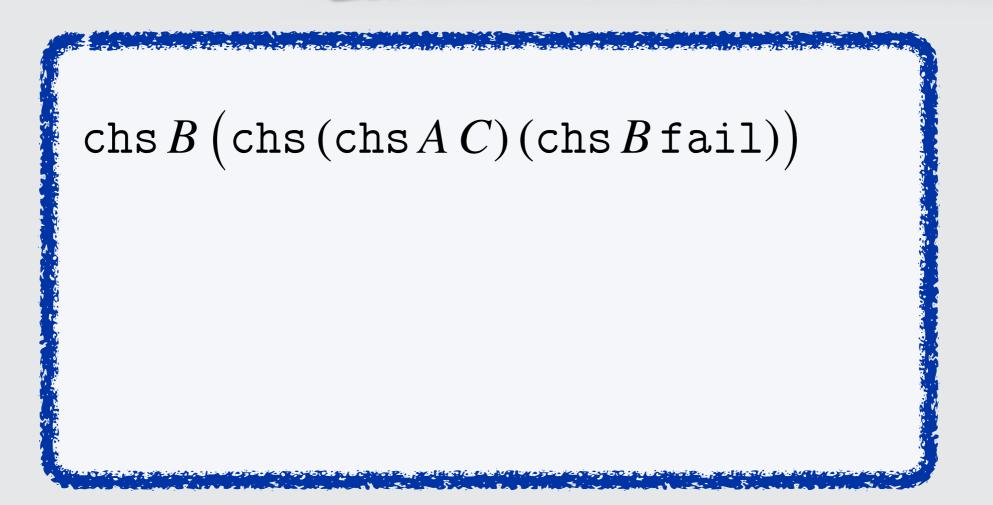
## equations

 $\begin{array}{l} {\rm choose}\,({\rm choose}\,M\,N)\,P={\rm choose}\,M\,({\rm choose}\,N\,P)\\ {\rm choose}\,M\,N={\rm choose}\,N\,M\\ {\rm choose}\,M\,M=M\\ {\rm choose}\,fail\,M=M={\rm choose}\,M\,fail \end{array}$ 

fail:0
choose:2

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 $chs B (chs (chs A C) (chs B fail)) \\ = chs B (chs A (chs C (chs B fail)))$ 

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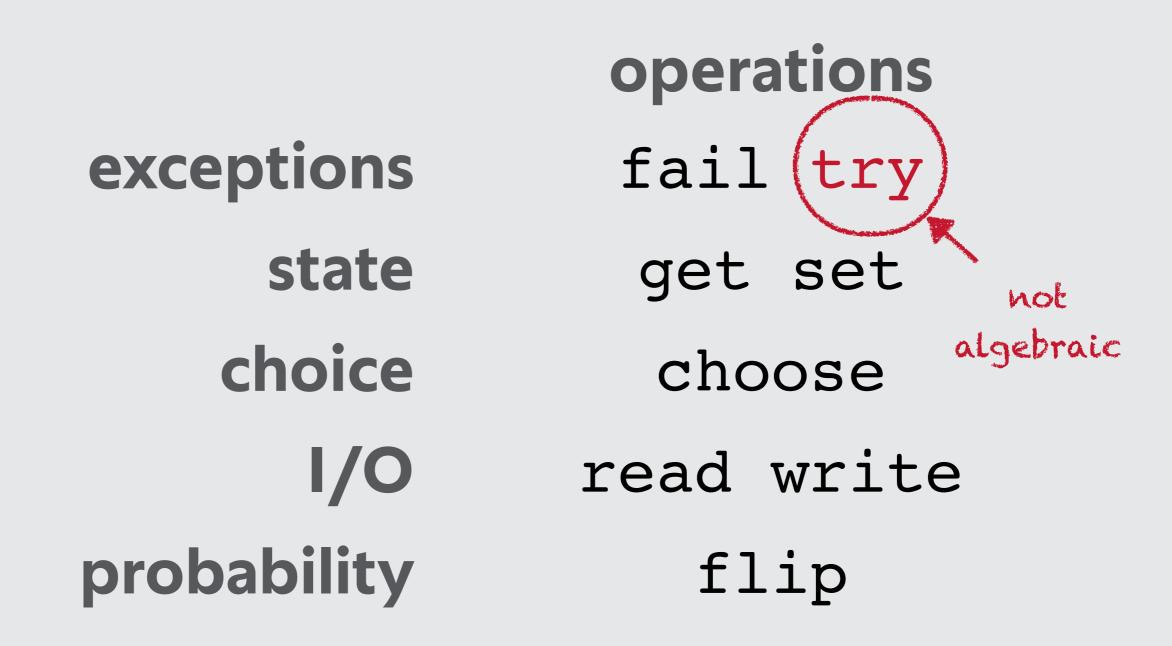
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## equations

 $\begin{array}{l} {\rm choose}\,({\rm choose}\,M\,N)\,P={\rm choose}\,M\,({\rm choose}\,N\,P)\\ {\rm choose}\,M\,N={\rm choose}\,N\,M\\ {\rm choose}\,M\,M=M\\ {\rm choose}\,fail\,M=M={\rm choose}\,M\,fail \end{array}$ 

 $\begin{aligned} \operatorname{chs} B\left(\operatorname{chs}\left(\operatorname{chs} A C\right)\left(\operatorname{chs} B \operatorname{fail}\right)\right) \\ &= \operatorname{chs} B\left(\operatorname{chs} A\left(\operatorname{chs} C\left(\operatorname{chs} B \operatorname{fail}\right)\right)\right) \\ &= \operatorname{chs} \operatorname{fail}\left(\operatorname{chs} A\left(\operatorname{chs} B\left(\operatorname{chs} B C\right)\right)\right) \\ &= \operatorname{chs} A\left(\operatorname{chs} B C\right) \approx \{A, B, C\} \end{aligned}$ 

Exception handling failed to be algebraic



try(fail, M) = Mtry(val V, M) = val Vhandling

handling  
try(fail, 
$$M$$
) =  $M$ try(val  $V, M$ ) = val  $V$ do  $x \leftarrow try(M_1, M_2)$  in  $N$ = try(do  $x \leftarrow M_1$  in  $N$ , do  $x \leftarrow M_2$  in  $N$ )

handling  

$$try(fail, M) = M$$
  
 $try(val V, M) = val V$  algebraicity  
 $do x \leftarrow try(M_1, M_2) in N$   
 $= try(do x \leftarrow M_1 in N, do x \leftarrow M_2 in N)$   
 $do x \leftarrow val 0 in N$ 

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 $do x \leftarrow val 0 in N$   
 $= do x \leftarrow try(val 0, val 1) in N$ 

#### Why handling is **not** an **algebraic** operation?

$$\begin{aligned} \text{try}(\text{fail}, M) &= M \\ \text{try}(\text{val} V, M) &= \text{val} V \end{aligned}$$

$$\begin{aligned} \text{do } x &\leftarrow \text{try}(M_1, M_2) \text{ in } N \\ &= \text{try}(\text{do } x &\leftarrow M_1 \text{ in } N, \text{do } x &\leftarrow M_2 \text{ in } N) \end{aligned}$$

 $do x \Leftarrow val 0 in N$ = do x \leftarrow try(val 0,val 1) in N = try(do x \leftarrow val 0 in N, do x \leftarrow val 1 in N)

# Why handling is not an algebraic operation?

$$try(fail, M) = M$$
  

$$try(val V, M) = val V$$
  

$$do x \leftarrow try(M_1, M_2) in N$$
  

$$= try(do x \leftarrow M_1 in N, do x \leftarrow M_2 in N)$$
  

$$\frac{do x \leftarrow val 0 in N}{failing}$$
  

$$= do x \leftarrow try(val 0, val 1) in N$$
  

$$= try(do x \leftarrow val 0 in N, do x \leftarrow val 1 in N)$$

# Why handling is **not** an **algebraic** operation?

$$\begin{aligned} \text{try}(\text{fail}, M) &= M \\ \text{try}(\text{val} V, M) &= \text{val} V \\ \text{do } x \in \text{try}(M_1, M_2) \text{ in } N \\ &= \text{try}(\text{do } x \in M_1 \text{ in } N, \text{do } x \in M_2 \text{ in } N) \\ &= \text{try}(\text{do } x \notin M_1 \text{ in } N, \text{do } x \notin M_2 \text{ in } N) \\ \hline \\ &= \text{do } x \notin \text{try}(\text{val} 0, \text{val} 1) \text{ in } N \\ &= \text{try}(\text{do } x \notin \text{val} 0 \text{ in } N, \text{do } x \notin \text{val} 1 \text{ in } N) \\ &= \text{do } x \notin \text{val} 0 \text{ in } N, \text{do } x \notin \text{val} 1 \text{ in } N) \\ &= \text{do } x \notin \text{val} 0 \text{ in } N, \text{do } x \notin \text{val} 1 \text{ in } N) \end{aligned}$$

On the other hand, for example, the exceptions monad does not support its exception handling operation: only the weaker naturality holds there. This monad is a free algebra functor for an equational theory, viz the one that has a constant for each exception and no equations; however the exception handling operation is not definable: only the exception raising operations are. Other standard monads present further difficulties. So while our account of operational semantics is quite general, it certainly does not cover all cases; it remains to be seen if it can be further extended.

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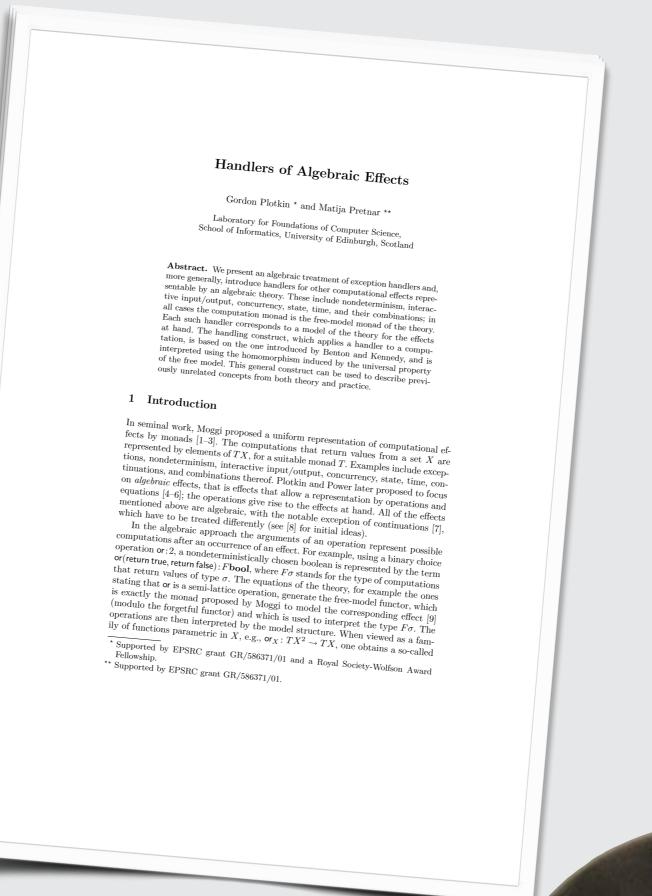
Of the various operations, **handle** is of a different computational character and, although natural, it is not algebraic. Andrzej Filinski (personal communication) describes **handle** as a *deconstructor*, whereas the other operations are *constructors* (of effects). In this paper, we make the notion of constructor precise by identifying it with the notion of *algebraic* operation.

# constructors deconstructors **exceptions** fail try state get set choice choose **I/O** read write probability flip

Mathematics was already suggesting **unrevealed constructs** 

# constructors deconstructors **exceptions** fail try state get set choice choose 1/O read write probability flip

#### Exception handlers are **homomorphisms** and they **generalise to other effects**





#### The next step was implementing handlers in **practice**

# The Programming Languages Zoo

A potpourri of programming languages

> home

#### About the zoo

The Programming Languages Zoo is a collection of miniature programming languages which demonstrates various concepts and techniques used in programming language design and implementation. It is a good starting point for those who would like to implement their own programming language, or just learn how it is done.

The following features are demonstrated:

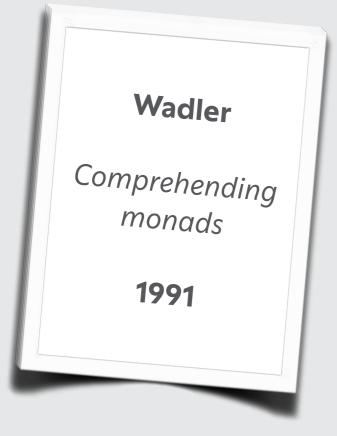
- >>> functional, declarative, object-oriented, and procedural languages
- >> source code parsing with a parser generator
- >> keep track of source code positions
- >> pretty-printing of values
- >> interactive shell (REPL) and non-interactive file processing
- >> untyped, statically and dynamically typed languages
- >> type checking and type inference
- >> subtyping, parametric polymorphism, and other kinds of type systems
- >> eager and lazy evaluation strategies
- >> recursive definitions
- >> exceptions
- >> interpreters and compilers
- >> abstract machine

#### Installation

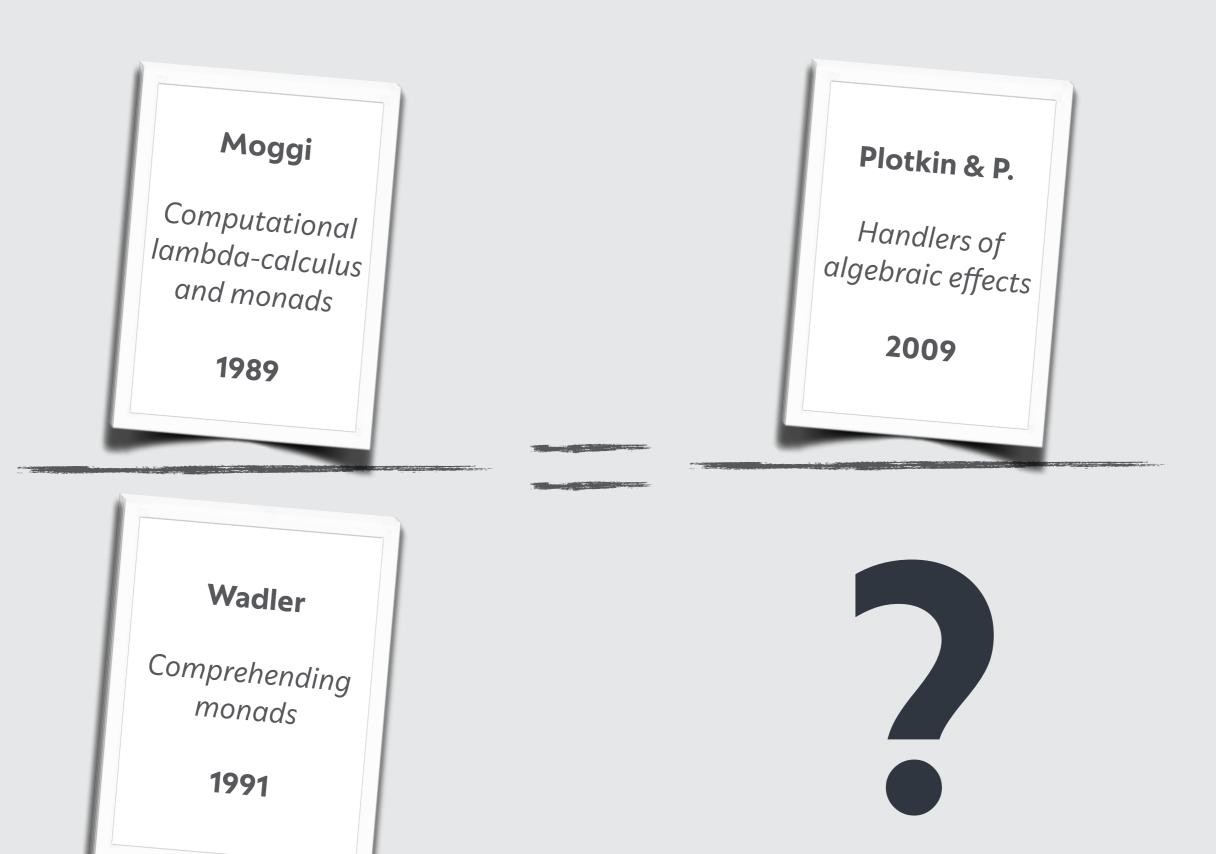
See the installation & compilation instructions.

### We wanted to **do the same for handlers** as Wadler did for monads





### We wanted to **do the same for handlers** as Wadler did for monads



#### Initial version of Eff had a Python-like syntax and was untyped

# **Mathematics and Computation**

A blog about mathematics for computers

Posts Talks Publications Software About

← How eff handles built-in effects

Programming with effects I: Theory →

#### **Programming with effects II: Introducing eff**

Q 27 September 2010

💄 Matija Pretnar

Computation, Eff, Guest post, Programming, Software, Tutorial

#### [UPDATE 2012-03-08: since this post was written eff has changed considerably. For updated information, please visit the eff page.]

\*\*This is a second post about the programming language eff. We covered the theory behind it in a <u>previous post</u>. Now we turn to the programming language itself.

Please bear in mind that eff is an academic experiment. It is not meant to take over the world. Yet. We just wanted to show that the theoretical ideas about the algebraic nature of computational effects can be put into practice. Eff has many superficial similarities with Haskell. This is no surprise because there is a precise connection between algebras and monads. The main advantage of eff over Haskell is supposed to be the ease with which computational effects can be combined.

#### Installation

If you have Mercurial installed (type hg at command prompt to find out) you can get eff like this:

```
$ hg clone http://hg.andrej.com/eff/ eff
```

Otherwise, you may also download the latest source as a <u>.zip</u> or <u>.tar.gz</u>, or <u>visit the repository with your browser</u> for other versions. Eff is

Initial version of Eff had a Python-like syntax and was untyped

# **Mathematics and Computation** A blo o for computers effect state x: Posts operation get (): (lambda s: yield s s) **operation** set s\_new: (lambda s: yield return y: () s\_new) (lambda s: (s, y)) finally f: f x surprise Dou ease with which computational en

#### Installation

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### Next version added types and moved much closer to OCaml

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← The topology of the set of all types

Programming with Algebraic Effects an...  $\rightarrow$ 



● 08 March 2012 ▲ Andrej Bauer ■ Eff, News

Matija and I are pleased to announce a new major release of the eff programming language.

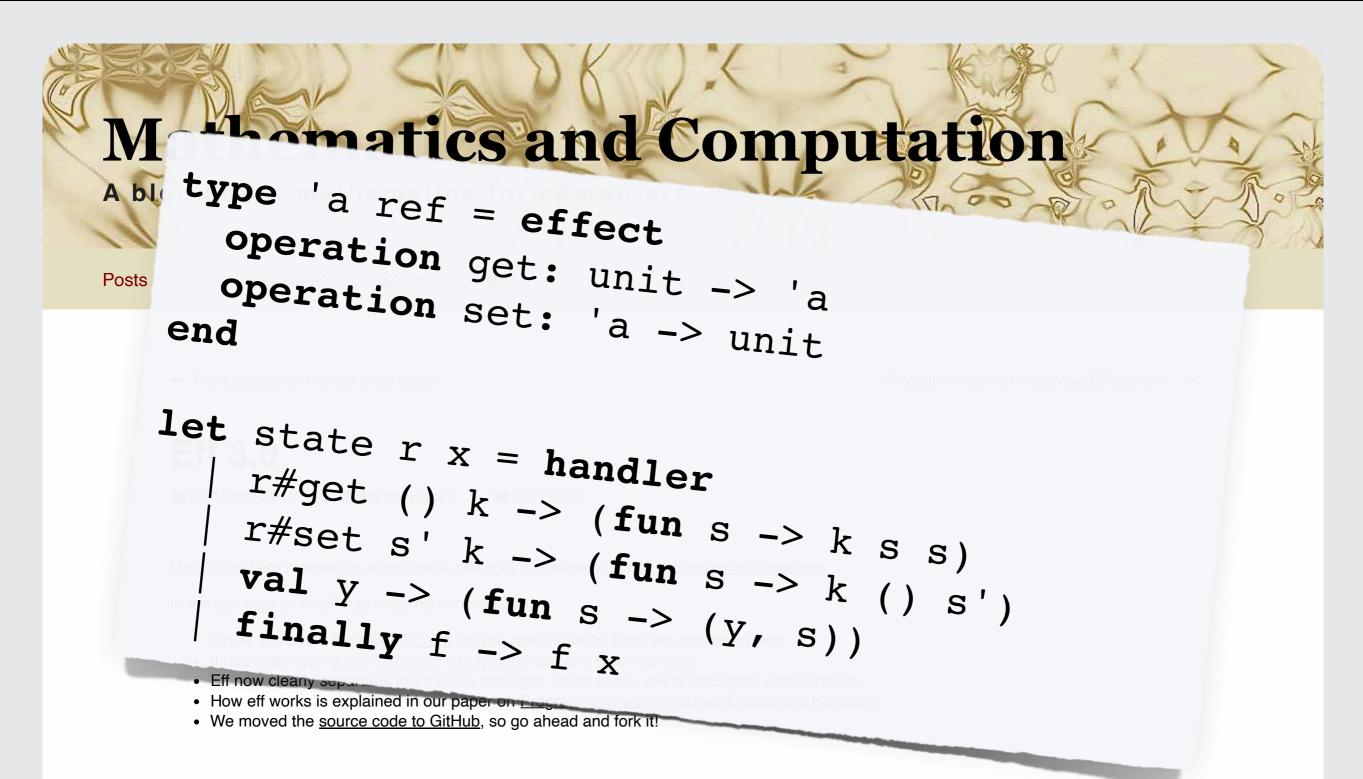
In the last year or so eff has matured considerably:

- It now looks and feels like <u>OCaml</u>, so you won't have to learn yet another syntax.
- It has static typing with parametric polymorphism and type inference.
- Eff now clearly separates three basic concepts: effect types, effect instances, and handlers.
- How eff works is explained in our paper on Programming with Algebraic Effects and Handlers.
- We moved the source code to GitHub, so go ahead and fork it!

#### Comments



Next version added types and moved much closer to OCaml



#### Comments



### The new version of Eff also had an accompanying research paper



Moggi	Plotkin & P.
Computational lambda-calculus and monads	Handlers of algebraic of
the same holds for algebraic effects and handlers, we stream the same holds for algebraic effects and handlers, we stream	mming concept would not have been discovered without their mmers could live in blissful ignorance of their origin. Because mlined the paper for the benefit of programmers, trusting that lying mathematical theory. syntax of <i>Eff</i> , Section 2 informally introduces constructs specific re give a domain-theoretic semantics of <i>Eff</i> , and in Section 5 we es in Section 6 demonstrate how effects and handlers can be
to Eff, Section 3 is devoted to eyror briefly discuss our prototype implementation. The example	
Comprehending monads 1991	Calculate To a function of the state of t

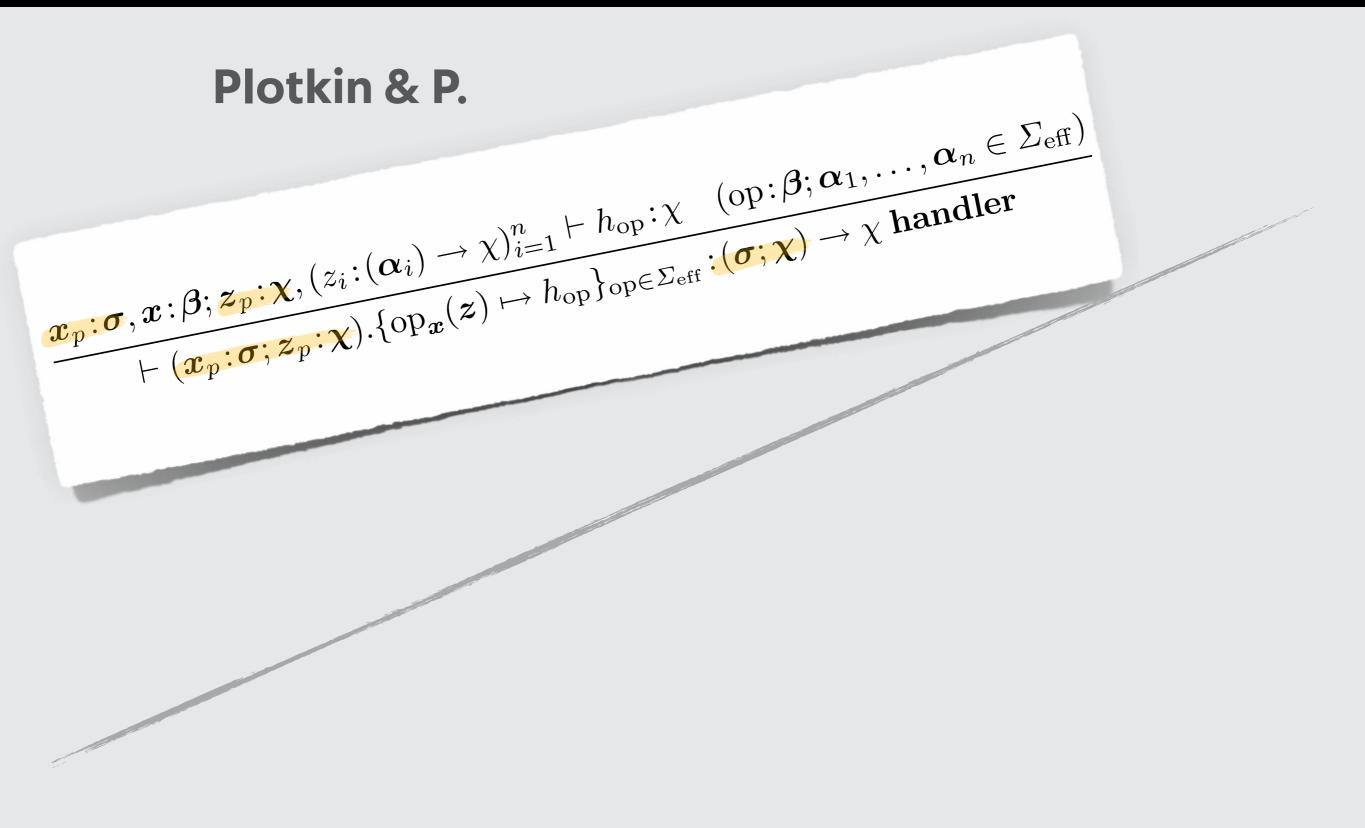
Moggi	Plotkin & P.
Computational lambda-calculus and monads	Handlers of algebraic off
the same holds for algebraic effects and handlers, we stream the same holds for algebraic effects and handlers, we stream the same holds for algebraic the connections with the under	we give a domain theory of the state how effects and handlers can be
Vadler Comprehending Monads	<text></text>
1991	The definition of the definiti

Moggi Computational lambda-calculus and monads	Plotkin & P. Handlers of algebraic off
Philip Wadler once opined [21] that monad category-theoretic counterparts, but once they the same holds for algebraic effects and handle resiscours will recognize the connections w	n Section 4 we give a domain the
Vadler Comprehending monads 1991	<image/>

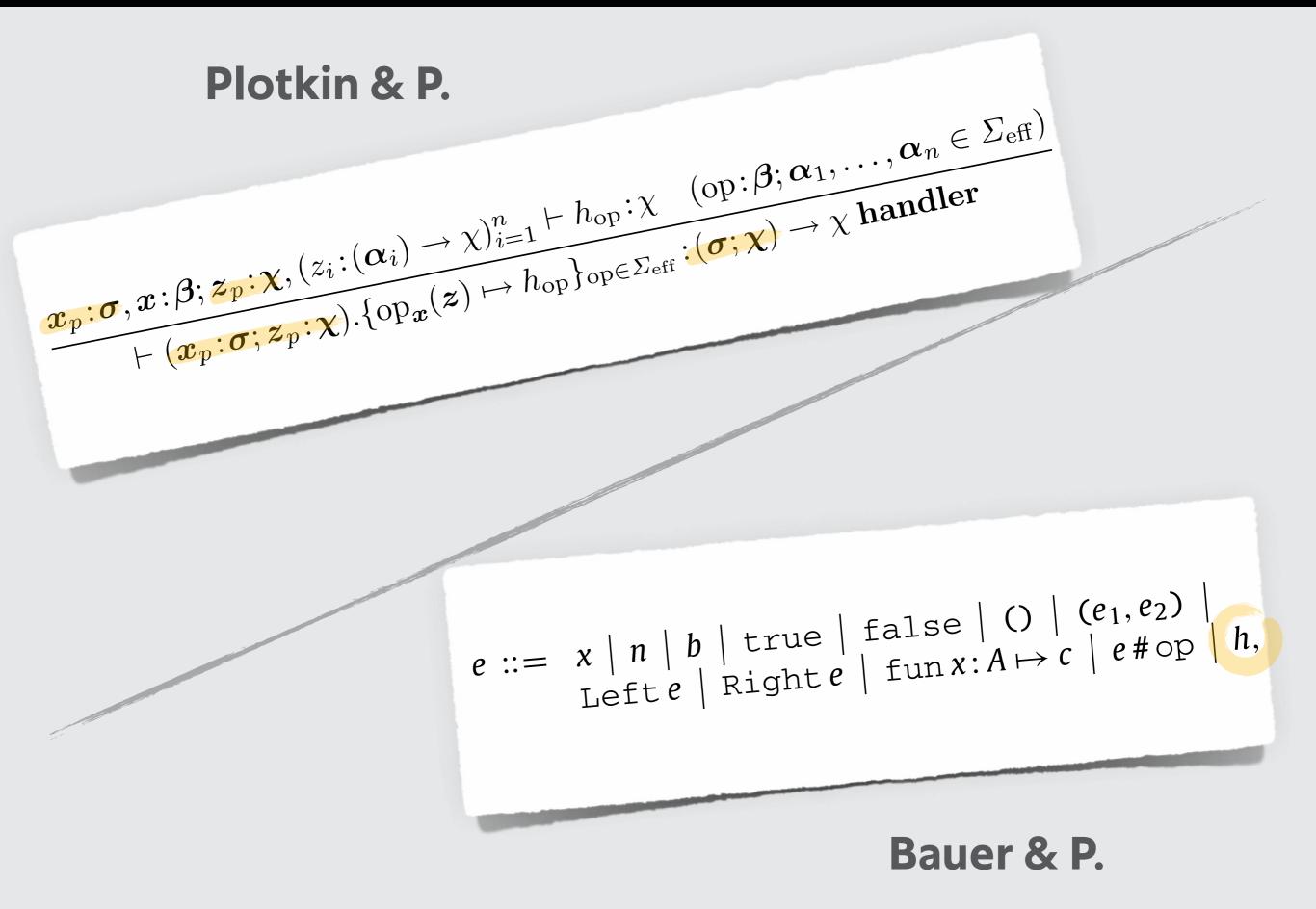
Moving from mathematics to programming gave extra flexibility

Plotkin & P.

Moving from mathematics to programming gave extra flexibility



Moving from mathematics to programming gave extra flexibility



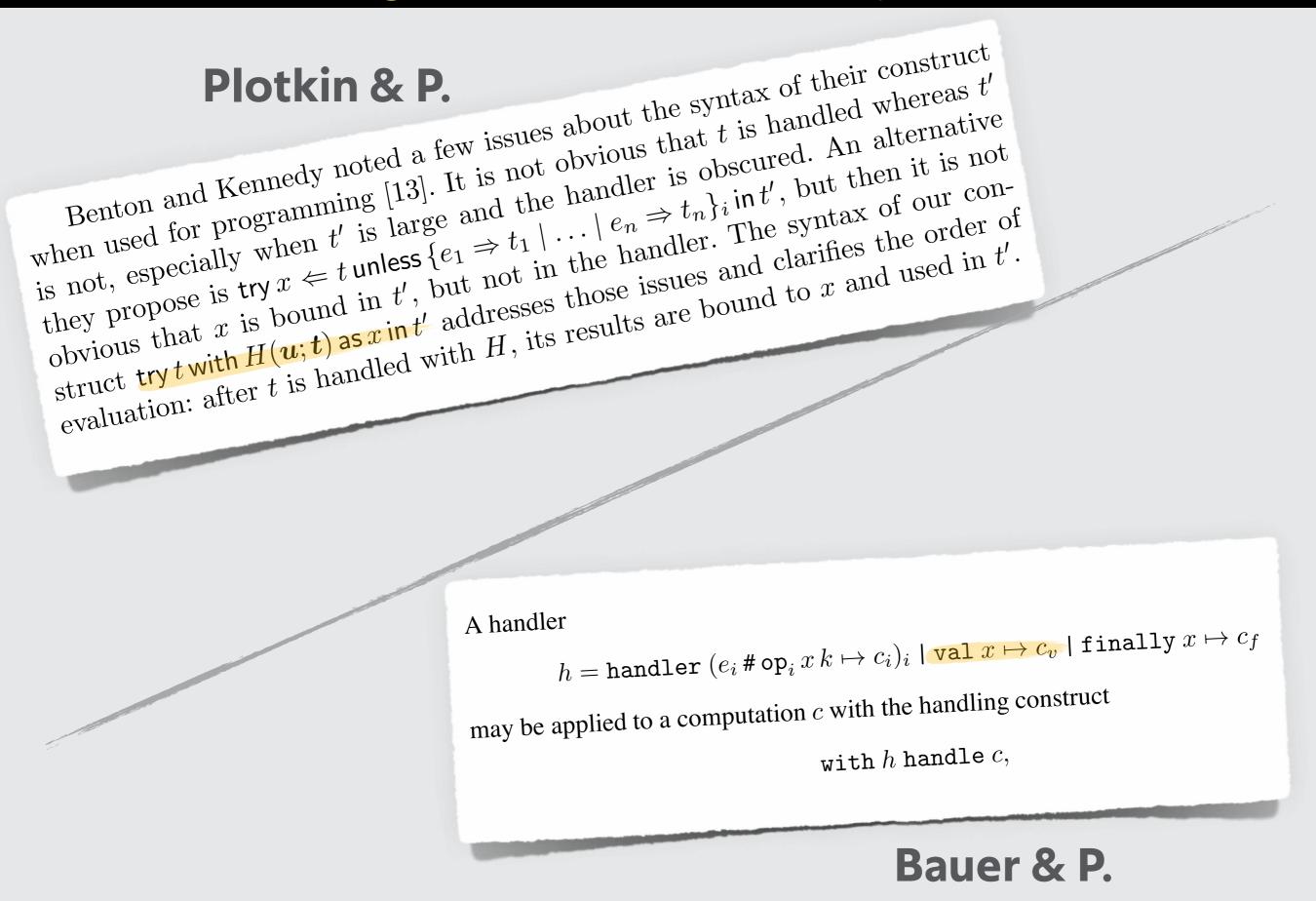
**Plotkin & P.** 

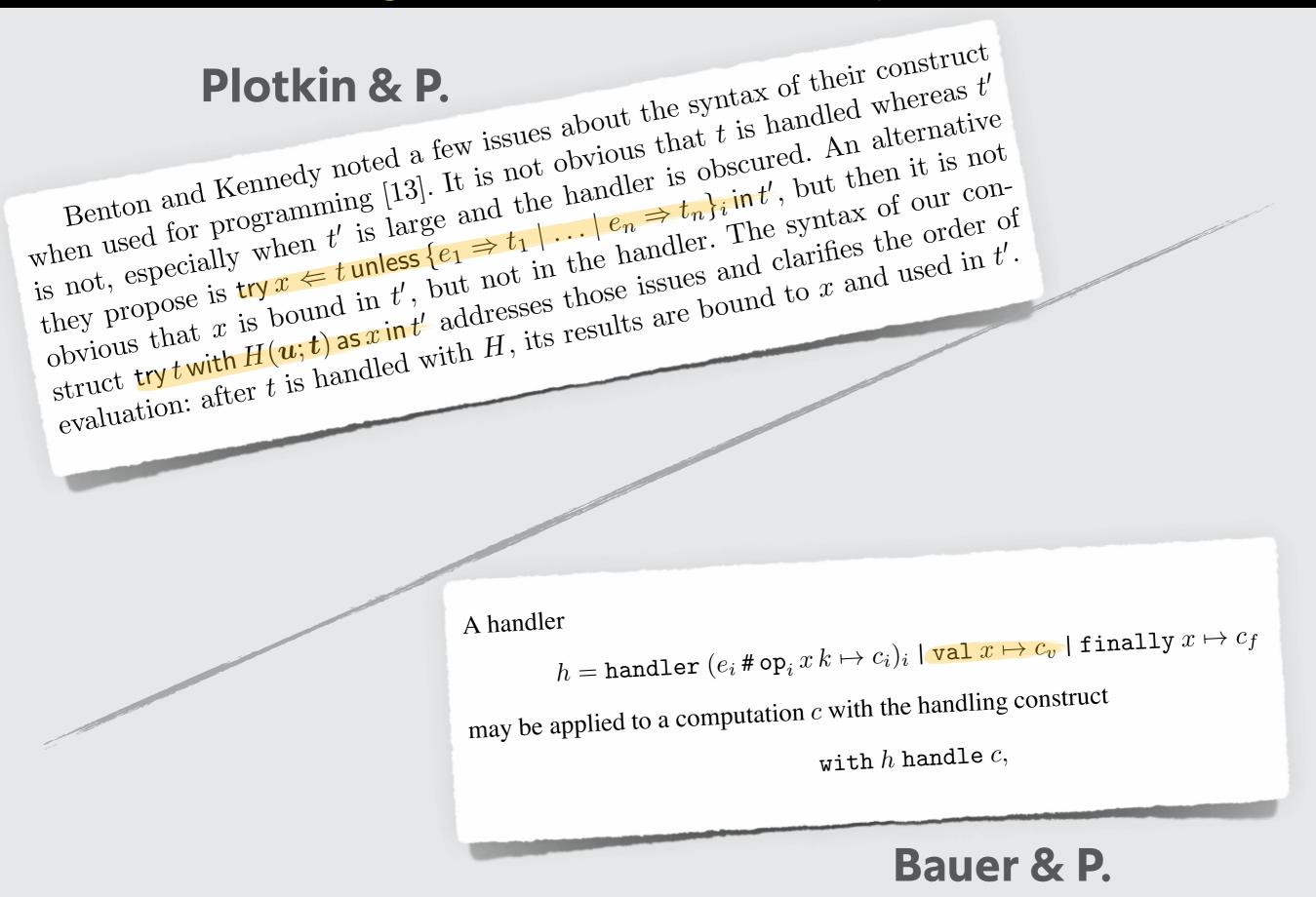
Plotkin & P.

A handler

 $h = \texttt{handler} \; (e_i \, \texttt{\#} \, \texttt{op}_i \, x \, k \mapsto c_i)_i \; | \; \texttt{val} \; x \mapsto c_v \; | \; \texttt{finally} \; x \mapsto c_f$ may be applied to a computation c with the handling construct

with h handle c,





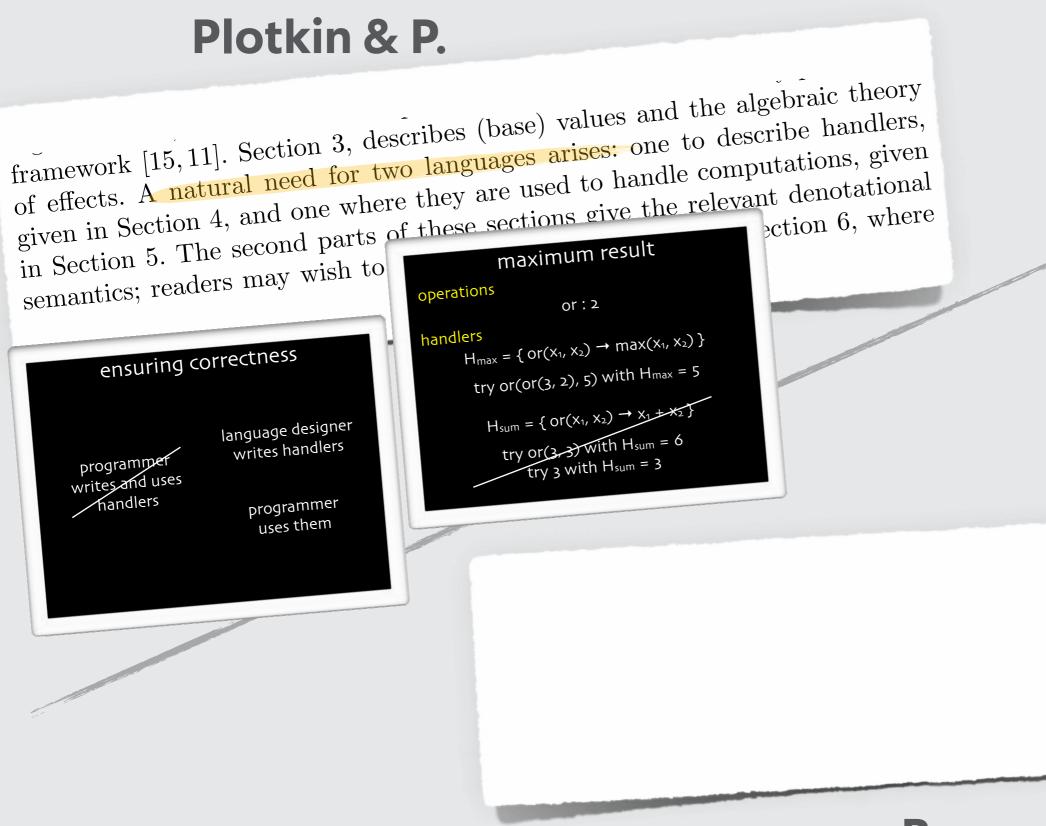
Plotkin & P.

# Plotkin & P.

framework [15, 11]. Section 3, describes (base) values and the algebraic theory of effects. A natural need for two languages arises: one to describe handlers, given in Section 4, and one where they are used to handle computations, given in Section 5. The second parts of these sections give the relevant denotational semantics; readers may wish to omit these and continue with Section 6, where

# **Plotkin & P.** framework [15, 11]. Section 3, describes (base) values and the algebraic theory of effects. A natural need for two languages arises: one to describe handlers, given in Section 4, and one where they are used to handle computations, given in Section 5. The second parts of these sections give the relevant denotational semantics; readers may wish to omit these and continue with Section 6, where ensuring correctness language designer writes handlers programmer writes and uses handlers programmer uses them

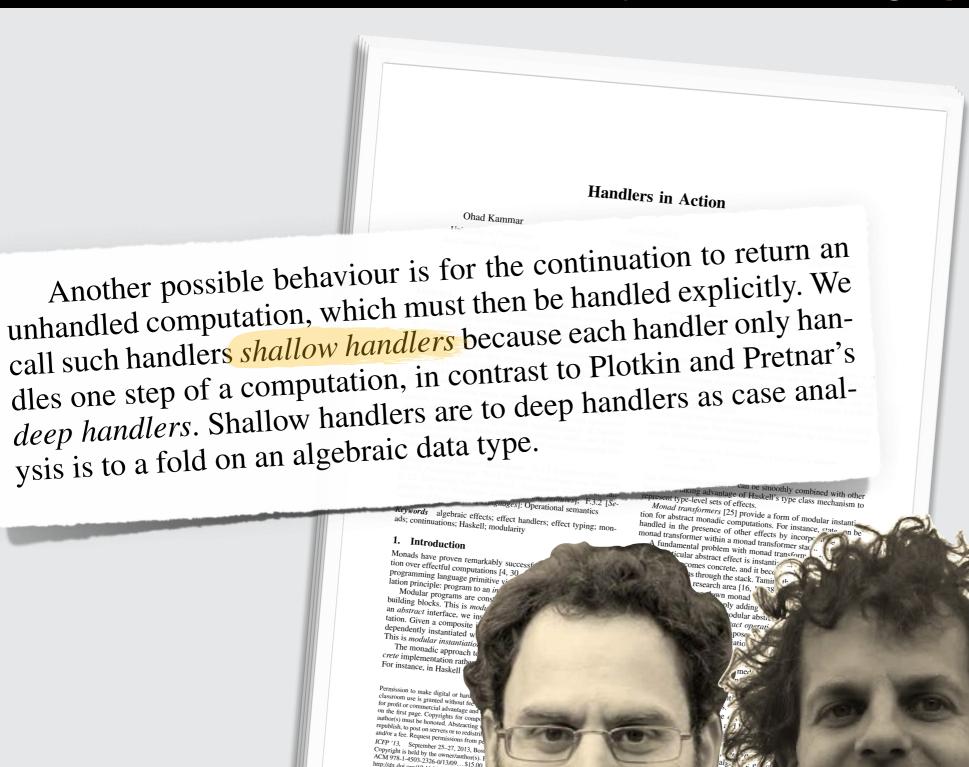
#### **Plotkin & P.** framework [15, 11]. Section 3, describes (base) values and the algebraic theory of effects. A natural need for two languages arises: one to describe handlers, given in Section 4, and one where they are used to handle computations, given in Section 5. The second parts of these sections give the relevant denotational semantics; readers may wish to operations or:2 $H_{max} = \{ or(x_1, x_2) \rightarrow max(x_1, x_2) \}$ handlers ensuring correctness try or(or(3, 2), 5) with H<sub>max</sub> = 5 $H_{sum} = \{ \operatorname{Or}(X_1, X_2) \rightarrow X_1 \pm X_2 \}$ language designer try Or(3-3) with $H_{sum} = 6$ writes handlers programmer try 3 with H<sub>sum</sub> = 3 writes and uses handlers programmer uses them



### Shallow handlers were visible only when looking operationally

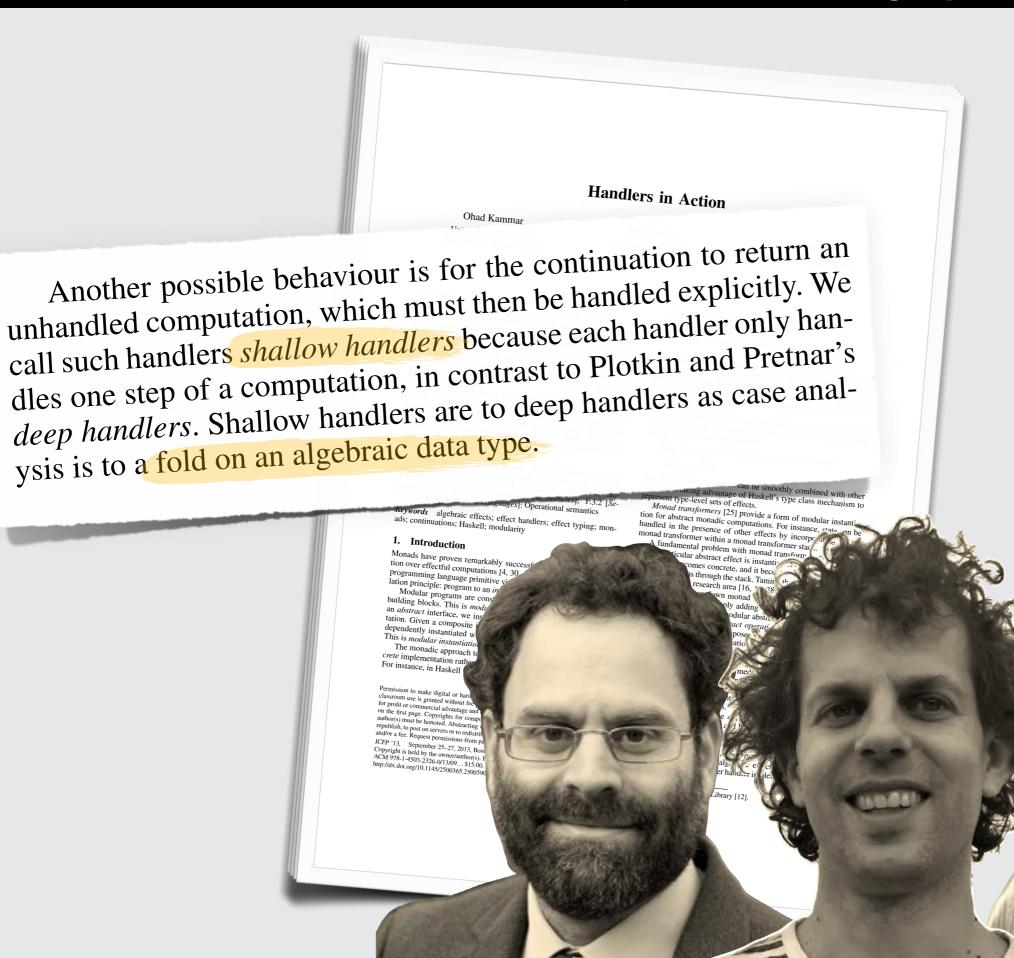


#### **Shallow** handlers were visible only when looking **operationally**



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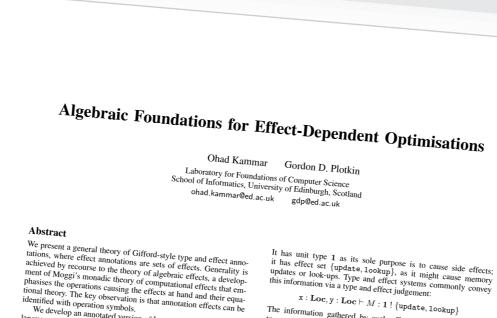
#### Shallow handlers were visible only when looking operationally







#### Equations not only describe effects, but entail additional laws



We develop an annotated version of Levy's Call-by-Push-Value language with a kind of computations for every effect set; it can tanguage with a kind of computations for every effect set; it can be thought of as a sequential, annotated intermediate language. We develop a range of validated optimisations (i.e., equivalences), generalising many existing ones and adding new ones. We classify these optimisations as structural, algebraic, or abstract: structural optimisations always hold; algebraic ones depend on the effect theory at hand; and abstract ones depend on the global nature of that theory (we give modularly-checkable sufficient conditions for their validity).

Categories and Subject Descriptors D.3.4 [Processors]: Compil-Categories and Subject Descriptors D.5.4 [Processors]: Comput-ers; Optimization; F.3.1 [Specifying and Verifying and Reasoning about Programs]: Logics of programs; F.3.2 [Semantics of Pro-gramming Languages]: Algebraic approaches to semantics; Denotational semantics; Program analysis; F.3.3 [Studies of Program General Terms Languages, Theory.

Keywords Call-by-Push-Value, algebraic theory of effects, code transformations, compiler optimisations, computational effects, denotational semantics, domain theory, inequational logic, relevant and affine monads, sum and tensor, type and effect systems, uni-

#### 1. Introduction

In Gifford-style type and effect analysis [27], each term of a programming language is assigned a type and an effect set. The type describes the values the term may evaluate to; the effect set describes the effects the term may cause during its computation, such as memory assignment, exception raising, or I/O. For example, consider the following term M:

if true then x := 1 else x := deref(y)

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updates or look-ups. Type and effect systems commonly convey

The information gathered by such effect analyses can be used to guarantee implementation correctness<sup>1</sup>, to prove authenticity properties [15], to aid resource management [44], or to optimise code using transformations. We focus on the last of these. As an example, purely functional code can be executed out of order:

 $\mathbf{x} \leftarrow M_1; \ \mathbf{y} \leftarrow M_2; \ N \quad = \quad \mathbf{y} \leftarrow M_2; \ \mathbf{x} \leftarrow M_1; \ N$ 

This reordering holds more generally, if the terms  $M_1$  and  $M_2$  have non-interfering effects. Such transformations are commonly used in optimising compilers. They are traditionally called optimisations, even if neither side is always the more optimal.

In a sequence of papers, Benton et al. [4–8] prove soundness of such optimisations for increasingly complex sets of effects. However, any change in the language requires a complete reformulation of its semantics and so of the soundness proofs, even though the essential reasons for the validity of the optimisations remain the same. Thus, this approach is not robust, as small language changes

A possible way to obtain robustness is to study effect systems in general. One would hope for a modular approach, seeking to isolate those parts of the theory that change under small language changes, and then recombining them with the unchanging parts. Such a theory may not only be important for compiler optimisations in big, stable languages. It can also be used for effect-dependent equational reasoning. This use may be especially helpful in the case of small, domain-specific languages, as optimising compiler are hardly ever designed for them and their diversity neces

The only available general work on effect system be that of Marino and Millstein [28]. They devise a to derive type and effect frameworks which they by-value language with recursion and reference methodology does not account for effect-depend Fortunately, Wadler and Thiemann [46, 4 made an important connection with the mon computational effects. They translated judgem  $\Gamma \vdash M : A \mid \varepsilon$  in a region analysis calculus form  $\Gamma' \vdash M' : T_{\varepsilon}A$  in a multi-monadic cal

latter calculus an operational semantics, and tence of a corresponding general monadic denin which  $T_{\varepsilon}$  would denote a monad correspondir  $\varepsilon$ , and in which the partial order of effect sets and ir <sup>1</sup>E. Cooper, S. Lindley, P. Wadler, and J. Yallop. http://groups.inf.ed.ac.uk/links

## equations

operations fail:0 choose:2

 $\begin{array}{l} {\rm choose}\,({\rm choose}\,M\,N)\,P={\rm choose}\,M\,({\rm choose}\,N\,P)\\ {\rm choose}\,M\,N={\rm choose}\,N\,M\\ {\rm choose}\,M\,M=M\\ {\rm choose}\,fail\,M=M={\rm choose}\,M\,fail \end{array}$ 

## algebraicity

 $do x \leftarrow (choose MN) in P = choose (do x \leftarrow M in P) (do x \leftarrow N in P)$ 

## equations

operations fail:0 choose:2

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## nondeterministic laws

 $choose (do x \leftarrow M in N) (do x \leftarrow M in P) = do x \leftarrow M in (choose NP)$  $do x \leftarrow M in (do y \leftarrow N in P) = do y \leftarrow N in (do x \leftarrow M in P)$ 

Dropping equations due to handlers weakens the results of the logic

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# operations fail:0 choose:2

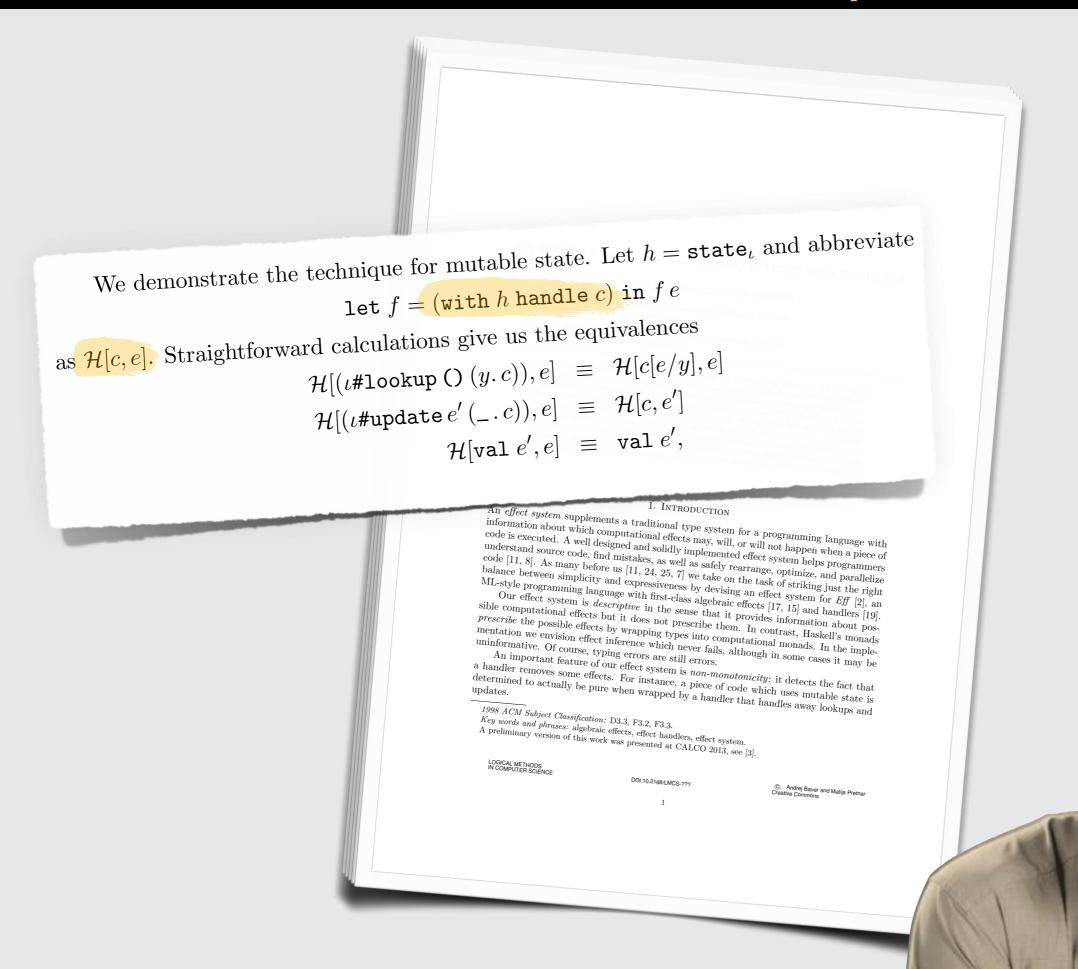
## algebraicity

 $do x \leftarrow (choose MN) in P = choose (do x \leftarrow M in P) (do x \leftarrow N in P)$ 

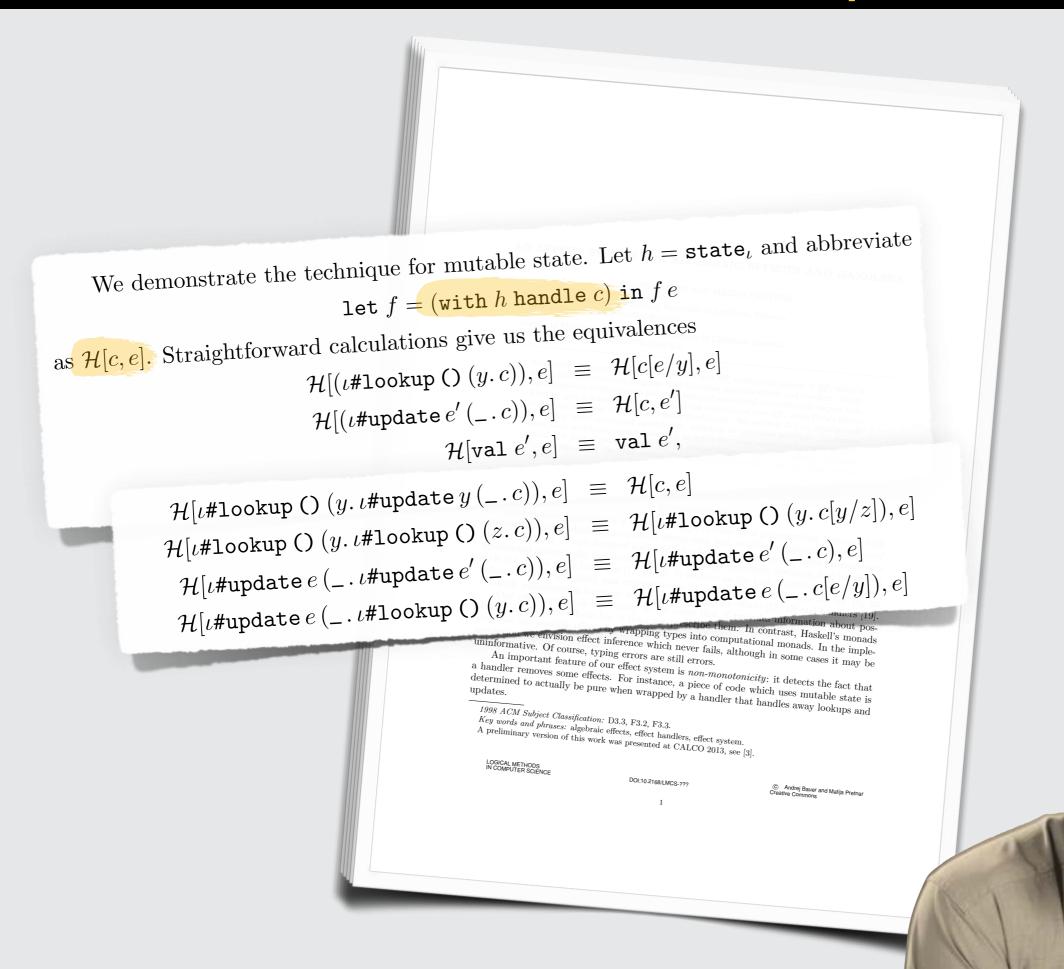
#### Certain laws can be reconstructed under a particular handler



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#### Certain laws can be reconstructed **under a particular handler**



 $\begin{aligned} \mathscr{H}_{\max}[M] &= \operatorname{with} H_{\max} \operatorname{handle} M \\ \mathscr{H}_{\max} \Big[ \operatorname{choose} \left( \operatorname{do} x \leftarrow M \operatorname{in} N \right) \left( \operatorname{do} x \leftarrow M \operatorname{in} P \right) \Big] &= \mathscr{H}_{\max} \Big[ \operatorname{do} x \leftarrow M \operatorname{in} \left( \operatorname{choose} NP \right) \Big] \\ \mathscr{H}_{\max} \Big[ \operatorname{do} x \leftarrow M \operatorname{in} \left( \operatorname{do} y \leftarrow N \operatorname{in} P \right) \Big] &= \mathscr{H}_{\max} \Big[ \operatorname{do} y \leftarrow N \operatorname{in} \left( \operatorname{do} x \leftarrow M \operatorname{in} P \right) \Big] \end{aligned}$ 

$$\begin{split} \mathscr{H}_{\max}[M] &= \texttt{with}\, H_{\max}\,\texttt{handle}\, M\\ \mathscr{H}_{\max}\big[\texttt{choose}\,(\texttt{do}\,x \Leftarrow M\,\texttt{in}\,N)\,(\texttt{do}\,x \Leftarrow M\,\texttt{in}\,P)\big] &= \mathscr{H}_{\max}\big[\texttt{do}\,x \Leftarrow M\,\texttt{in}\,(\texttt{choose}\,N\,P)\big]\\ \mathscr{H}_{\max}\big[\texttt{do}\,x \Leftarrow M\,\texttt{in}\,(\texttt{do}\,y \Leftarrow N\,\texttt{in}\,P)\big] &= \mathscr{H}_{\max}\big[\texttt{do}\,y \Leftarrow N\,\texttt{in}\,(\texttt{do}\,x \Leftarrow M\,\texttt{in}\,P)\big] \end{split}$$

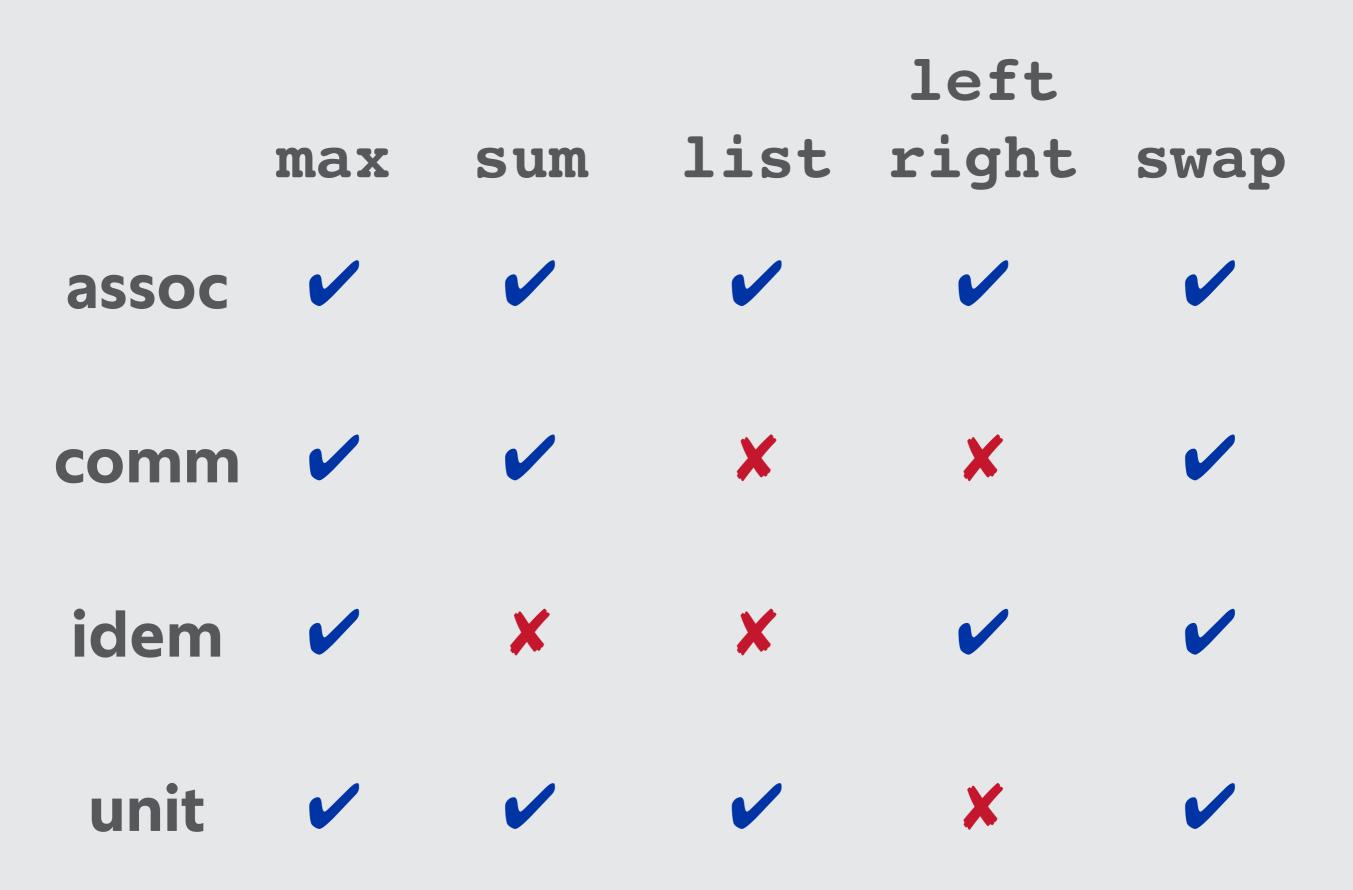
$$\begin{split} \mathscr{H}_{\mathrm{sum}}[M] &= \mathrm{with}\, H_{\mathrm{sum}}\,\mathrm{handle}\, M\\ \mathscr{H}_{\mathrm{sum}}\big[\mathrm{choose}\,(\mathrm{do}\,x \Leftarrow M\,\mathrm{in}\,N)\,(\mathrm{do}\,x \Leftarrow M\,\mathrm{in}\,P)\big] &= \mathscr{H}_{\mathrm{sum}}\big[\mathrm{do}\,x \Leftarrow M\,\mathrm{in}\,(\mathrm{choose}\,N\,P)\big]\\ \mathscr{H}_{\mathrm{sum}}\big[\mathrm{do}\,x \leftarrow M\,\mathrm{in}\,(\mathrm{do}\,y \Leftarrow N\,\mathrm{in}\,P)\big] &= \mathscr{H}_{\mathrm{sum}}\big[\mathrm{do}\,y \leftarrow N\,\mathrm{in}\,(\mathrm{do}\,x \Leftarrow M\,\mathrm{in}\,P)\big] \end{split}$$

$$\begin{split} \mathscr{H}_{\max}[M] &= \texttt{with}\, H_{\max}\,\texttt{handle}\, M\\ \mathscr{H}_{\max}\big[\texttt{choose}\,(\texttt{do}\,x \Leftarrow M\,\texttt{in}\,N)\,(\texttt{do}\,x \Leftarrow M\,\texttt{in}\,P)\big] &= \mathscr{H}_{\max}\big[\texttt{do}\,x \Leftarrow M\,\texttt{in}\,(\texttt{choose}\,N\,P)\big]\\ \mathscr{H}_{\max}\big[\texttt{do}\,x \Leftarrow M\,\texttt{in}\,(\texttt{do}\,y \Leftarrow N\,\texttt{in}\,P)\big] &= \mathscr{H}_{\max}\big[\texttt{do}\,y \Leftarrow N\,\texttt{in}\,(\texttt{do}\,x \Leftarrow M\,\texttt{in}\,P)\big] \end{split}$$

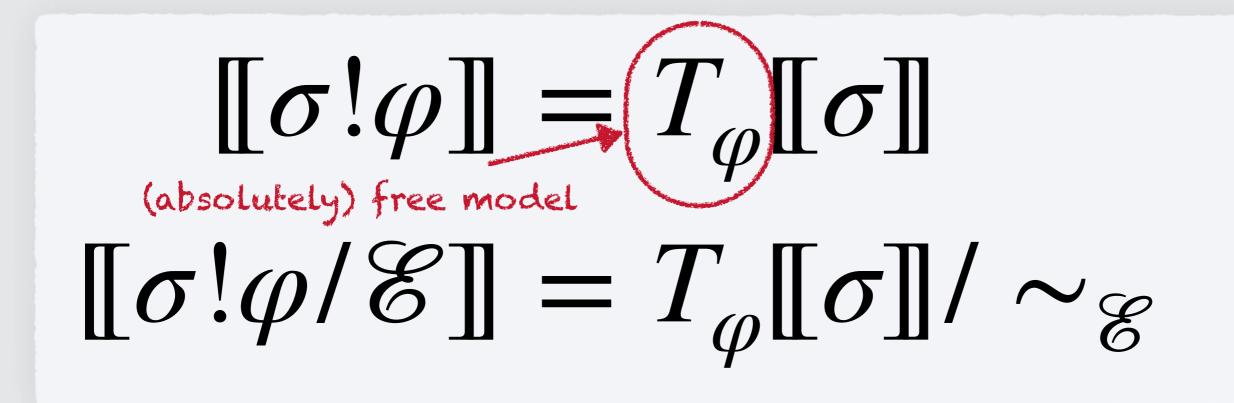
$$\begin{split} \mathscr{H}_{\mathrm{sum}}[M] &= \mathtt{with}\, H_{\mathrm{sum}}\, \mathtt{handle}\, M \\ \mathscr{H}_{\mathrm{sum}}\big[\mathtt{choose}\,(\mathtt{do}\, x \Leftarrow M\, \mathtt{in}\, N)\,(\mathtt{do}\, x \Leftarrow M\, \mathtt{in}\, P)\big] &= \mathscr{H}_{\mathrm{sum}}\big[\mathtt{do}\, x \Leftarrow M\, \mathtt{in}\,(\mathtt{choose}\, N\, P)\big] \\ \mathscr{H}_{\mathrm{sum}}\big[\mathtt{do}\, x \Leftarrow M\, \mathtt{in}\,(\mathtt{do}\, y \Leftarrow N\, \mathtt{in}\, P)\big] &= \mathscr{H}_{\mathrm{sum}}\big[\mathtt{do}\, y \Leftarrow N\, \mathtt{in}\,(\mathtt{do}\, x \Leftarrow M\, \mathtt{in}\, P)\big] \end{split}$$

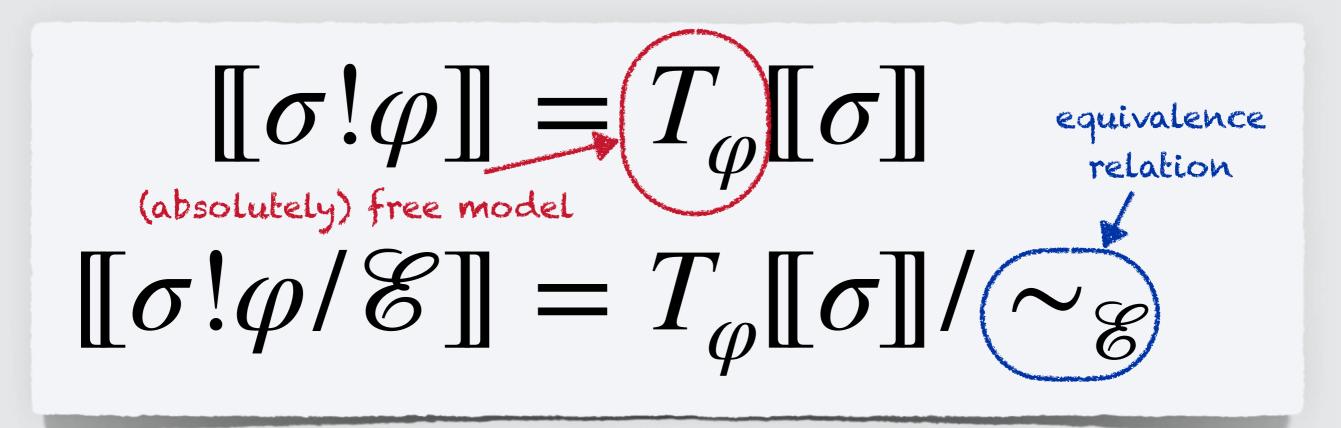
$$\begin{split} \mathscr{H}_{\mathrm{list}}[M] &= \mathtt{with}\, H_{\mathrm{list}}\, \mathtt{handle}\, M \\ \mathscr{H}_{\mathrm{list}}\big[\mathtt{choose}\,(\mathtt{do}\,x \Leftarrow M\, \mathtt{in}\, N)\,(\mathtt{do}\,x \Leftarrow M\, \mathtt{in}\, P)\big] &= \mathscr{H}_{\mathrm{list}}\big[\mathtt{do}\,x \Leftarrow M\, \mathtt{in}\,(\mathtt{choose}\, N\, P)\big] \\ \mathscr{H}_{\mathrm{list}}\big[\mathtt{do}\,x \twoheadleftarrow M\, \mathtt{in}\,(\mathtt{do}\,y \twoheadleftarrow N\, \mathtt{in}\, P)\big] &\neq \mathscr{H}_{\mathrm{list}}\big[\mathtt{do}\,y \twoheadleftarrow N\, \mathtt{in}\,(\mathtt{do}\,x \twoheadleftarrow M\, \mathtt{in}\, P)\big] \end{split}$$

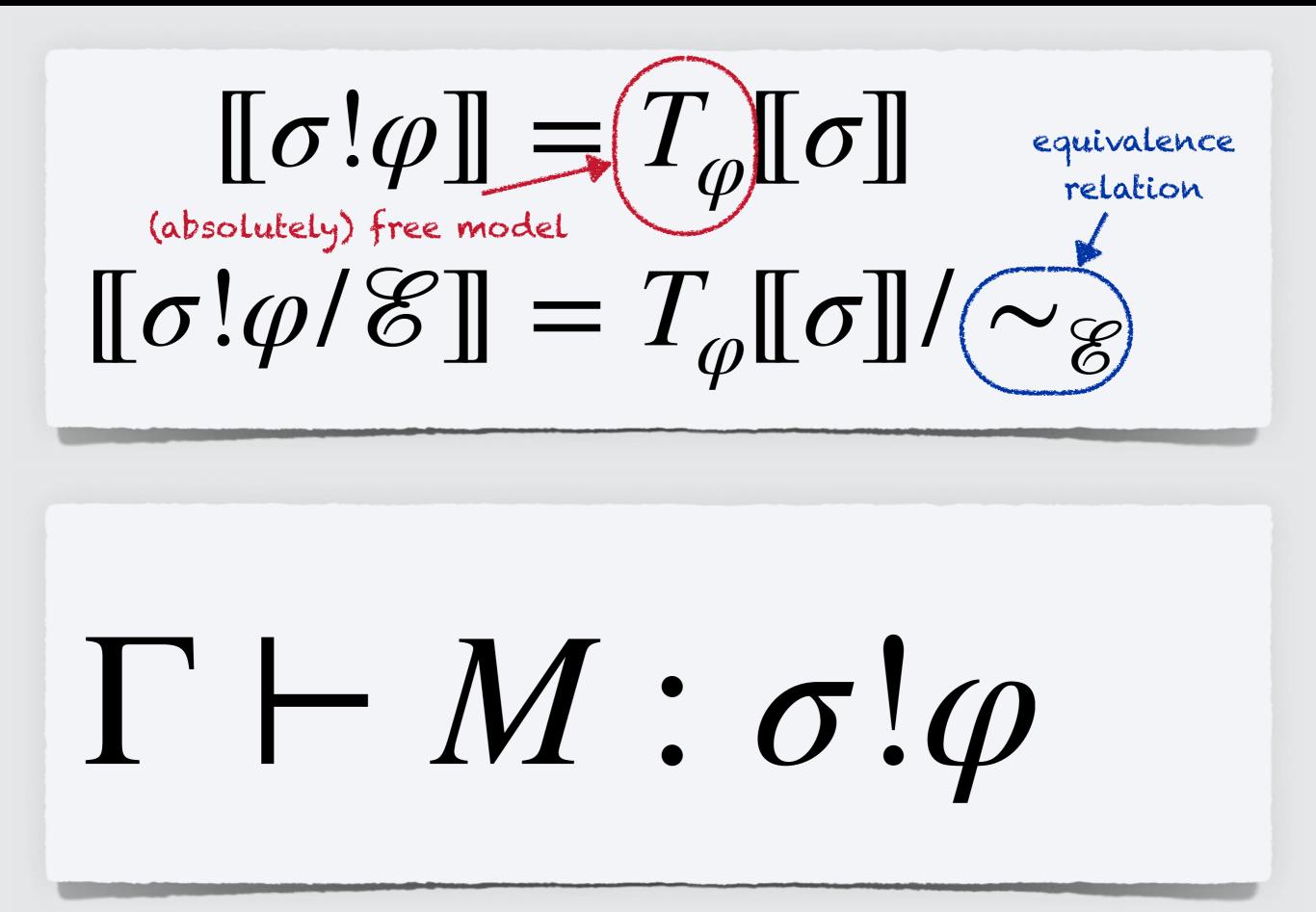
Different handlers satisfy varying equations

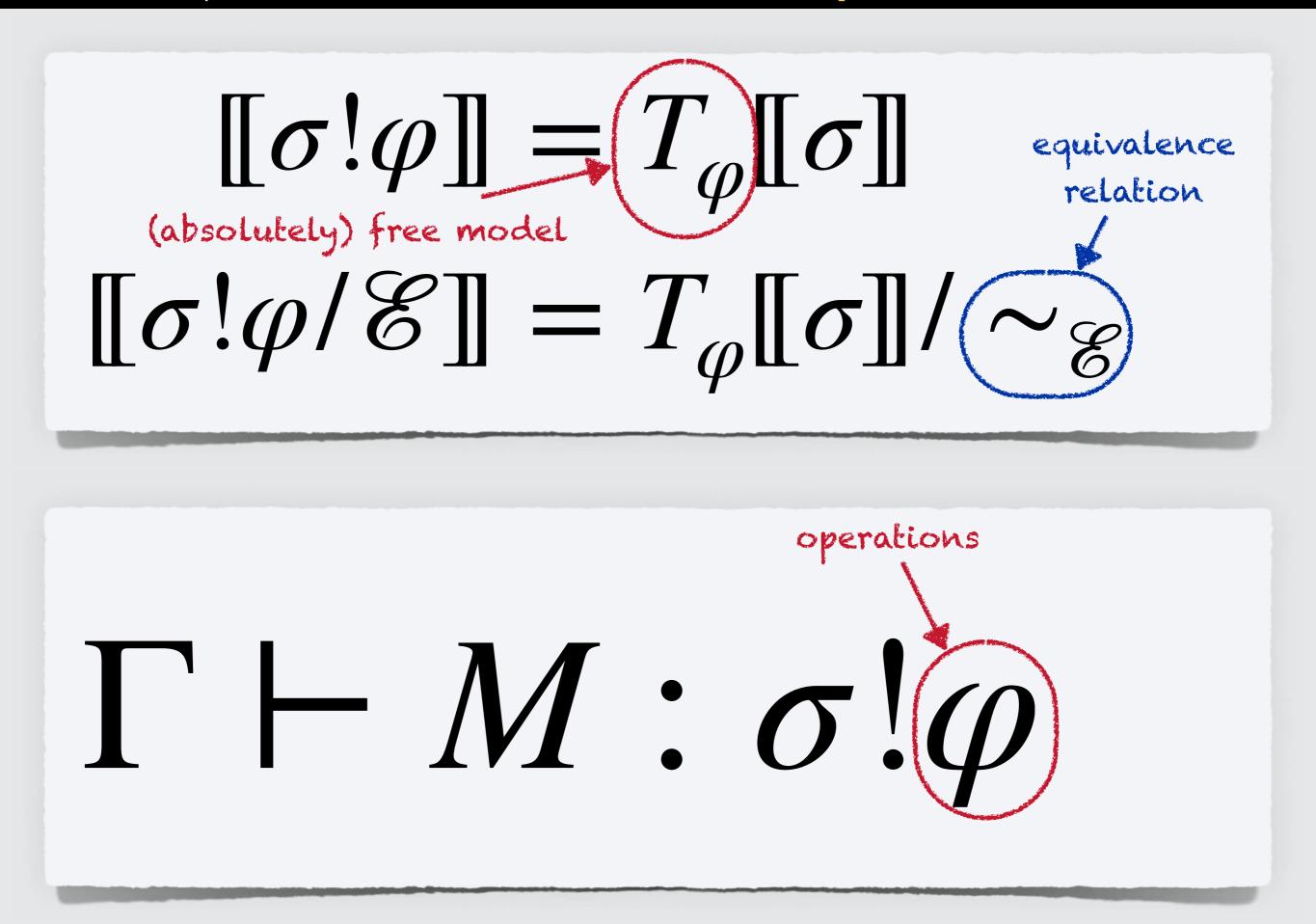


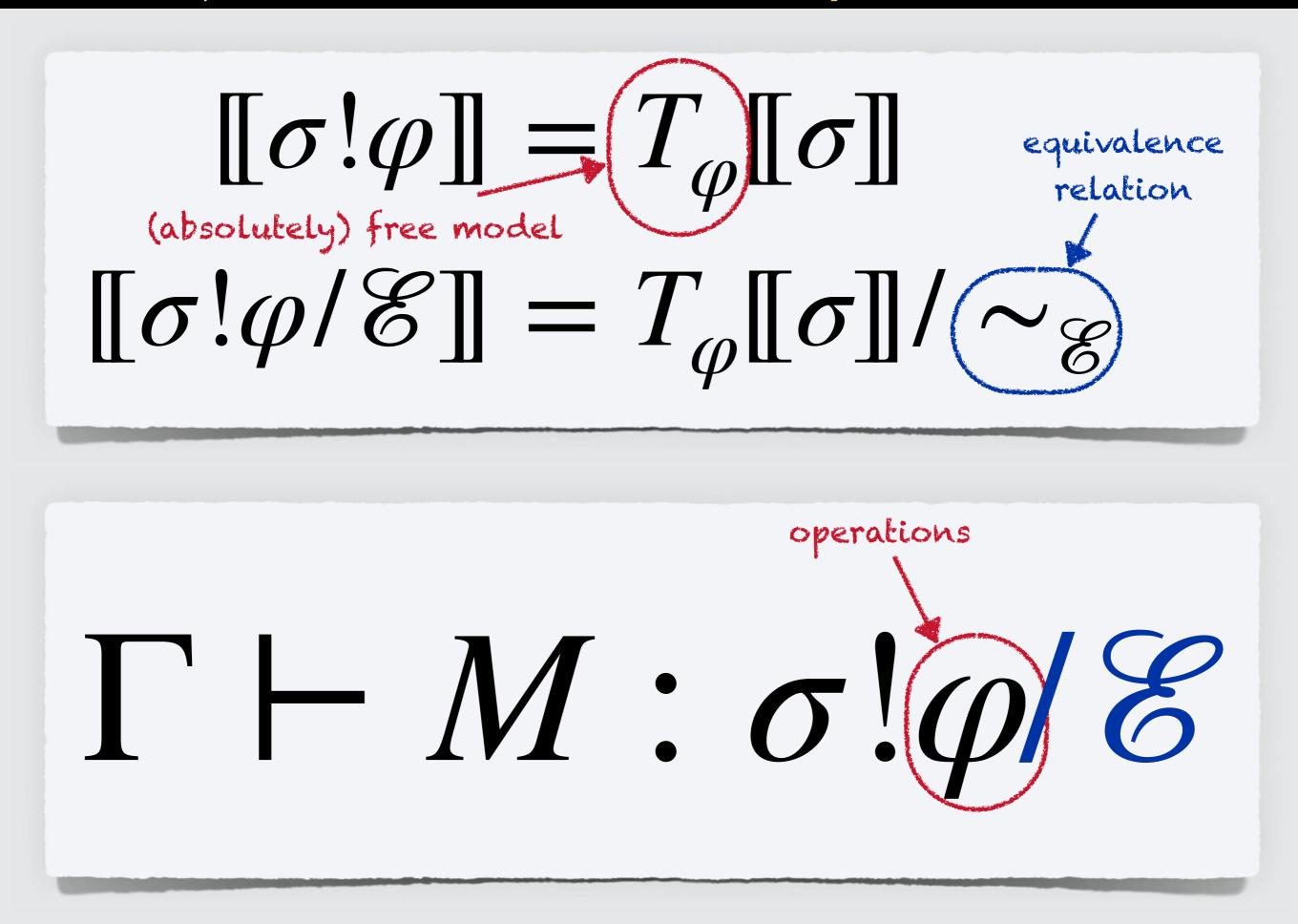
# $\llbracket \sigma! \varphi \rrbracket = T_{\varphi} \llbracket \sigma \rrbracket$ $\llbracket \sigma! \varphi \mathscr{E} \rrbracket = T_{\varphi} \llbracket \sigma \rrbracket / \sim_{\mathscr{E}}$

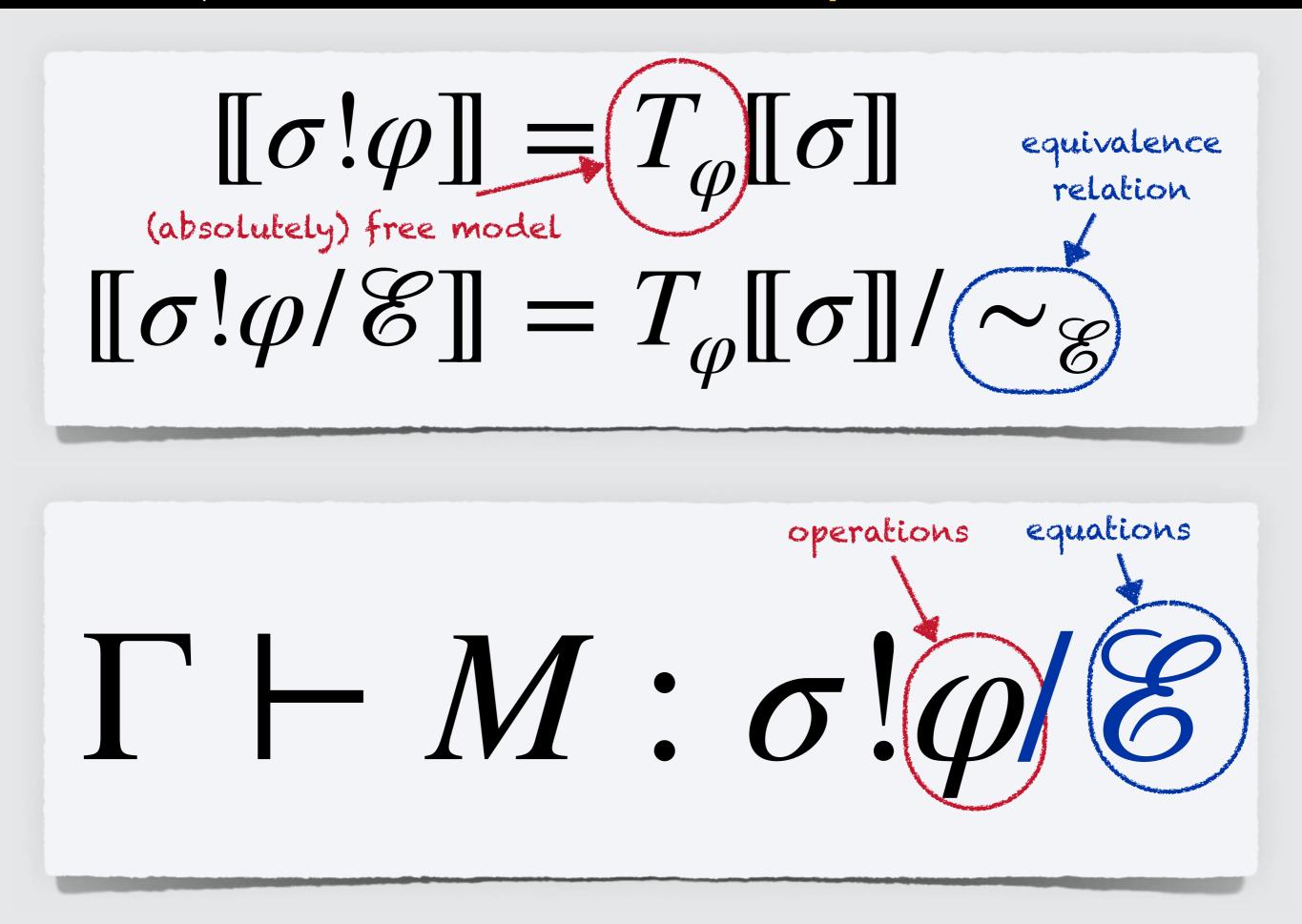












#### Previous reasoning can be factored into two parts

#### handlers respect equations

 $H_{\max}$ : int!{choose, fail}/{assoc, comm, idem, unit}  $\Rightarrow$  int! $\emptyset/\emptyset$ 

 $H_{\text{sum}}: \text{int!}\{\text{choose, fail}\} / \mathscr{E} \Rightarrow \text{int!} \emptyset / \emptyset$ 

 $H_{\text{list}}: \text{int!} \{\text{choose, fail}\} / \{\text{assoc, unit}\} \Rightarrow \text{intlist!} \emptyset / \emptyset$ 

 $H_{\text{left}}: \tau!\{\text{choose, fail}\}/\{\text{assoc, idem, unit}\} \Rightarrow \tau!\{\text{fail}\}/\emptyset$ 

 $H_{\text{swap}}: \tau!\{\text{choose, fail}\}/\{\text{assoc, unit}\} \Rightarrow \tau!\{\text{choose, fail}\}/\{\text{assoc, unit}\}$ 

E

 $H_{\text{swap}}: \tau!\{\text{choose, fail}\}/\mathscr{E} \Rightarrow \tau!\{\text{choose, fail}\}/\mathscr{E}$ 

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E

 $H_{\text{swap}}: \tau!\{\text{choose, fail}\} \not > \tau!\{\text{choose, fail}\} \not > \cdots$ 

#### equations imply properties

 $choose (do x \leftarrow M in N) (do x \leftarrow M in P) = \mathcal{B} do x \leftarrow M in (choose NP)$  $do x \leftarrow M in (do y \leftarrow N in P) = \mathcal{B} do y \leftarrow N in (do x \leftarrow M in P)$ 

#### Typing rules for **monadic constructs**

 $\Gamma \vdash V : \sigma$  $\Gamma \vdash \operatorname{val} V : \sigma! \varphi / \mathscr{E}$ 

 $\Gamma \vdash M : \sigma! \varphi / \mathscr{E} \qquad \Gamma, x : \sigma \vdash N : \tau! \varphi / \mathscr{E}$  $\Gamma \vdash \operatorname{do} x \Leftarrow M \operatorname{in} P : \tau! \varphi / \mathscr{E}$  $\Gamma \vdash V : \sigma \qquad (F : \sigma \twoheadrightarrow \tau) \in \varphi$  $\Gamma \vdash \operatorname{perform} FV : \tau! \varphi / \mathscr{E}$ 

#### Handling and subsumption typing rules

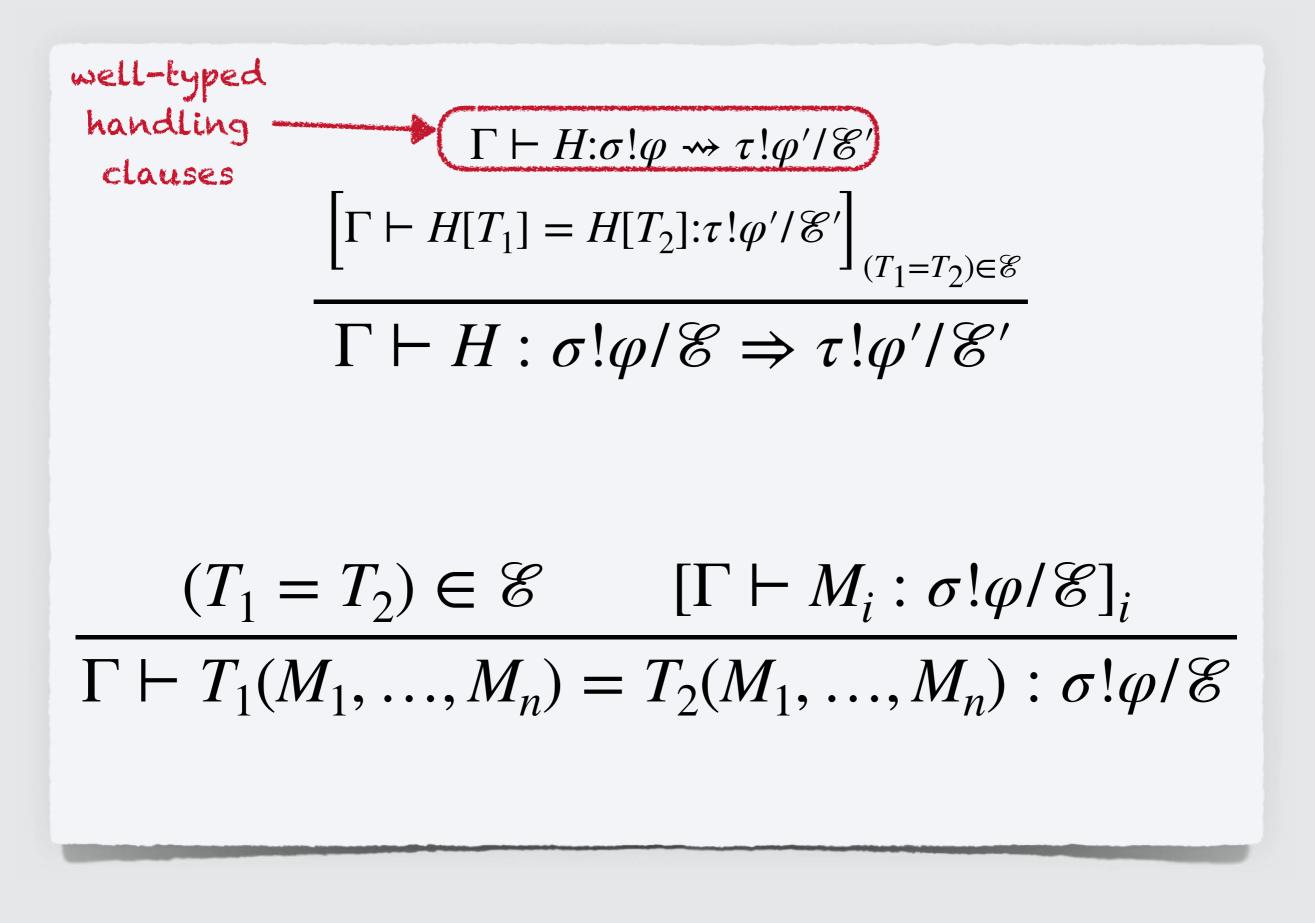
 $\Gamma \vdash H : \sigma! \varphi / \mathscr{E} \Rightarrow \tau! \varphi' / \mathscr{E}' \qquad \Gamma \vdash M : \sigma! \varphi / \mathscr{E}$  $\Gamma \vdash \text{with} H \text{handle} M : \tau! \varphi' / \mathscr{E}'$  $\sigma <: \sigma' \quad \varphi \subseteq \varphi' \quad \mathscr{E}' \vDash \mathscr{E}$  $\Gamma \vdash M : \sigma! \varphi / \mathscr{E}$  $\Gamma \vdash M : \sigma' ! \varphi' / \mathscr{E}'$ 

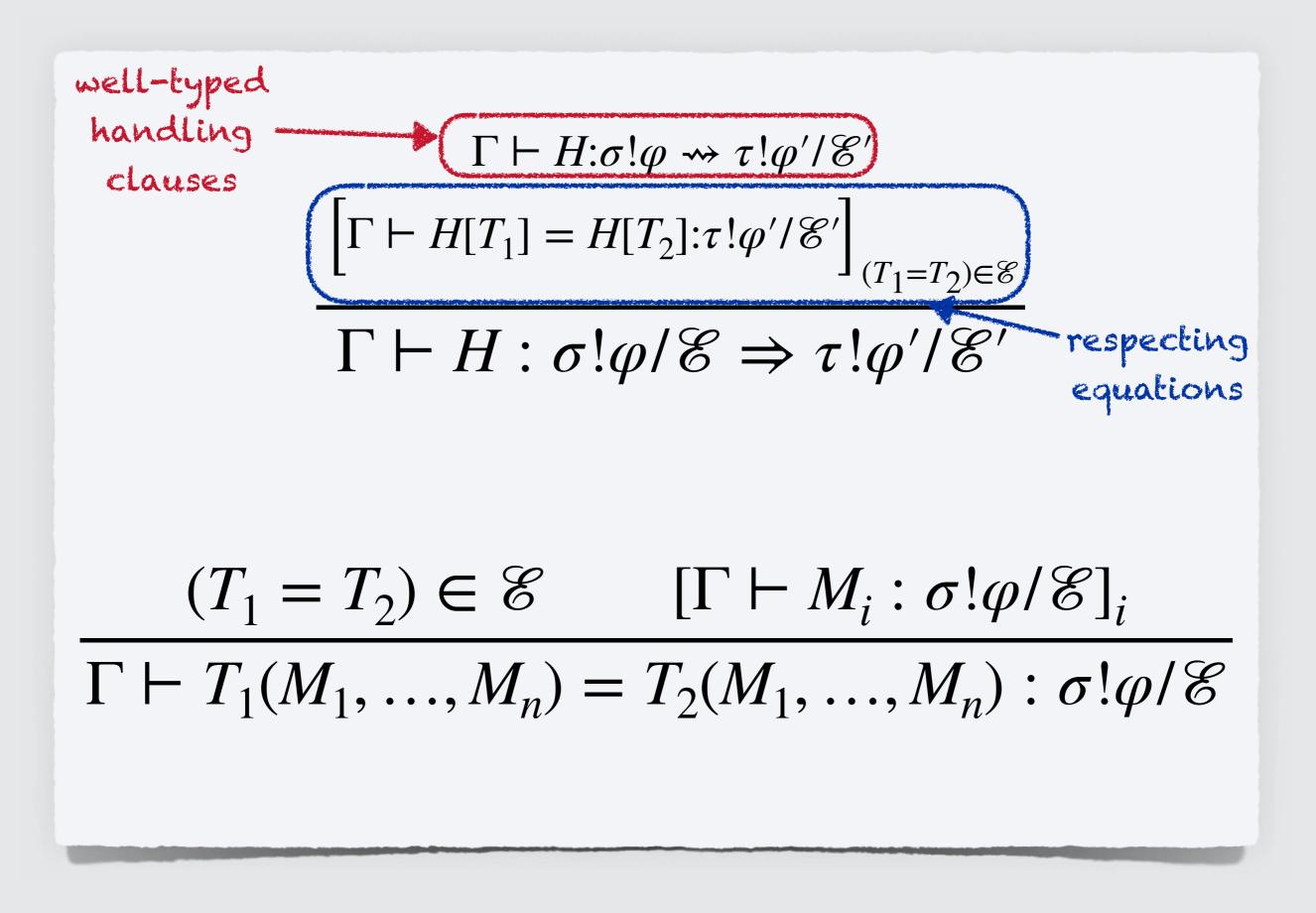
#### Handling and subsumption typing rules

 $\Gamma \vdash H : \sigma! \varphi / \mathscr{E} \Rightarrow \tau! \varphi' / \mathscr{E}' \qquad \Gamma \vdash M : \sigma! \varphi / \mathscr{E}$  $\Gamma \vdash \text{with} H \text{handle} M : \tau! \varphi' / \mathscr{E}'$  $\sigma <: \sigma' \quad \varphi \subseteq \varphi' \quad \mathscr{E}' \models \mathscr{E}$  $\Gamma \vdash M : \sigma! \varphi / \mathscr{E}$  $\Gamma \vdash M : \sigma' ! \varphi' / \mathscr{E}'$ 

Handler typing rule and instantiation of theory equations

$$\begin{split} \Gamma \vdash H: \sigma ! \varphi \rightsquigarrow \tau ! \varphi' / \mathscr{E}' \\ & \frac{\left[ \Gamma \vdash H[T_1] = H[T_2]: \tau ! \varphi' / \mathscr{E}' \right]_{(T_1 = T_2) \in \mathscr{E}}}{\Gamma \vdash H: \sigma ! \varphi / \mathscr{E} \Rightarrow \tau ! \varphi' / \mathscr{E}'} \\ \\ & \frac{(T_1 = T_2) \in \mathscr{E} \qquad [\Gamma \vdash M_i: \sigma ! \varphi / \mathscr{E}]_i}{\Gamma \vdash T_1(M_1, \dots, M_n) = T_2(M_1, \dots, M_n): \sigma ! \varphi / \mathscr{E}} \end{split}$$





#### This work has only **partly** been **put into practice**

Under consideration for publication in J. Functional Programming

#### Local Algebraic Effect Theories

1

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#### Abstract

Algebraic effects are computational effects that can be described with a set of basic operations and equations between them. As many interesting effect handlers do not respect these equations, most approaches assume a trivial theory, sacrificing both reasoning power and safety. We present an alternative approach where the type system tracks equations that are observed

in subparts of the program, yielding a sound and flexible logic, and paving a way for practical optimizations and reasoning tools.

Algebraic effects are computational effects that can be described by a signature of primitive operations and a collection of equations between them (Plotkin & Power, 2001; Plotkin & Power, 2003), while algebraic effect handlers are a generalization of exception handlers to arbitrary algebraic effects (Plotkin & Pretnar, 2009; Plotkin & Pretnar, 2013). Even though the early work considered only handlers that respect equations of the effect theory, a considerable amount of useful handlers did not, and the restriction was dropped in most though not all (Ahman, 2018) — of the later work on handlers (Kammar et al., 2013; Bauer & Pretnar, 2015; Leijen, 2017; Biernacki et al., 2018), resulting in a weaker reasoning logic and imprecise specifications.

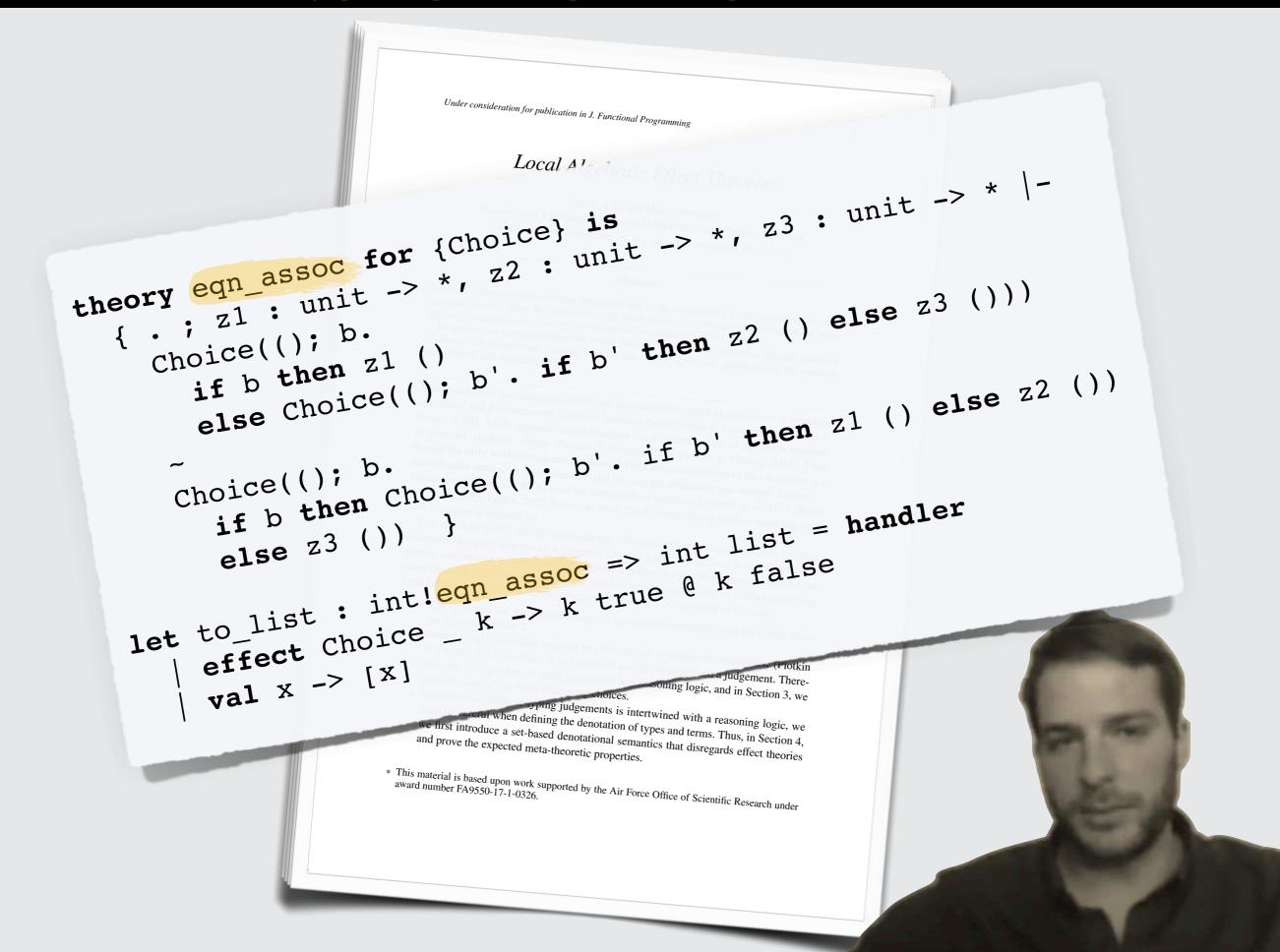
Our aim is to rectify this by reintroducing effect theories into the type system, tracking equations observed in parts of a program. On one hand, the induced logic allows us to

rewrite computations into equivalent ones with respect to the effect theory, while on the other hand, the type system enforces that handlers preserve equivalences, further specifying their behaviour. After an informal overview in Section 1, we proceed as follows:

• The syntax of the working language, its operational semantics, and the typing rules

- Determining if a handler respects an effect theory is in general undecidable (Plotkin
- & Pretnar, 2013), so there is no canonical way of defining such a judgement. There-
- fore, the typing rules are given parametric to a reasoning logic, and in Section 3, we
- Since the definition of typing judgements is intertwined with a reasoning logic, we
- must be careful when defining the denotation of types and terms. Thus, in Section 4, we first introduce a set-based denotational semantics that disregards effect theories and prove the expected meta-theoretic properties.
- \* This material is based upon work supported by the Air Force Office of Scientific Research under

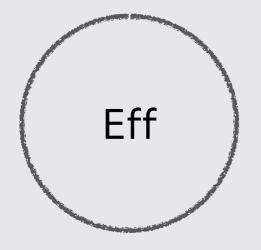
#### This work has only partly been put into practice







## The simplest way of efficiently executing Eff was through OCaml



efficient execution

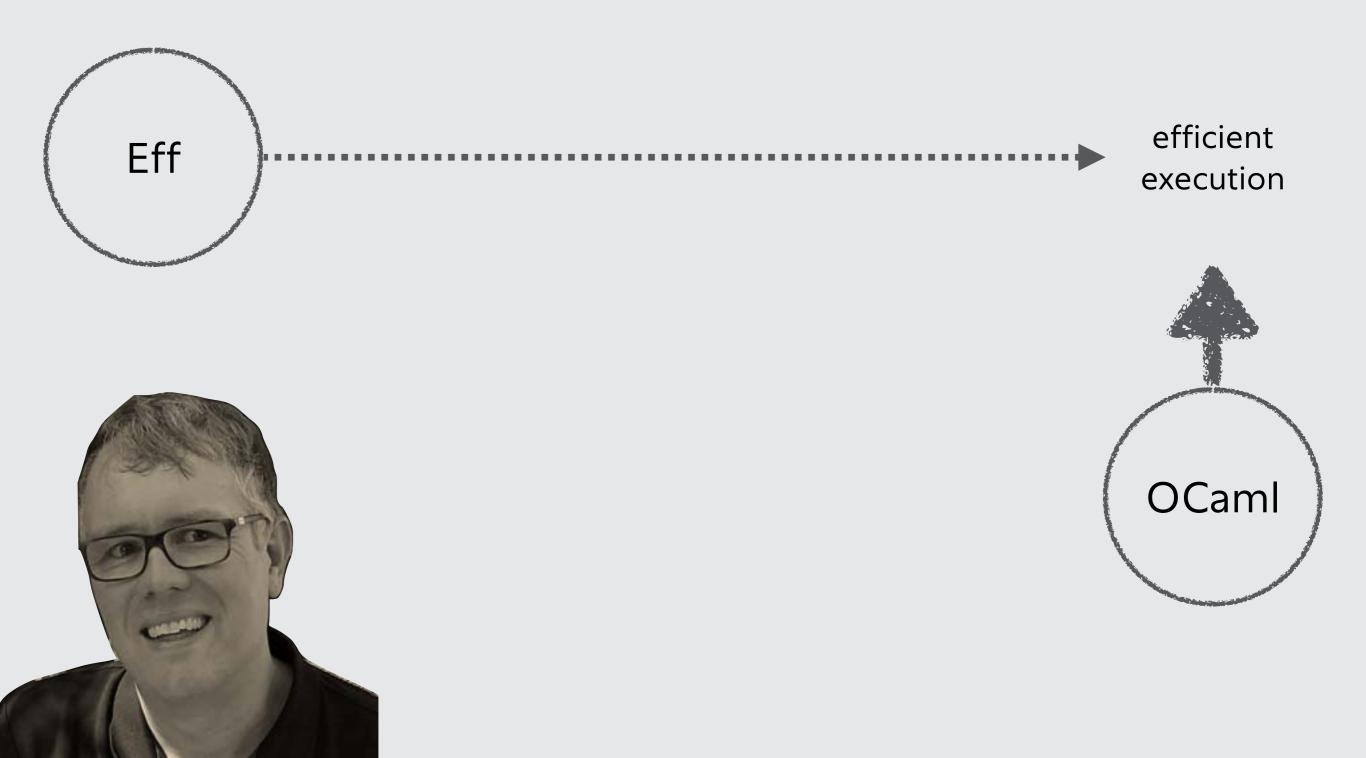


## The simplest way of efficiently executing Eff was through OCam

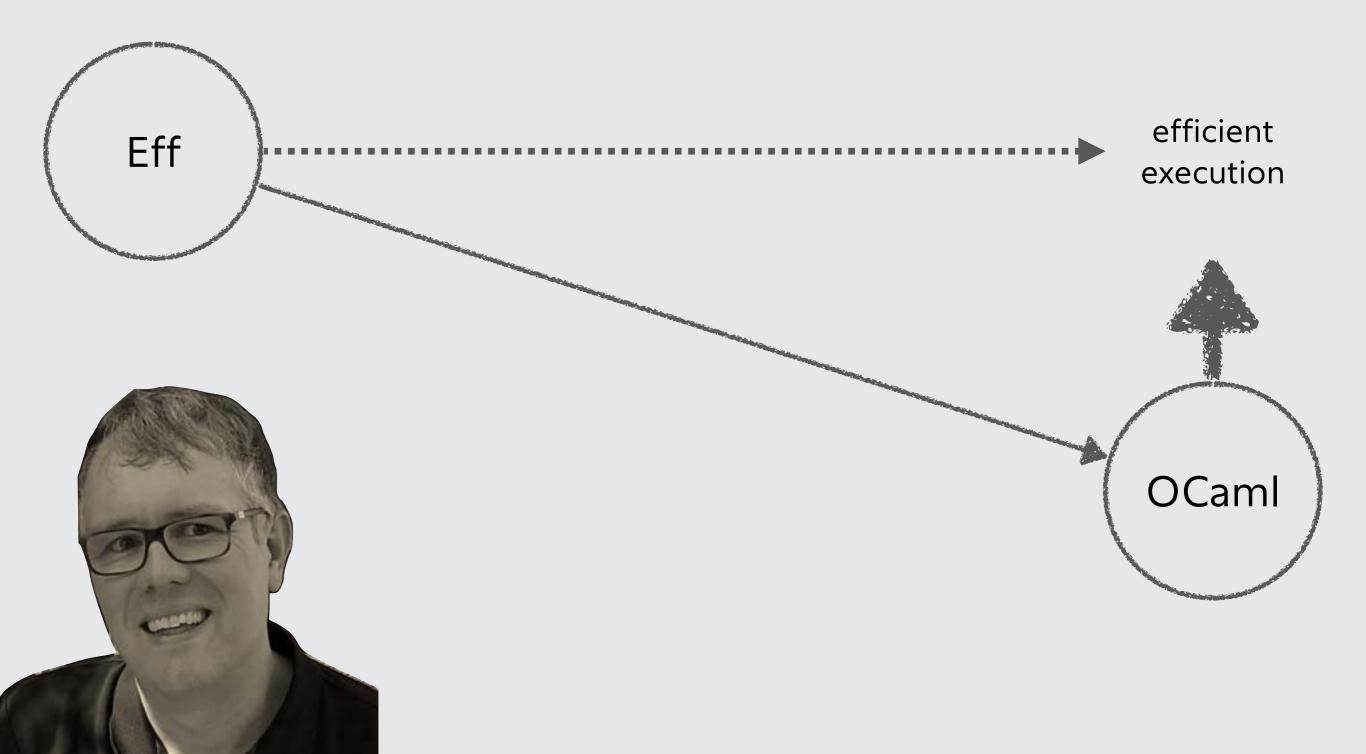




## The simplest way of efficiently executing Eff was through OCaml



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### free monad

type ('a, 'b) handler = { (\* handler clauses \*) }

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## operations

```
val return : 'a -> 'a comp
val (>>=) : 'a comp -> ('a -> 'b comp) -> 'b comp
val map : ('a -> 'b) -> 'a comp -> 'b comp
```

val get : unit -> int comp
val set : int -> unit comp

val handle : ('a, 'b) handler -> 'a comp -> 'b comp

### free monad

type ('a, 'b) handler = { (\* handler clauses \*) }

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### source Eff

let y = perform Get in
perform (Set (y + 1));
loop (n - 1)

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### desired OCaml

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let y = perform Get in
perform (Set (y + 1));
loop (n - 1)

# generated OCaml

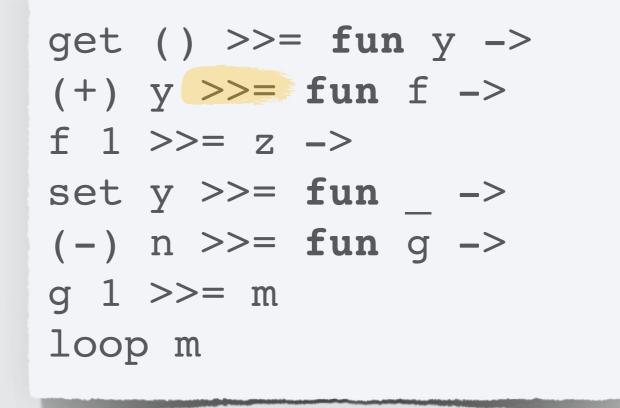
get () >>= fun y ->
(+) y >>= fun f ->
f 1 >>= z ->
set y >>= fun \_ ->
(-) n >>= fun g ->
g 1 >>= m
loop m

### desired OCaml

### source Eff

let y = perform Get in
perform (Set (y + 1));
loop (n - 1)

# generated OCaml



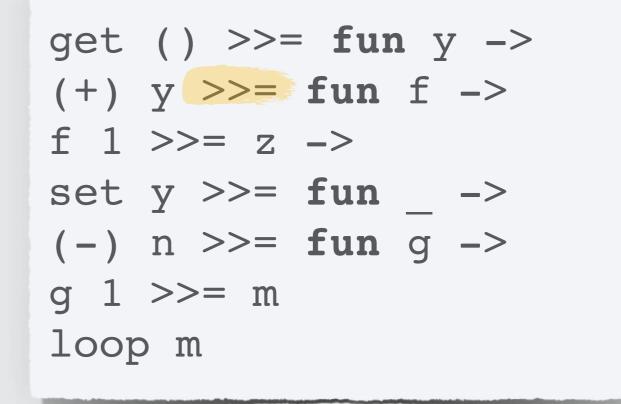
### desired OCaml

## source Eff

let y = perform Get in
perform (Set (y + 1));
loop (n - 1)

# purity-aware translation

# generated OCaml



# desired OCaml

source Eff generated OCaml get () >>= **fun** y -> let y = perform Get in (+) y >>= fun f ->perform (Set (y + 1)); 1(000(n-1))f 1 >>= z -> $\rightarrow \cdots \rightarrow = fun \rightarrow$  $\mathscr{C}(\sigma!\varphi) = \begin{cases} \mathscr{C}(\sigma) \\ \mathscr{C}(\sigma) \operatorname{comp} \end{cases}$  $\varphi = \emptyset$  $\varphi \neq \emptyset$ let I let z = f 1 in desirea - m set y >>= fun -> get () >>= **fun** y -> let g = (-) n inset (y+1) >>= **fun** -> let m = q 1 inloop (n - 1)loop m

# Second component was inlining handler definitions

### stateful function

```
let rec loop n =
  if n = 0 then () else
    let y = perform Get () in
    perform (Set (y + 1));
    loop (n - 1)
```

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```

### handler for state

```
let state_handler = handler
    | effect (Get ()) k -> (fun s -> k s s)
    | effect (Set s') k -> (fun _ -> k () s')
    | _-> (fun s -> s)
```

### Handlers get **pushed inside** other constructs

```
with state_handler handle
  if n = 0 then () else
    let y = perform Get () in
    perform (Set (y + 1));
    loop (n - 1)
```

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if n = 0 then
with state_handler handle ()
else
with state_handler handle
  let y = perform Get () in
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```

```
if n = 0 then (fun s -> s) else
  fun s -> with state_handler handle
      loop (n - 1)
      (s + 1)
```

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if n = 0 then
  with state_handler handle ()
else
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```
if n = 0 then (fun s -> s) else
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    loop (n - 1)
    (s + 1)
```

let rec loop' n =
 with state\_handler handle loop n

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let rec loop' n =
with state handler handle (\* ...loop body... \*)

```
let rec loop' n =
  with state_handler handle loop n
```

```
let rec loop' n =
with state handler handle (* ...loop body... *)
```

```
let rec loop' n s =
    if n = 0 then s else
    (with state_handler handle loop (n - 1))
        (s + 1)
```

```
let rec loop' n =
  with state_handler handle loop n
```

```
let rec loop' n =
with state_handler handle (* ...loop body... *)
```

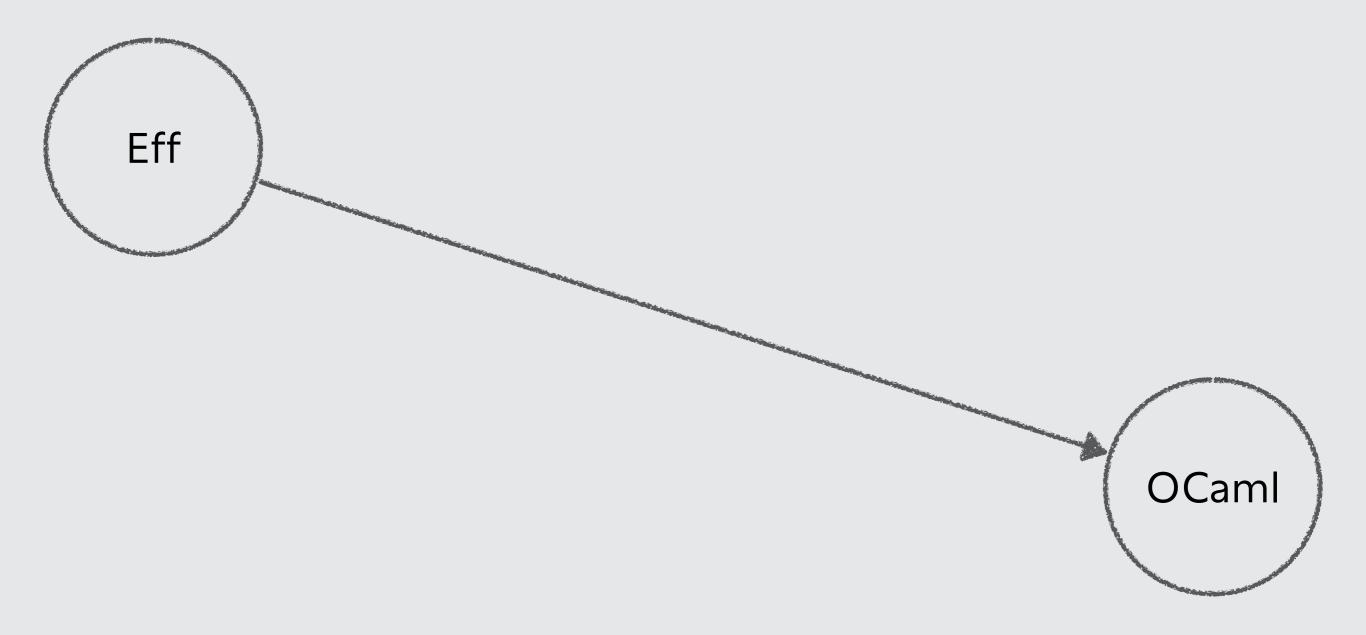
```
let rec loop' n s =
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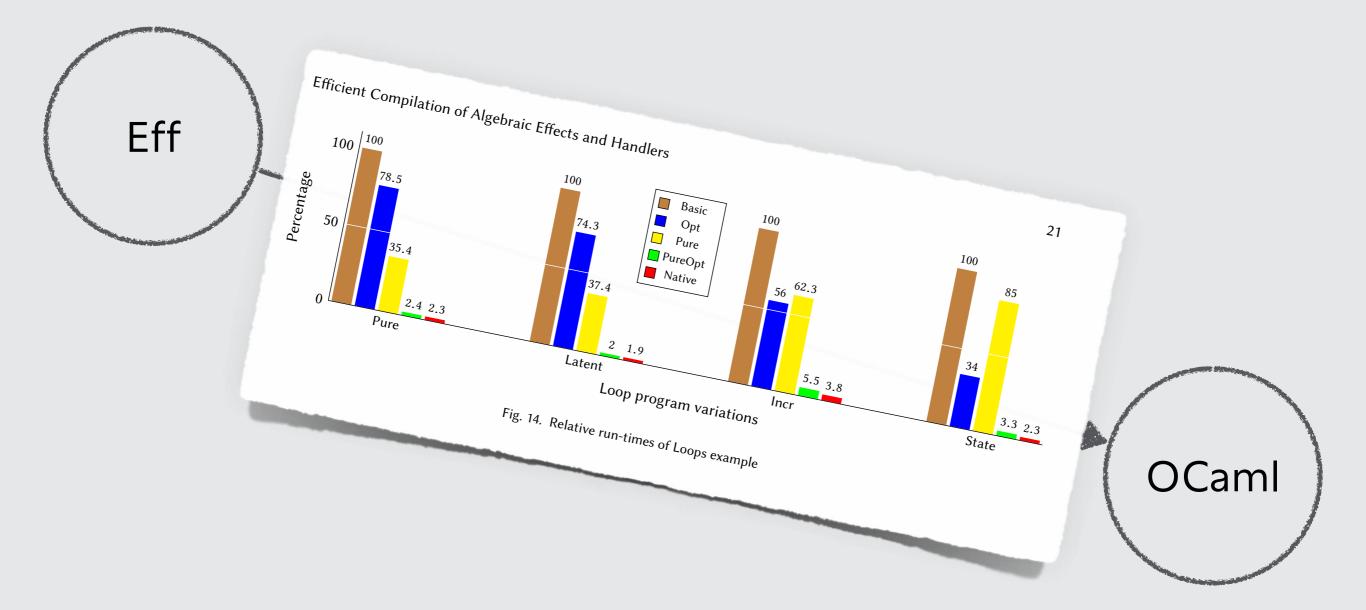
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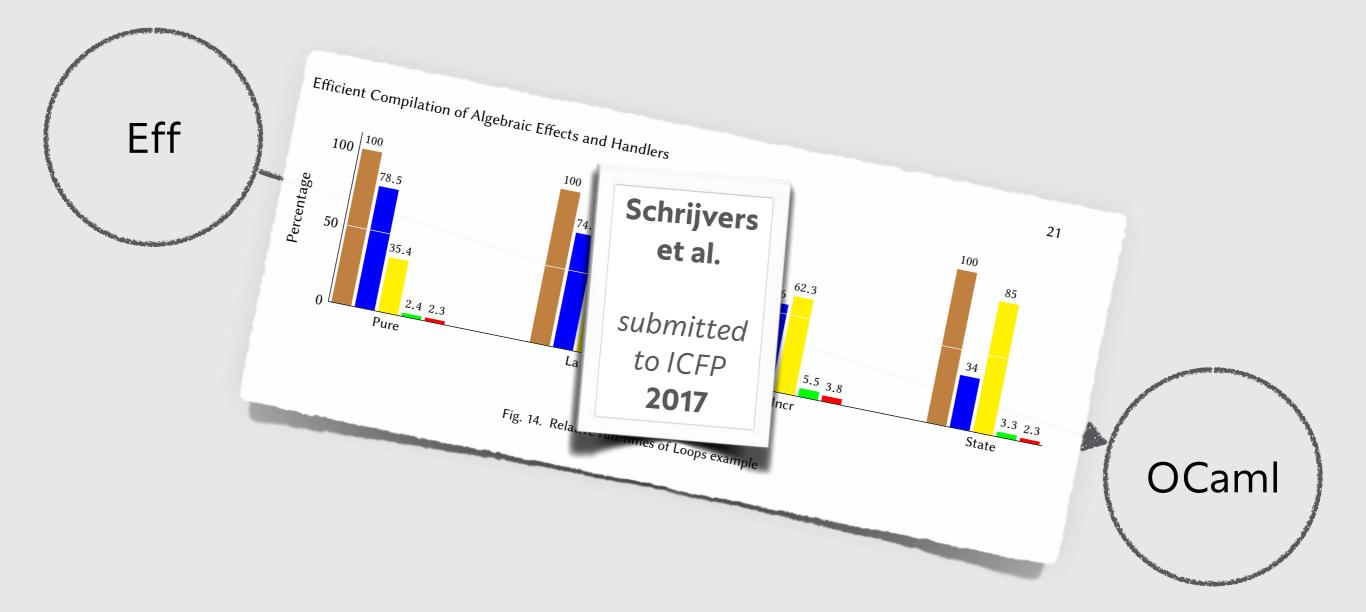
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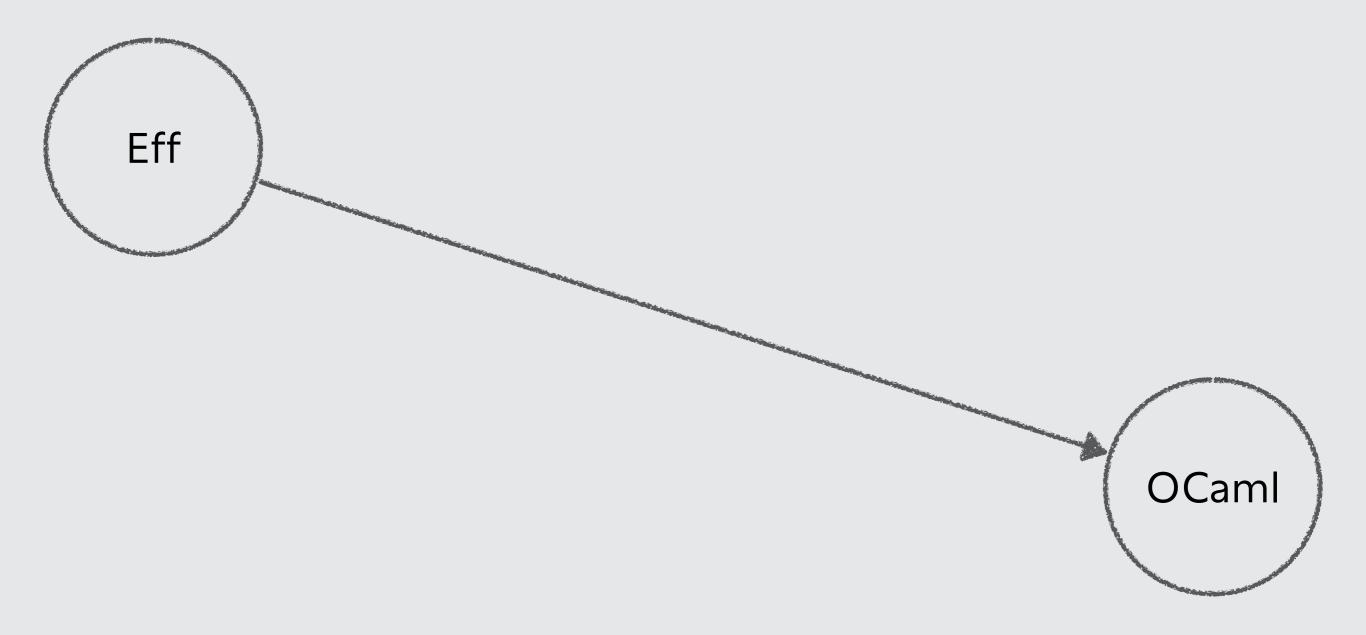
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let rec loop' n s =
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```

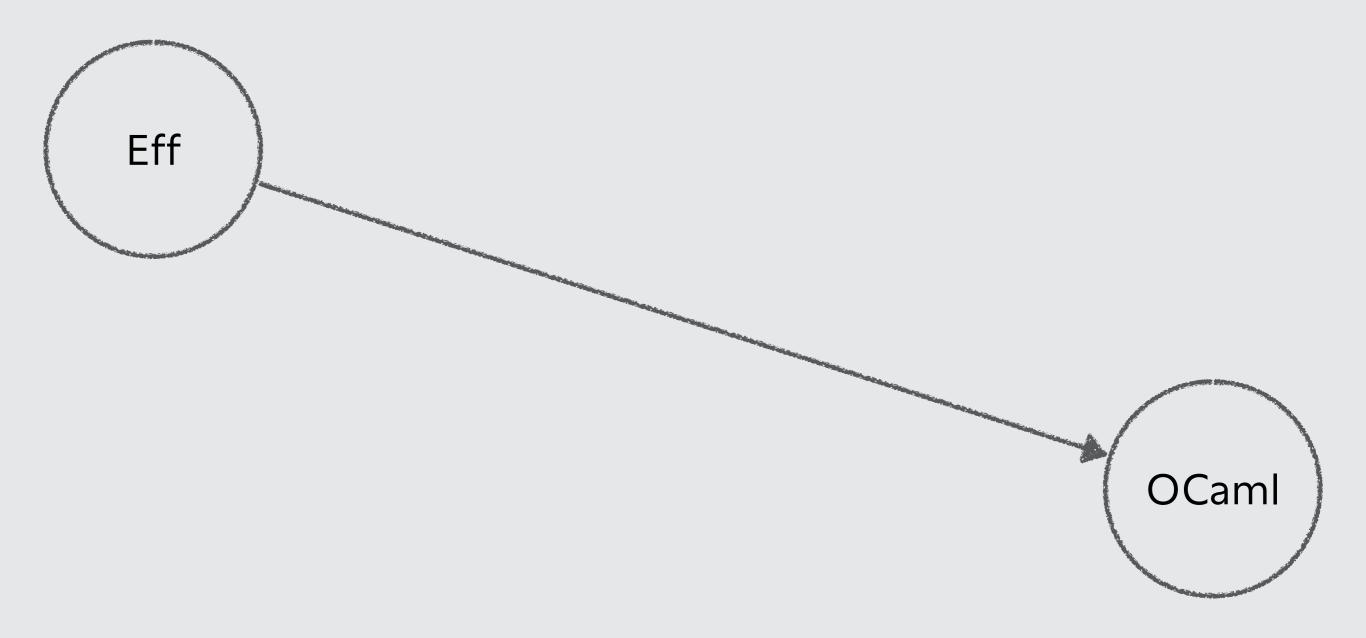








# One thing removed for simplicity were **effect instances**

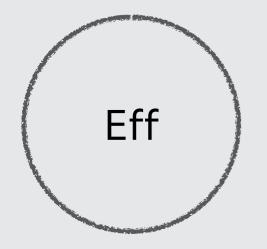


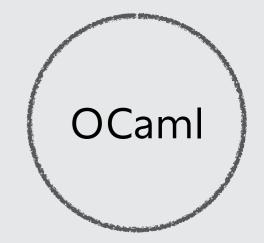
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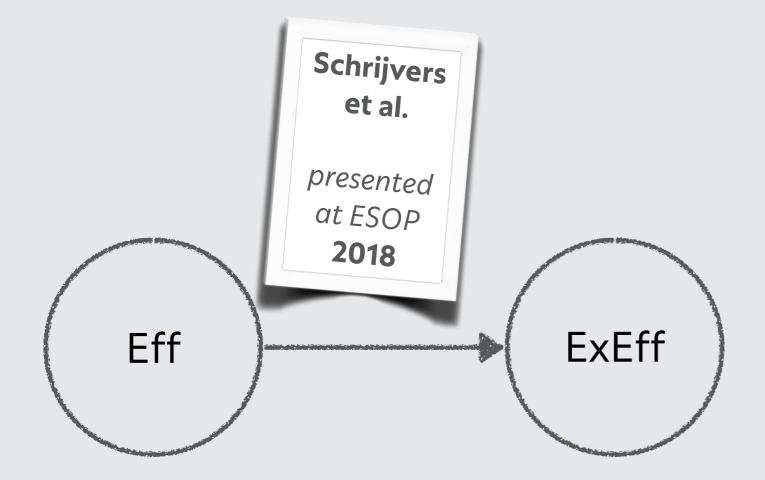
type 'a ref = effect **operation** get: unit -> 'a operation set: 'a -> unit Eff end let state r x = handler r#get () k -> (fun s -> k s s) r#set s' k -> (fun s -> k () s') **val** y -> (**fun** s -> (y, s)) finally f -> f x OCaml

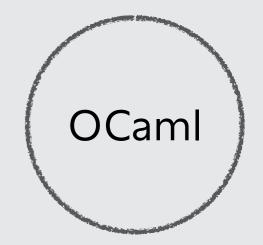
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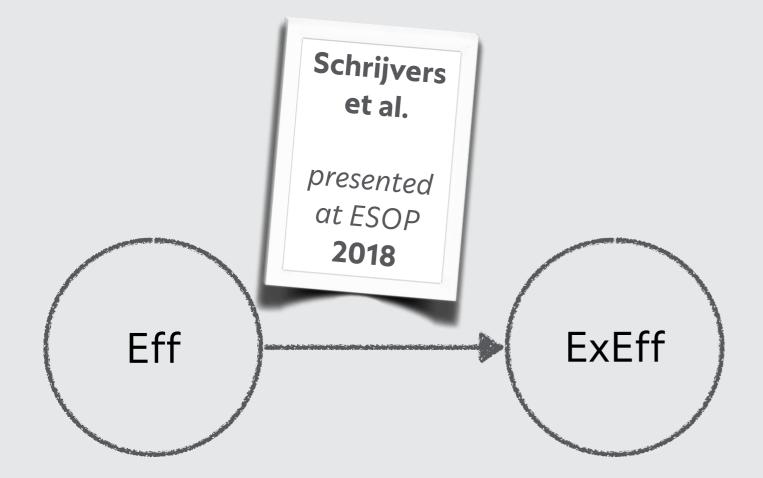
**operation** get: unit -> int **operation** set: int -> unit Eff let state r x = handler #get () k -> (fun s -> k s s) #set s' k -> (fun s -> k () s') **val** y -> (**fun** s -> (y, s)) finally f -> f x OCaml

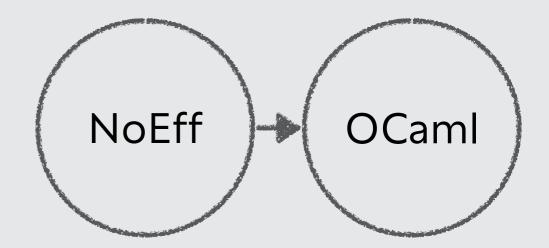


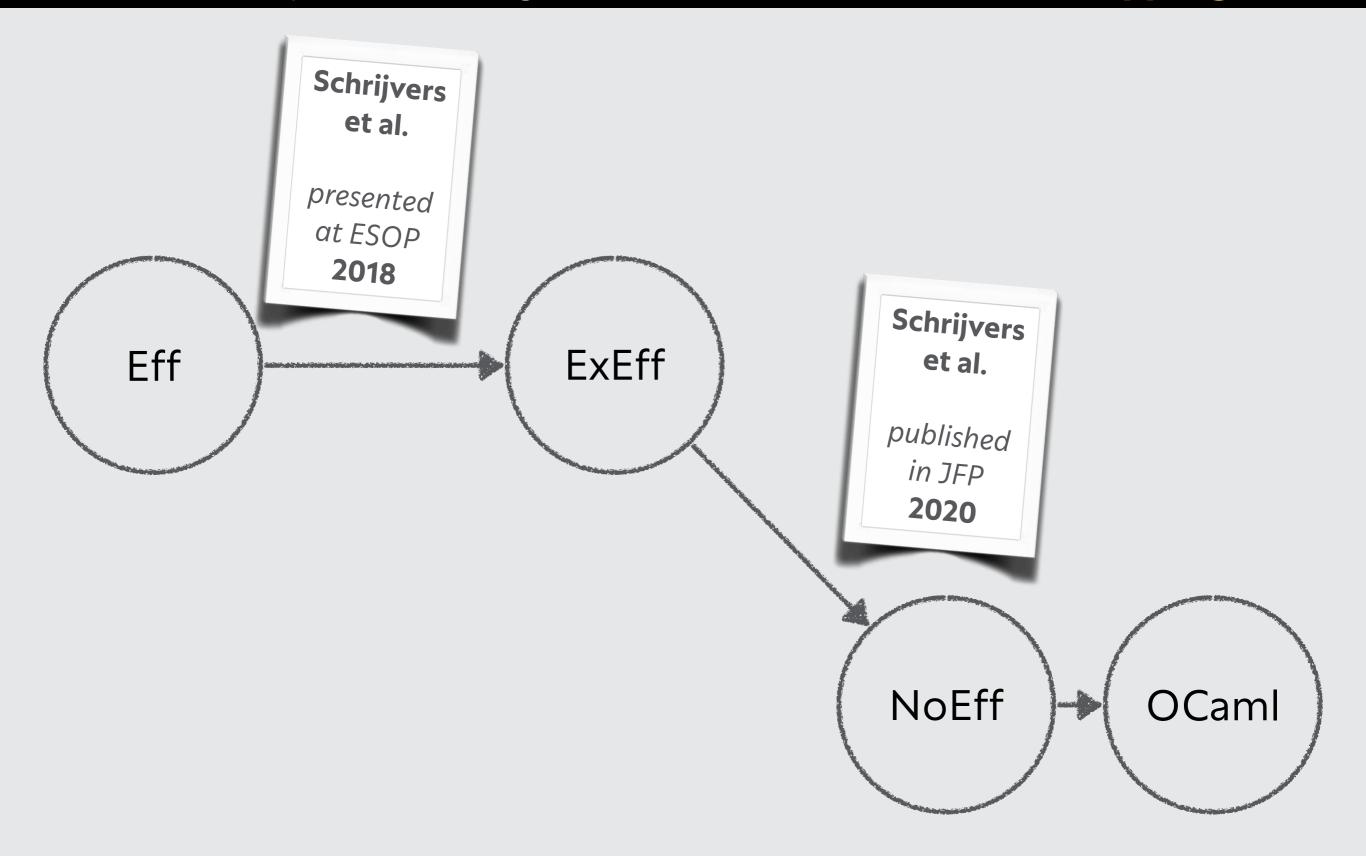


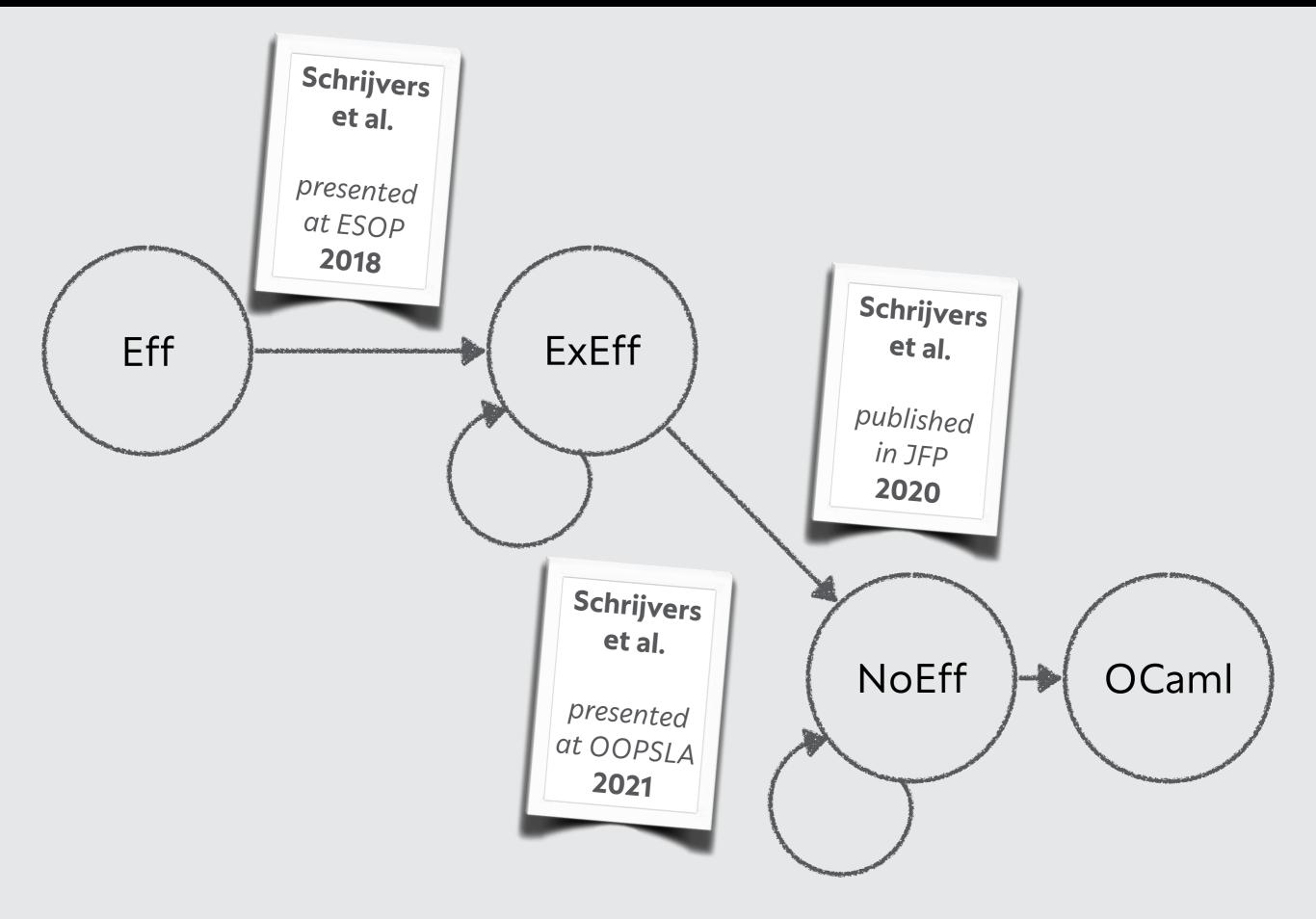












# The syntax of types and well-formedness rules for coercions

$$\begin{aligned}
\sigma ::= b \mid \alpha \mid \sigma \to \underline{\tau} \qquad \underline{\tau} ::= \sigma ! \varphi \\
\hline
coercions \\
\hline
\Xi \vdash \langle \sigma \rangle : (\sigma <: \sigma) \qquad \underline{\omega} : (\sigma <: \sigma') \in \Xi \\
\hline
\Xi \vdash \omega_{v} : (\sigma <: \sigma') \qquad \underline{\Xi \vdash \omega_{c} : (\underline{\tau} <: \underline{\tau}')} \\
\hline
\underline{\Xi \vdash \omega_{v} : (\sigma' <: \sigma) \qquad \underline{\Xi \vdash \omega_{c} : (\underline{\tau} <: \underline{\tau}')} \\
\hline
\Xi \vdash \omega_{v} \to \omega_{c} : ((\sigma \to \underline{\tau}) <: (\sigma \to \underline{\tau}')) \\
\hline
\underline{\Xi \vdash \omega_{v} : (\sigma <: \sigma') \qquad \underline{\Xi \vdash \omega} : (\varphi <: \varphi')} \\
\hline
\underline{\Xi \vdash \omega_{v} : (\omega : \sigma') \qquad \underline{\Xi \vdash \omega} : (\varphi <: \varphi')} \\
\hline
\end{array}$$

# When compiling to **OCaml**, coercions are mapped into **functions**

$$\begin{aligned} \mathscr{C}(\langle \sigma \rangle) &= \text{id} \\ \mathscr{C}(\omega_i) &= \texttt{w\_i} \\ \mathscr{C}(\omega_v \to \omega_c) &= \texttt{fun} f \mapsto x \mapsto (f(x \triangleright \mathscr{C}(\omega_v)) \triangleright \mathscr{C}(\omega_c)) \end{aligned}$$

$$\mathscr{C}(\omega_{v}!\varpi) = \begin{cases} \mathscr{C}(\omega_{v}) & \varpi : \emptyset \subseteq \emptyset \\ \operatorname{return} \circ \mathscr{C}(\omega_{v}) & \varpi : \emptyset \subseteq \varphi \\ \operatorname{map} \mathscr{C}(\omega_{v}) & \varpi : \varphi \subseteq \varphi' \end{cases}$$

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# Translating a **polymorphic** function incurs **additional parameters**

let apply\_zero f = f 0 in
apply\_zero cos

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# **Internal representation**

 $\texttt{let applyZero}_{\alpha,\beta,(\omega:\texttt{int}<:\alpha)}(f:\alpha\rightarrow\beta)=f(0\triangleright\omega)\texttt{ in }$ 

 $applyZero_{float,float,int2float}cos$ 

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applyZero<sub>float,float,int2float</sub>cos

#### **OCaml translation**

let apply\_zero w f = f (w 0) in
apply\_zero float\_of\_int cos

let apply\_zero f = f 0 in
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let apply\_zero w f = f (w 0) in
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Eff standard library ~450 coercion parameters quicksort ~200 coercion parameters

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# **Internal representation**

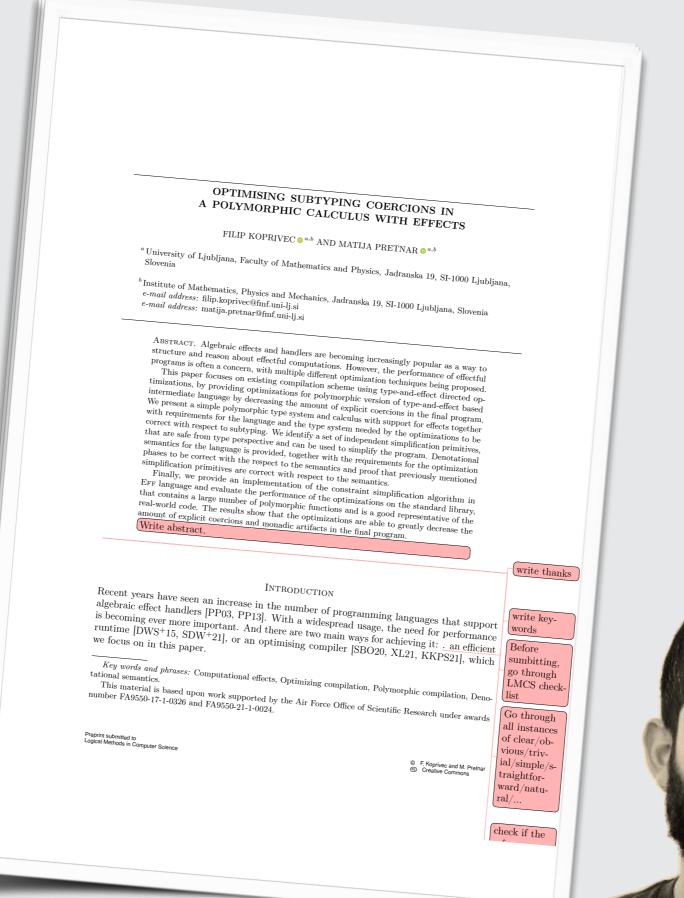
$$\texttt{let applyZero}_{\alpha,\beta,(\omega:\texttt{int}<:\alpha)}(f:\alpha\rightarrow\beta)=f(0\triangleright\omega)\texttt{ in }$$

 $applyZero_{float,float,int2float}cos$ 

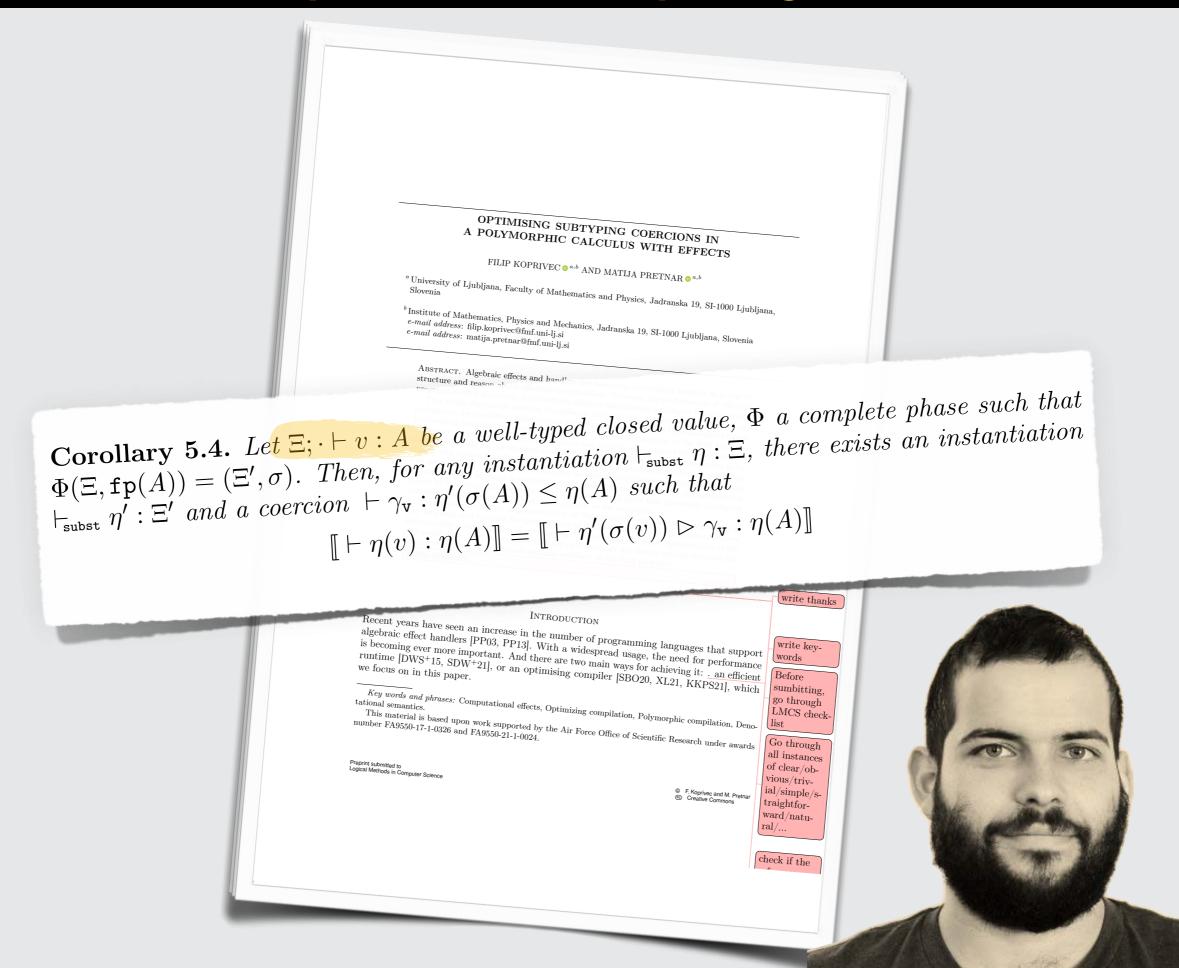
#### **OCaml translation**

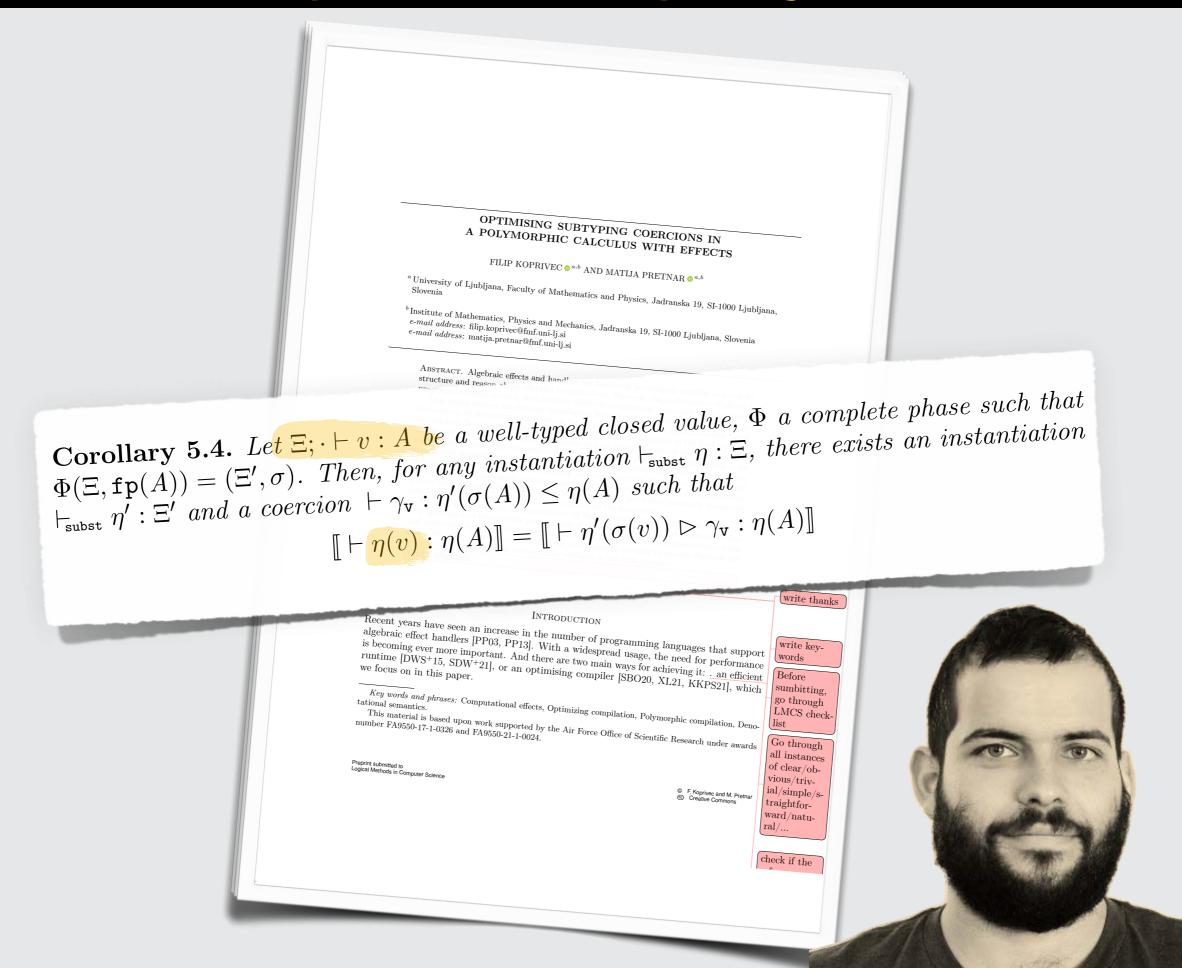
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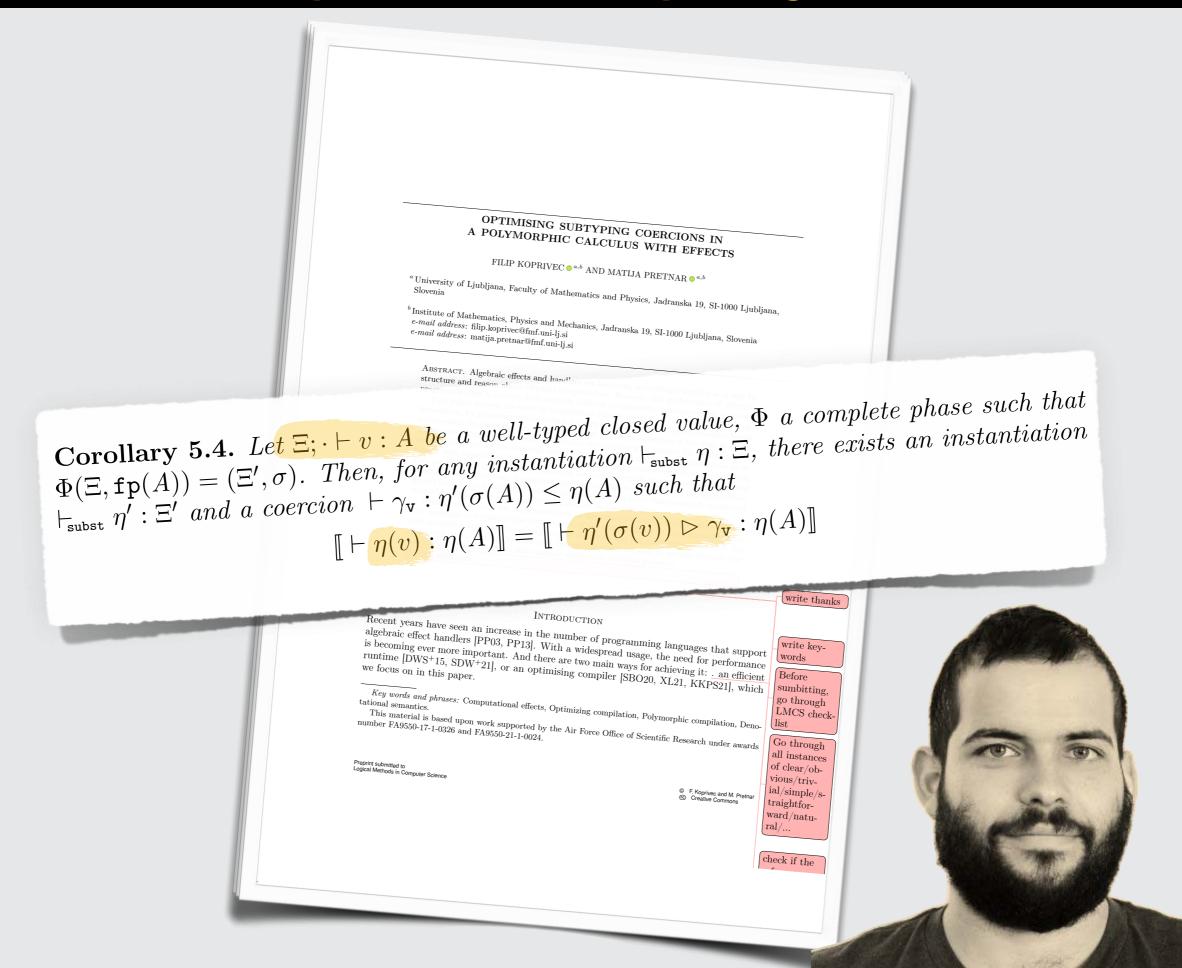
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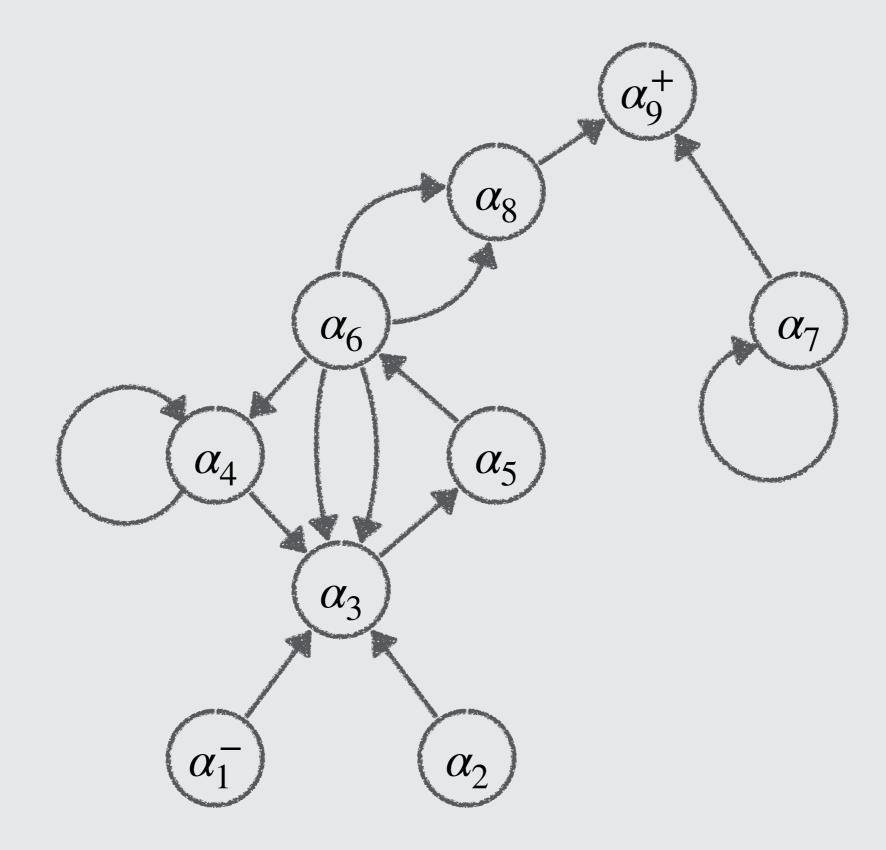




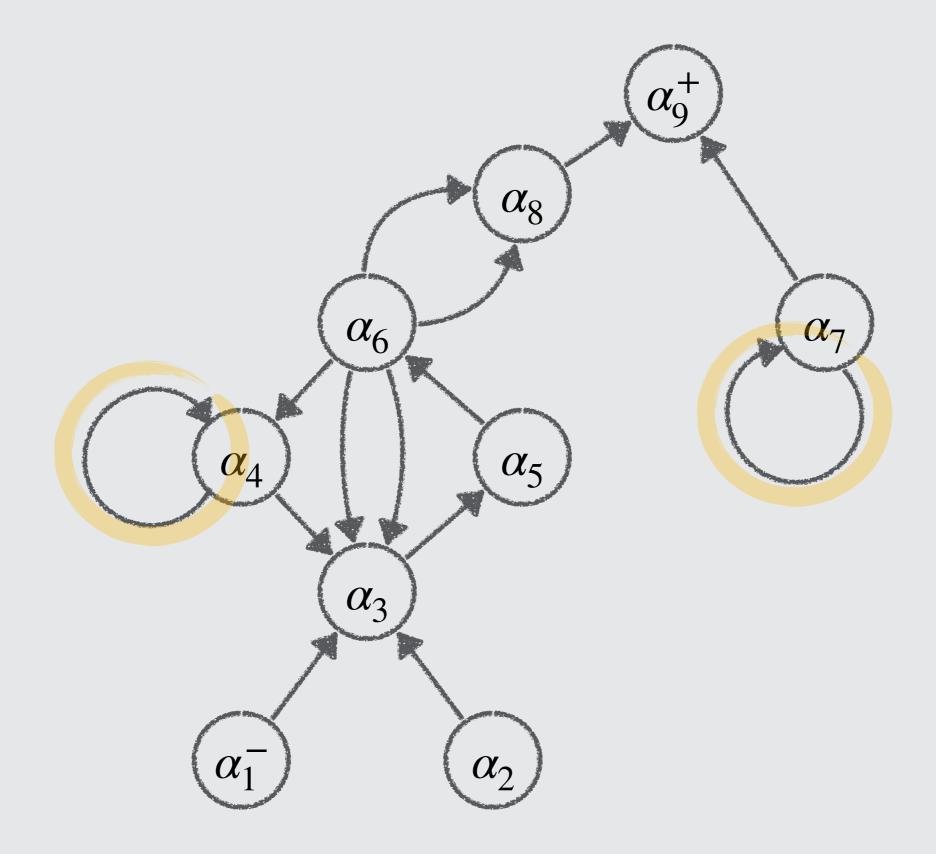




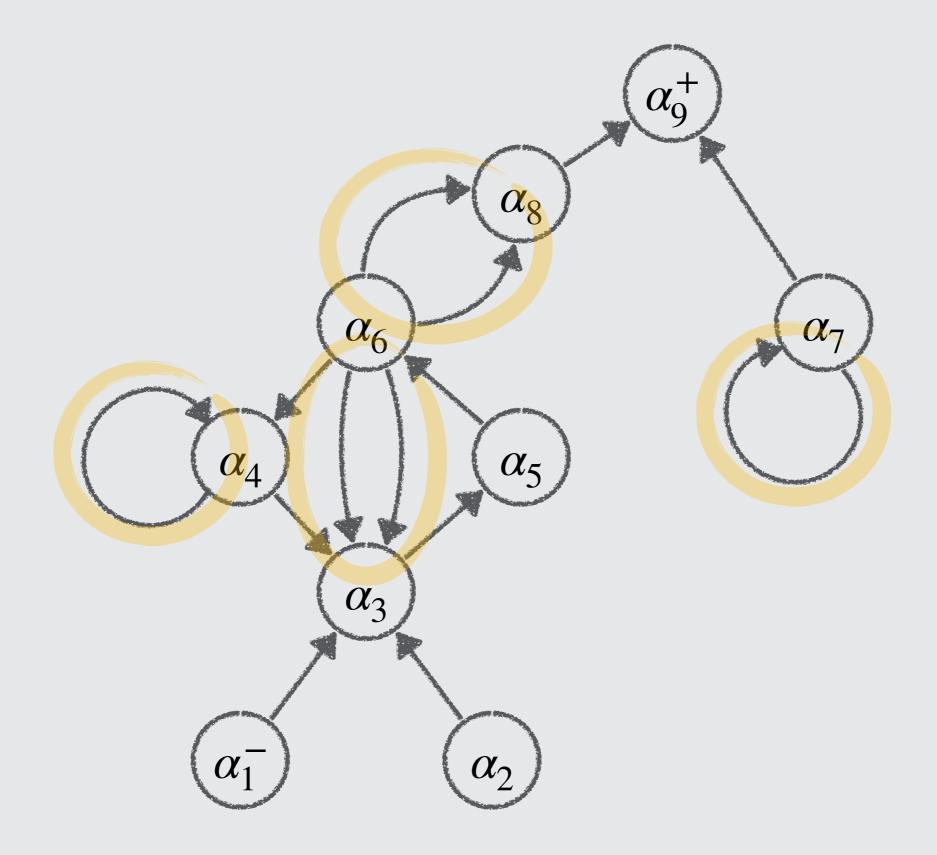
## Constraints can be represented with **directed graphs**



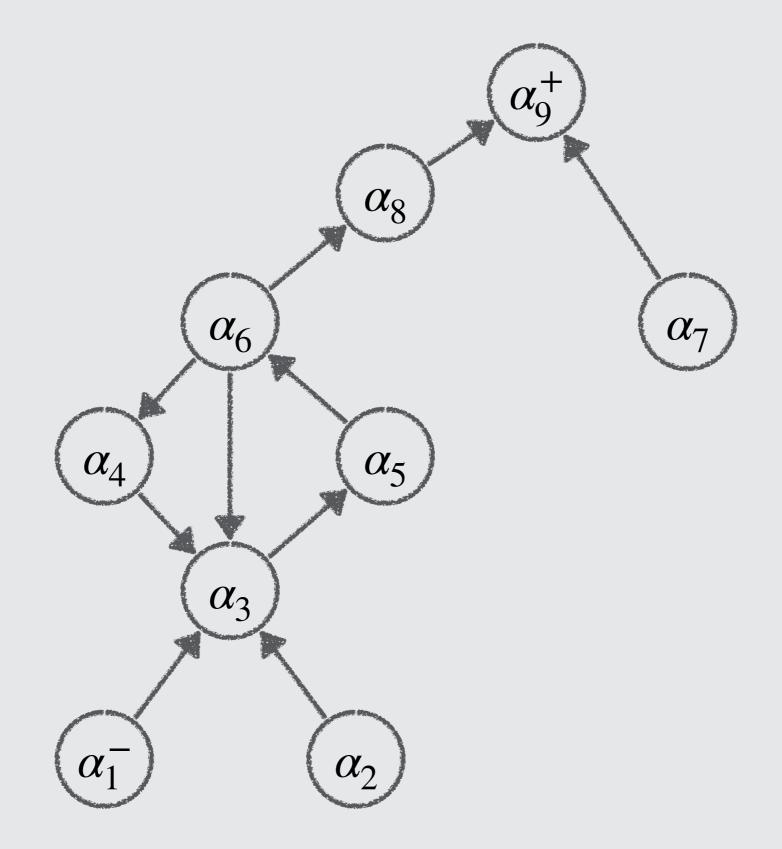
## Constraints can be represented with **directed graphs**



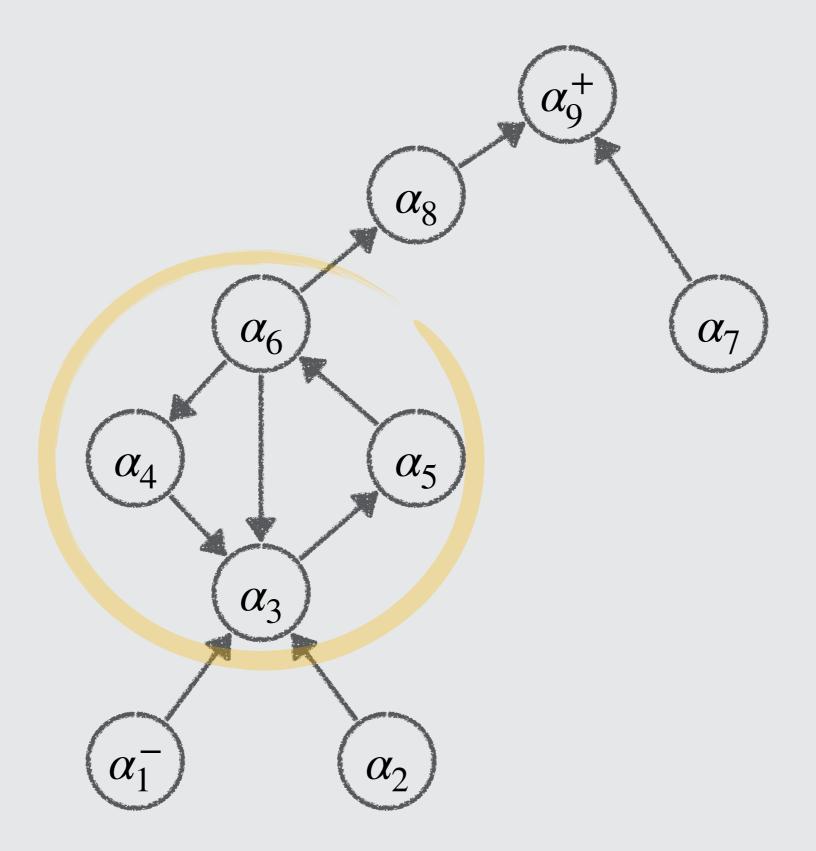
## Constraints can be represented with **directed graphs**



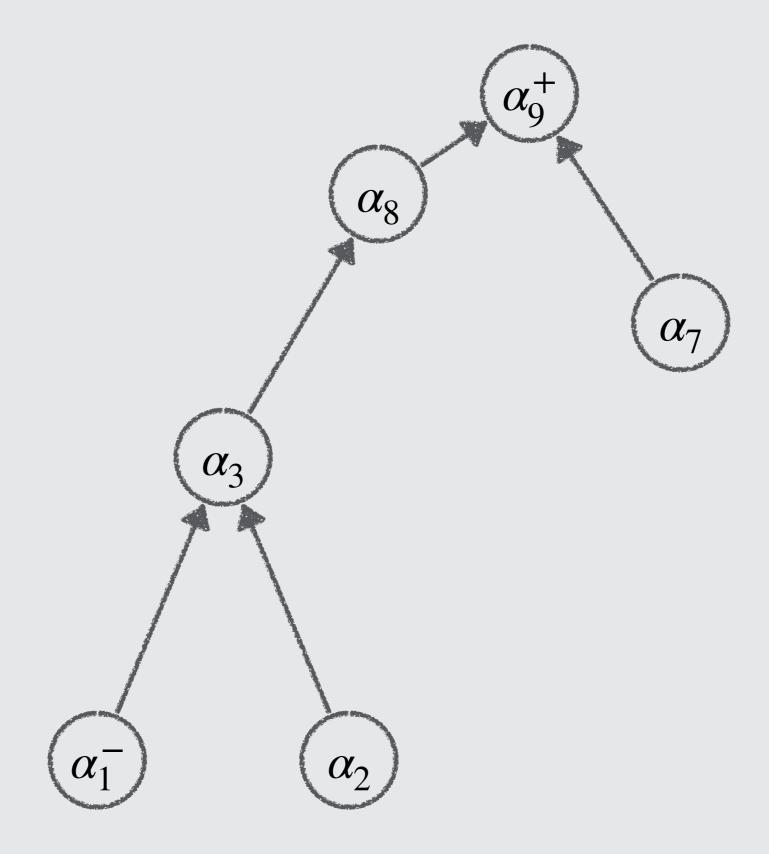
### We can **remove** self **loops** and **parallel** edges to get a simple graph



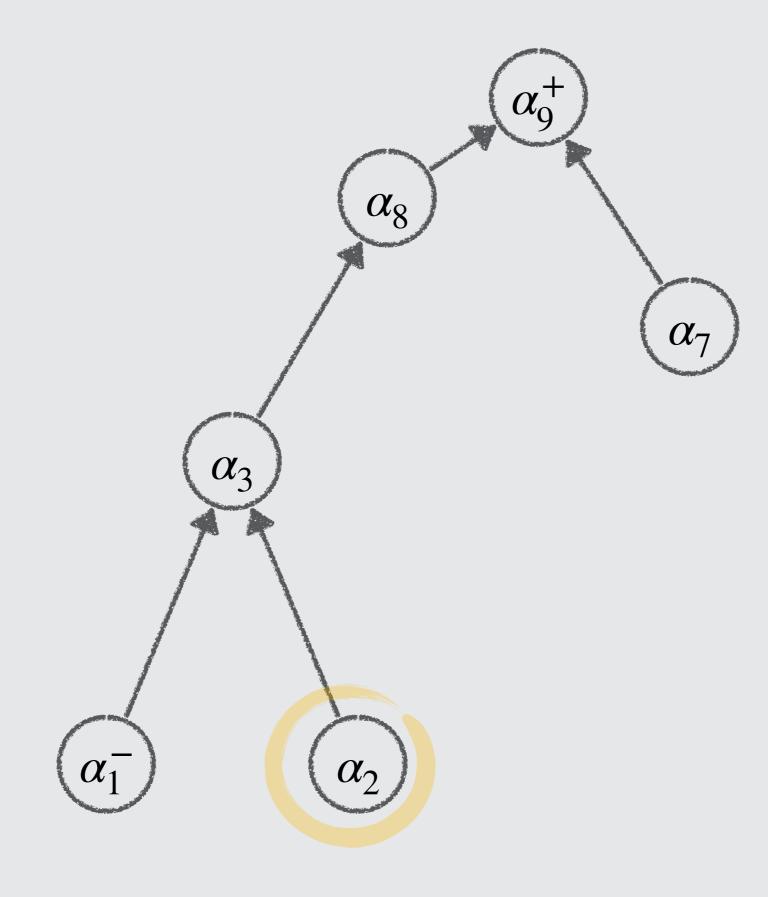
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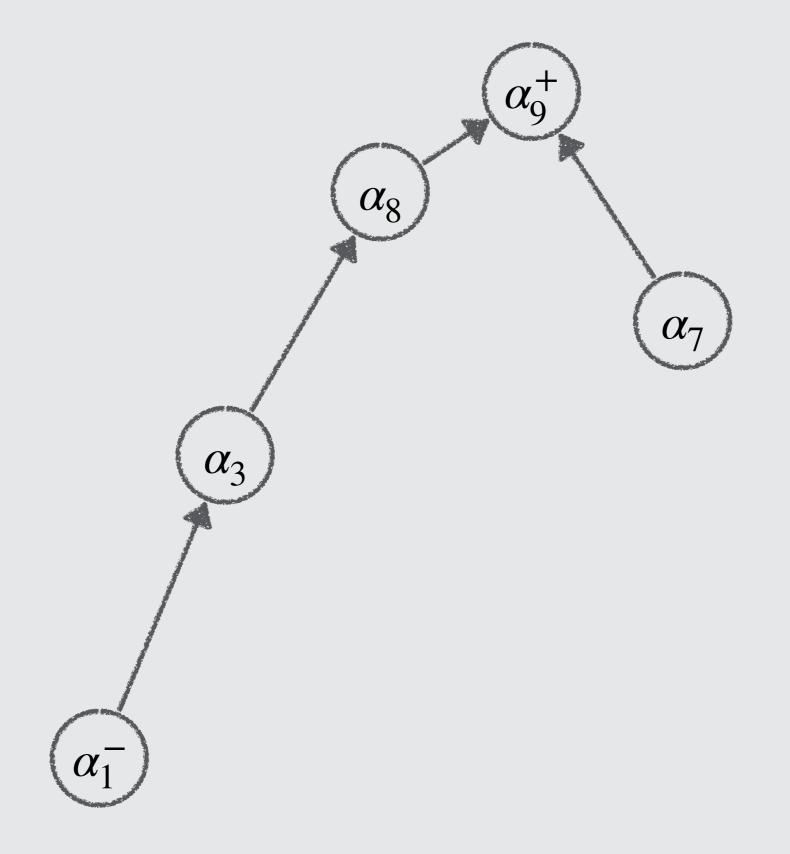


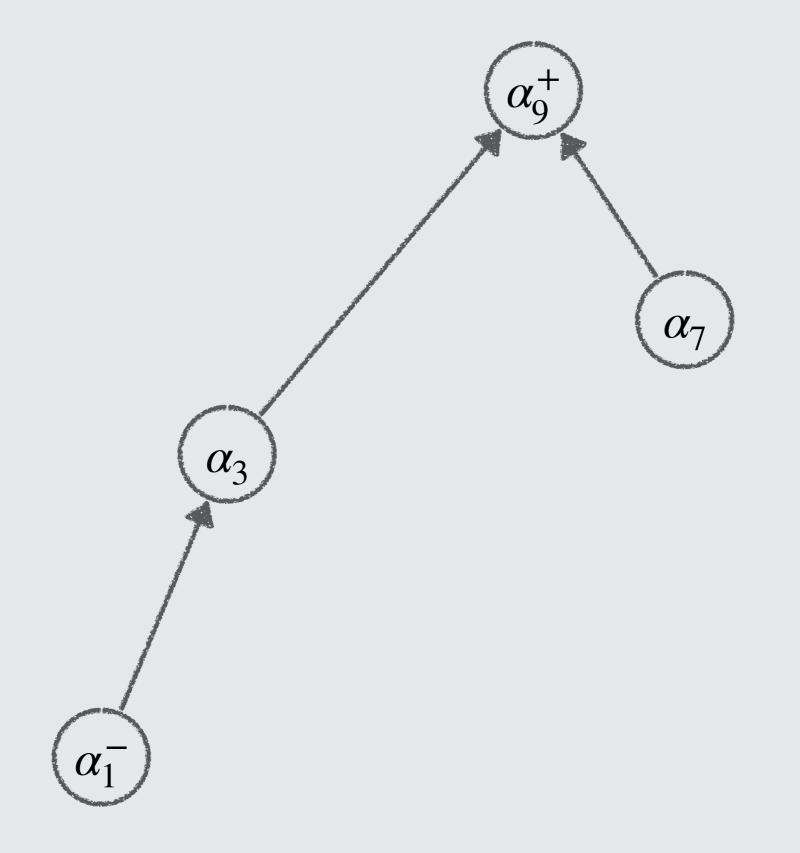
### We can **collapse** strongly **connected** components to get a DAG

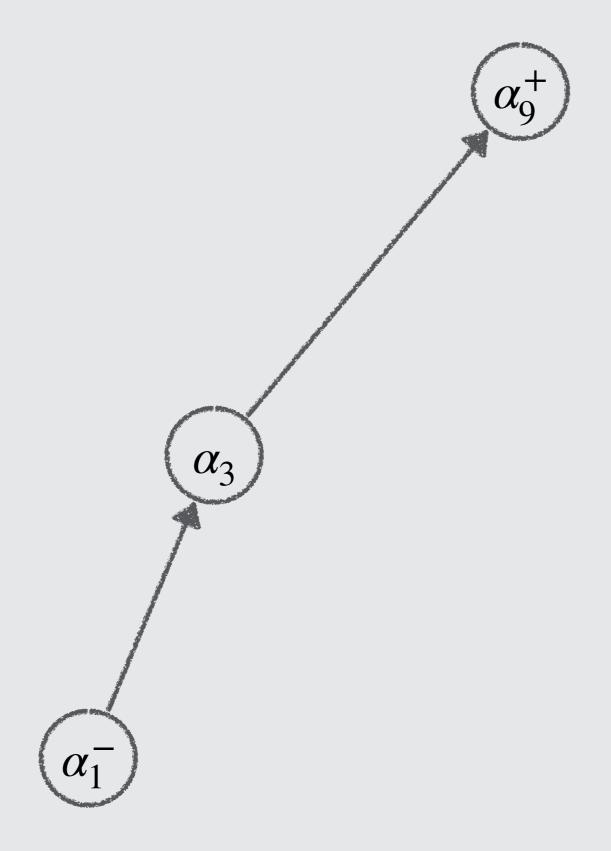


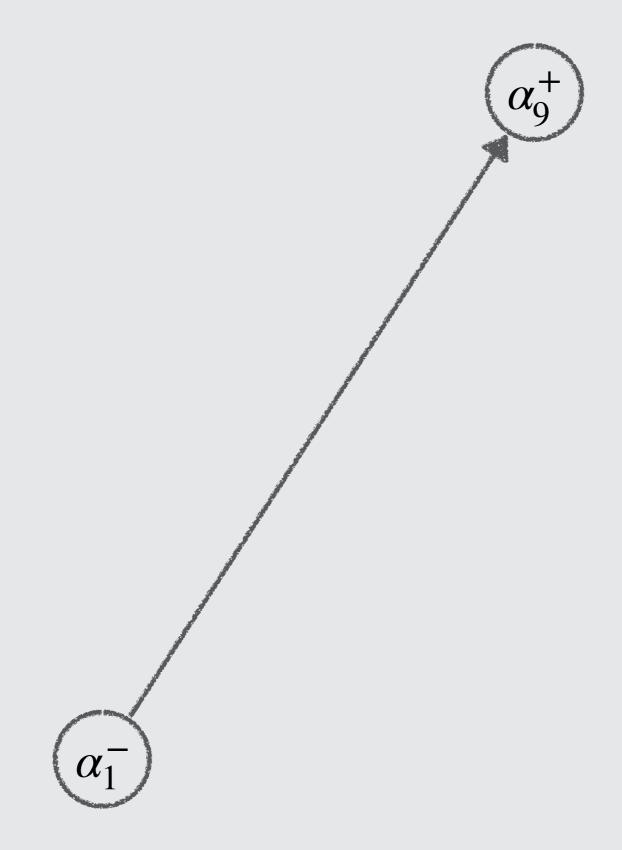
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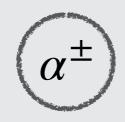


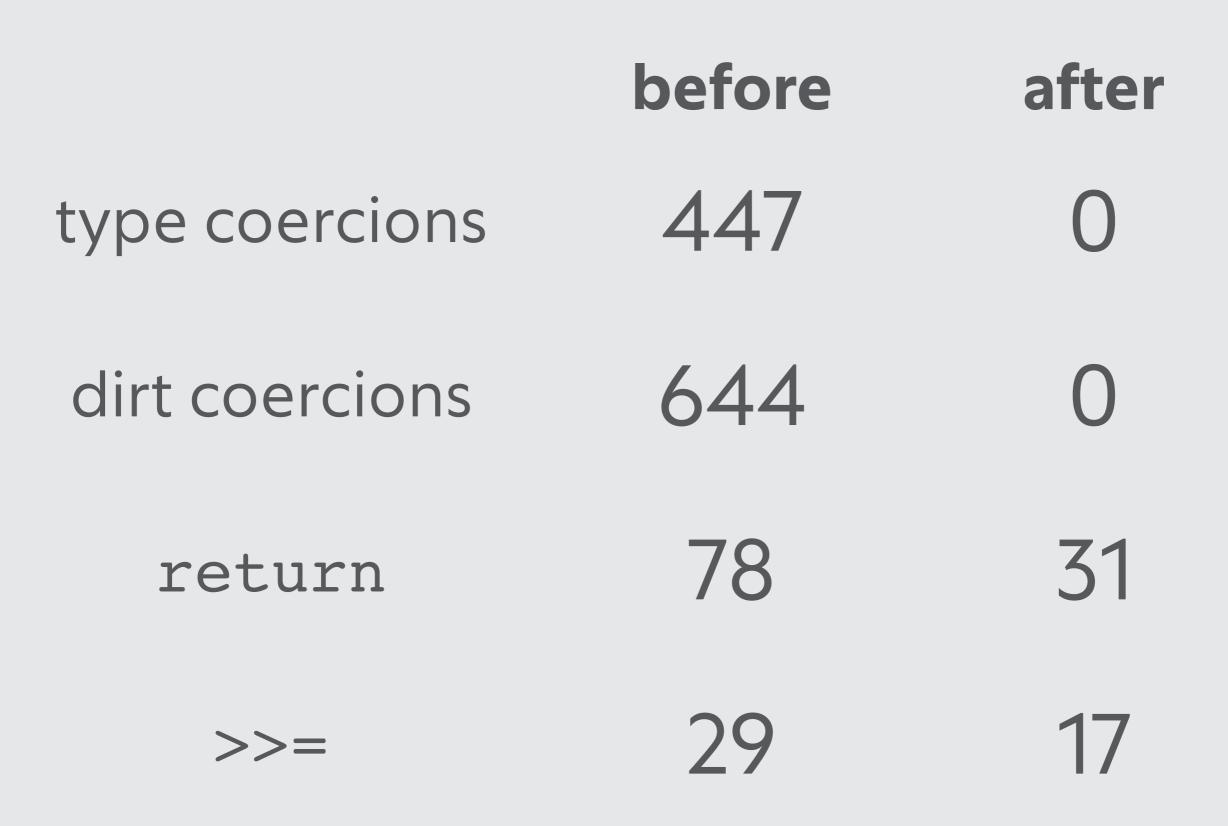














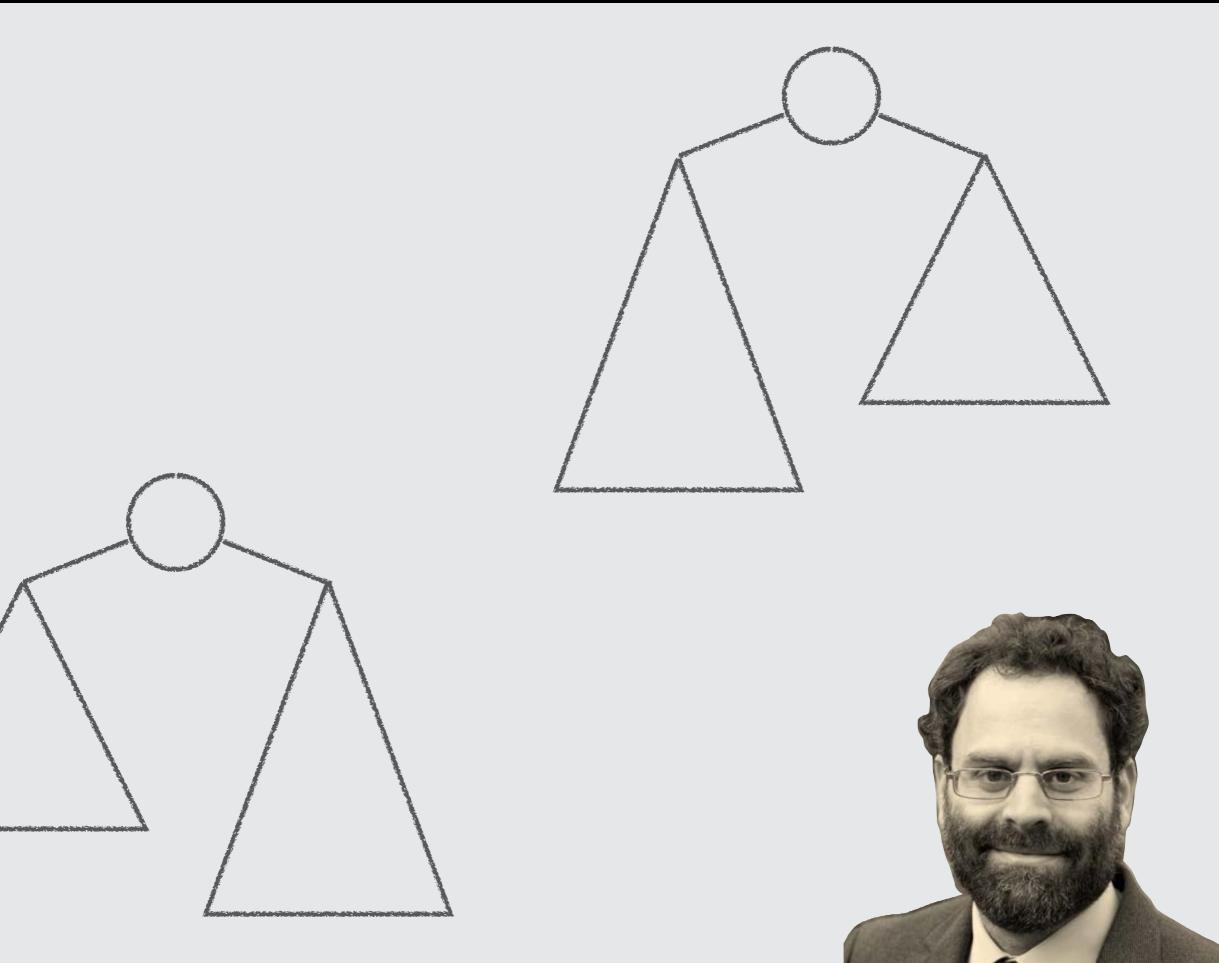




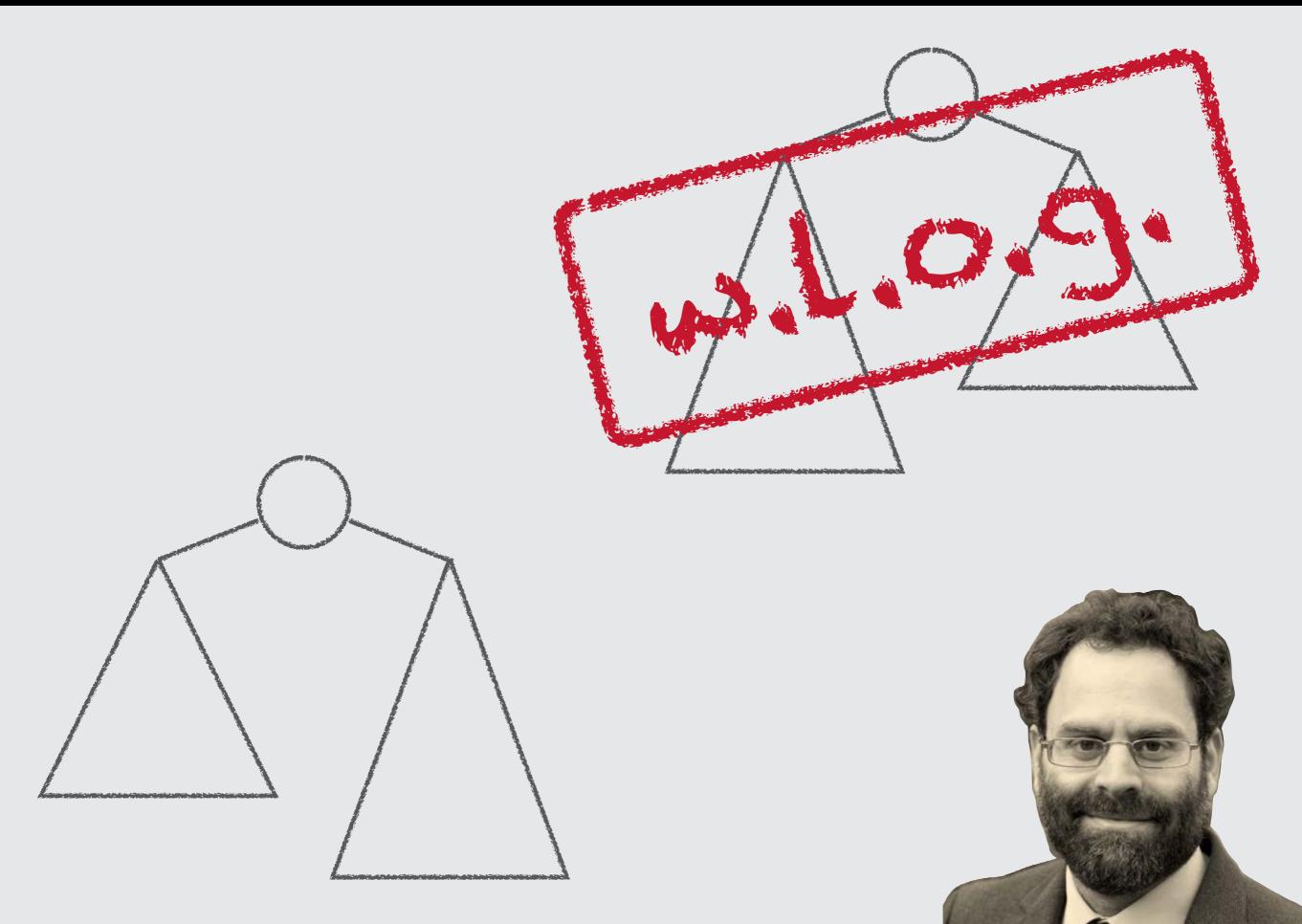
# Symmetry is present, but not used in **programming/proving**



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# Symmetry is present, but not used in **programming/proving**



**QUESTIONS?** 

THANK YOU.