

Component-Based Reduced Order Modeling for Large-Scale Industrial Digital Twins

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Principal Scientist



Protecting infrastructure across the energy industry with Akselos Structural Performance Management



GLOBAL PRESENCE

- LAUSANNE
- DUBAI
- HOUSTON
- BOSTON
- PORTO
- SINGAPORE
- HO CHI MINH CITY



LICENSED PATENTED TECHNOLOGY

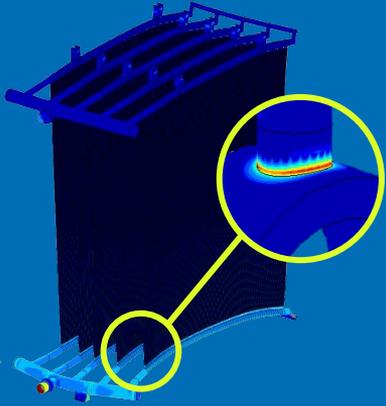
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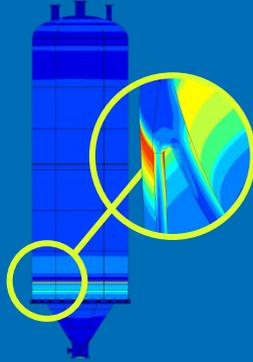
WORLD ECONOMIC FORUM
GLOBAL INNOVATOR



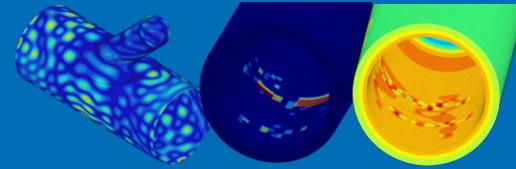
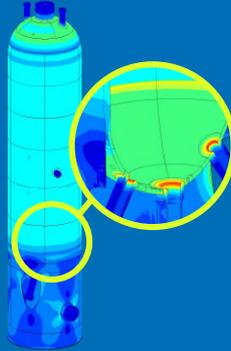
ORVs



COKERS

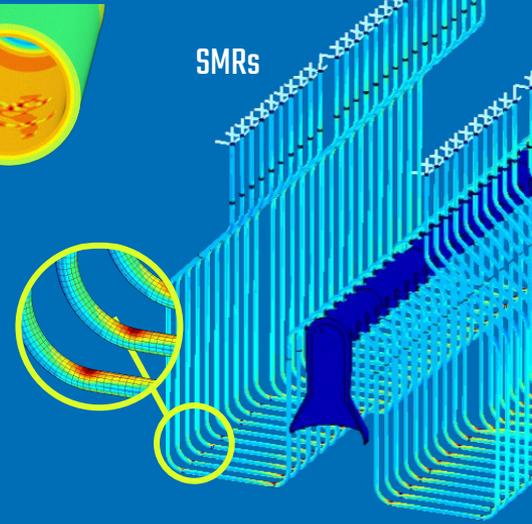


REACTORS

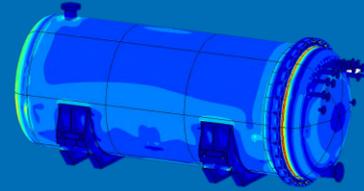


PIPES

SMRs



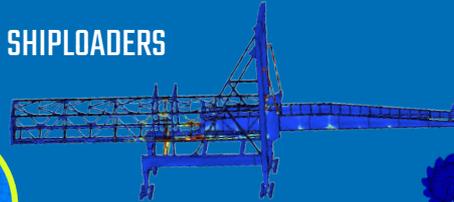
PRESSURE VESSELS



JACKETS



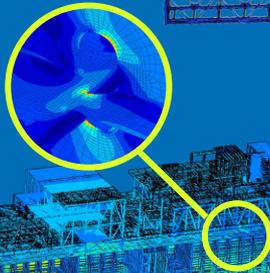
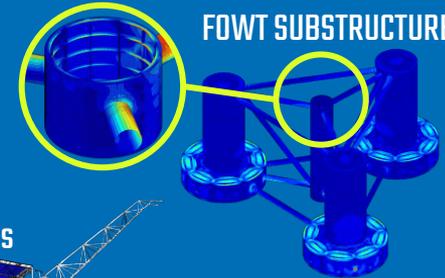
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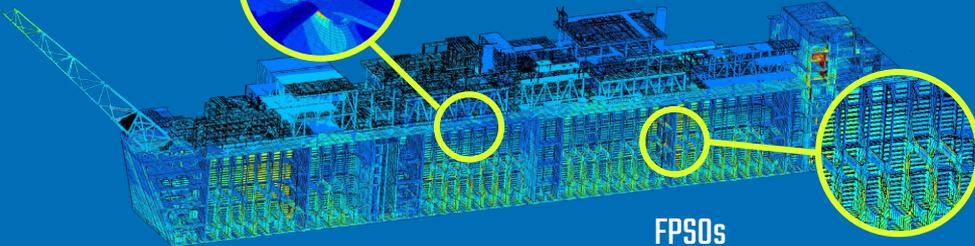
RECLAIMERS



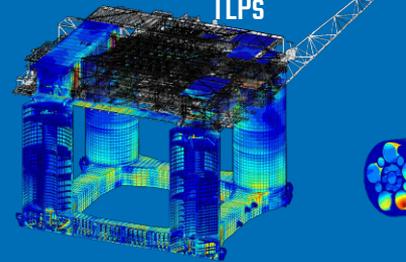
FOWT SUBSTRUCTURES



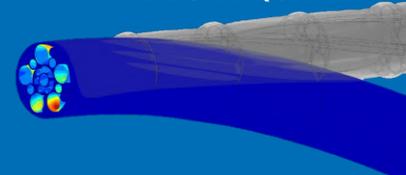
FPSOs



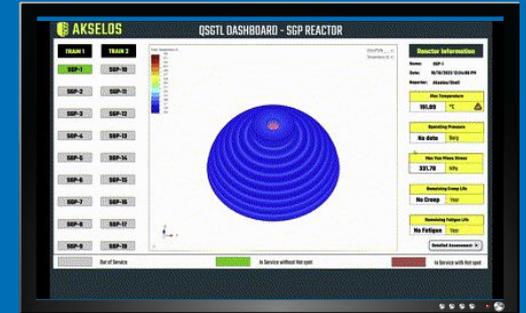
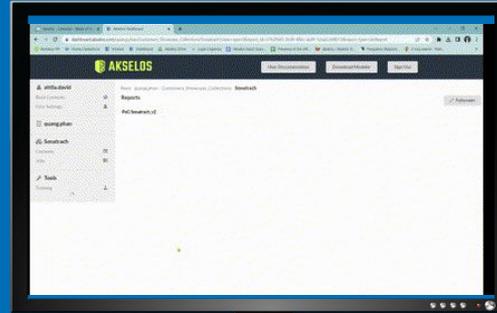
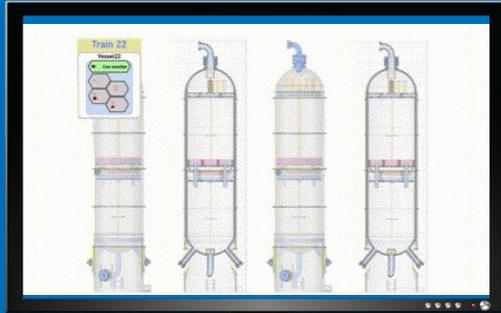
TLPs



UMBILICALS & CABLES



DASHBOARD EXAMPLES



A Digital Twin Definition

A digital twin is a set of virtual information constructs that mimics the structure, context, and behavior of a natural, engineered, or social system (or system-of-systems), is dynamically updated with data from its physical twin, has a predictive capability, and informs decisions that realize value. The bidirectional interaction between the virtual and the physical is central to the digital twin.

US National Academies Report on Digital Twins, Dec 2023

Focus of Akselos Digital Twins

- Structural analysis
- Used in operations, incorporates all data available (design data, sensor feeds, inspection reports, etc.), **deliver value to operators!**
- Model entire asset in full 3D including “as is” condition data
- Must be fast enough to “keep up” with cadence of operations
- Must be compliant with industry standards (e.g. ASME, API, DNV, ABS, LR, ...)

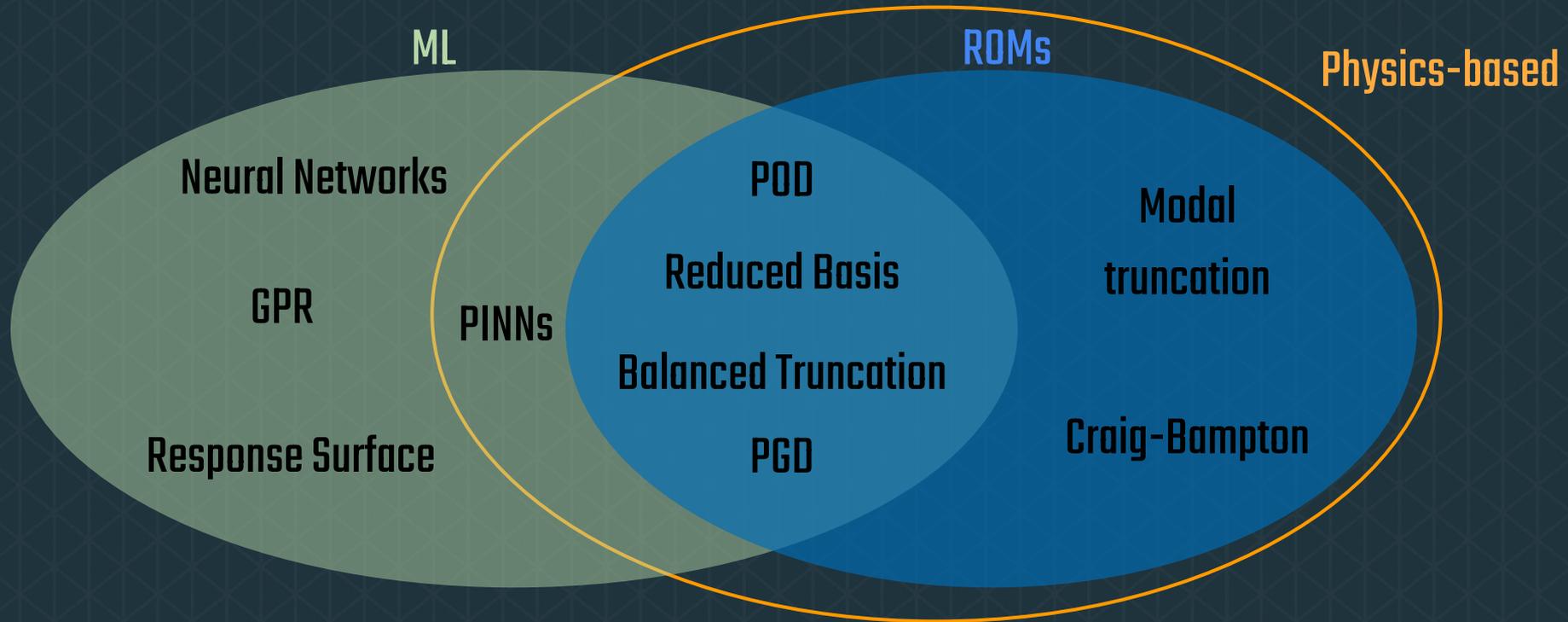
Reduced Order Modeling (ROM) for Digital Twins

To achieve these goals, Akselos uses physics-based ROMs:

- **Reduced Basis (RB):** ROM for fast response to “keep up” with operations
- **Component-based:** Large-scale, detailed models of entire assets
- **Parametric:** Incorporate new data based on sensor or inspections (temperatures, strains, loads, defects, etc.), or run “what if” scenarios
- **Based on FEA, with a posteriori error estimators:** Compliant with industry standards

ROMs and ML

RB can be considered Physics-based ML: Training phase based on physics to “learn” the response, and fast Online evaluation phase



Reduced Basis Method

FEA: Given the parameter vector μ find solution that satisfies PDE weak form for all “test functions”:

$$a(u^N(\mu), v; \mu) = f(v; \mu) \quad \forall v \in X^N$$

RB: Same as FEA, but “trial” and “test” spaces are span of a Reduced Basis ($n \ll N$):

$$a(u_n(\mu), v; \mu) = f(v; \mu) \quad \forall v \in X_n$$

(See review article: Rozza, Huynh, Patera, Arch. Comput. Methods Eng., 2007)

Reduced Basis Method: Linear Algebra Version

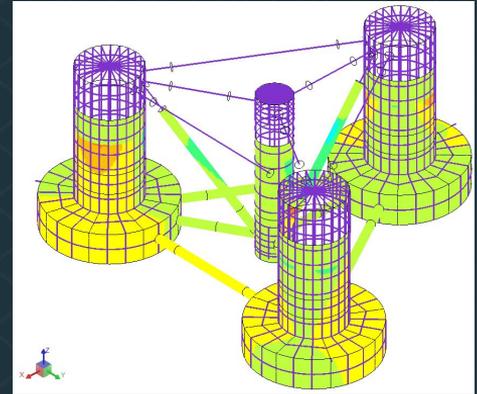
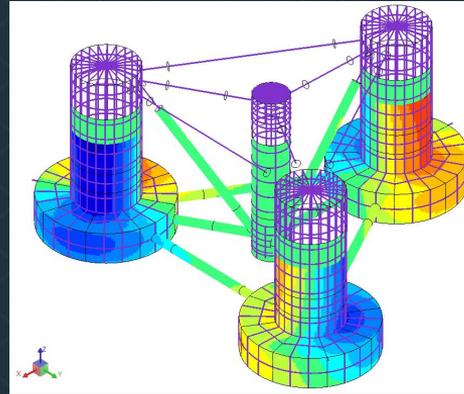
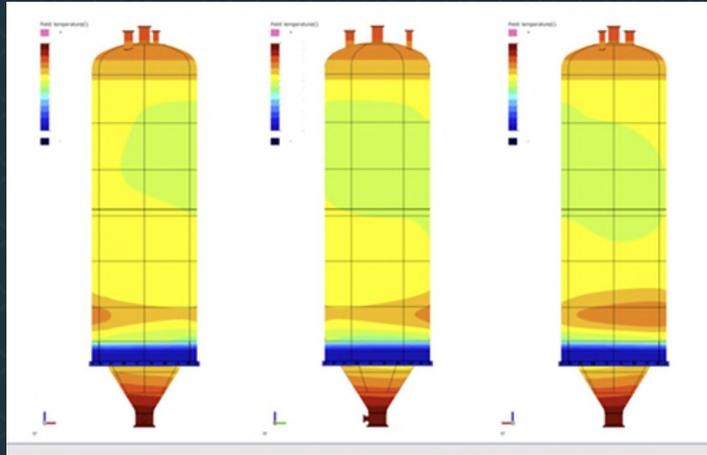
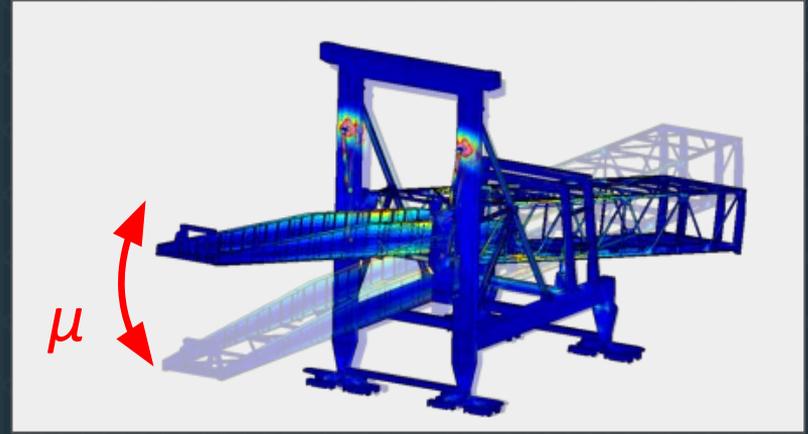
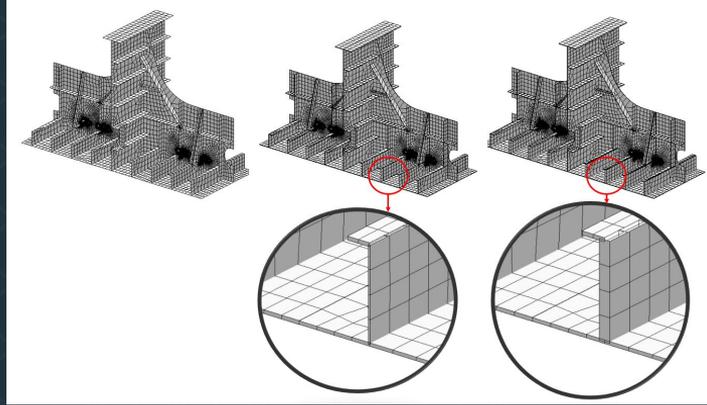
FEA matrices/vectors: $A(\mu) \in \mathbb{R}^{N \times N}$, $U(\mu), F(\mu) \in \mathbb{R}^N$

$$A(\mu)U(\mu) = F(\mu)$$

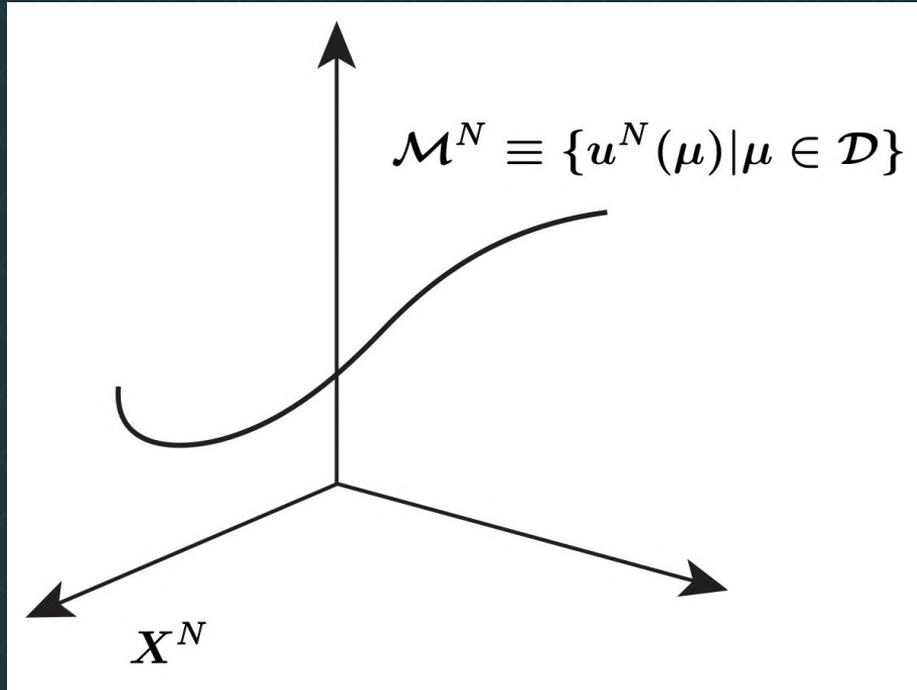
Reduced Basis: $Z \in \mathbb{R}^{N \times n}$, $U_{RB} \in \mathbb{R}^n$

$$Z^T A(\mu) Z U_{RB}(\mu) = Z^T F(\mu)$$

Reduced Basis Method: Parameters

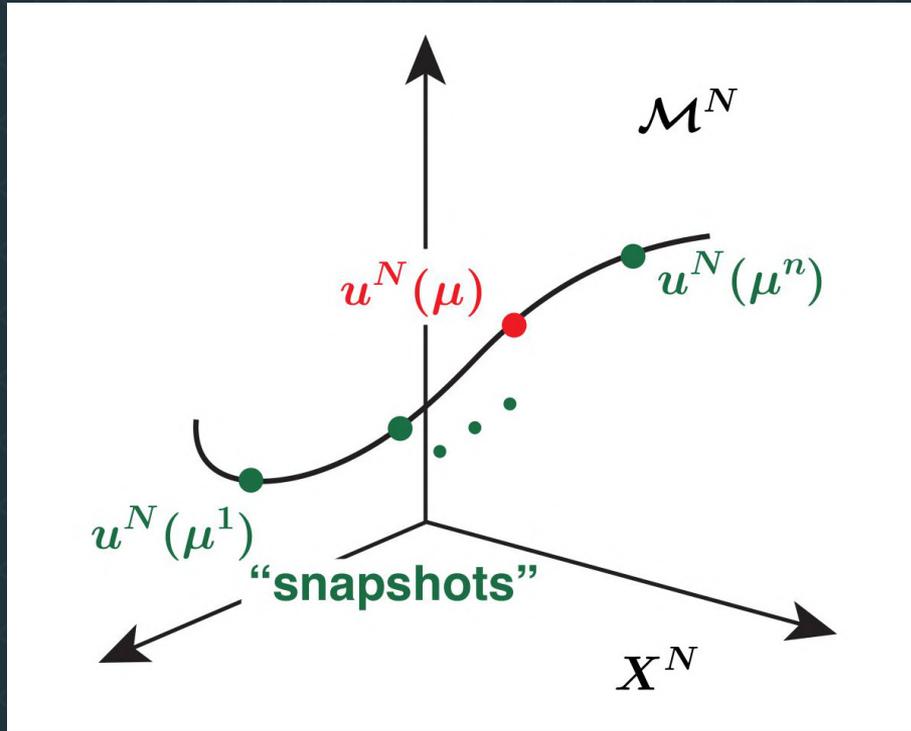


Reduced Basis Method: Solution Manifold



Parametrized “solution manifold” in a high-dimensional space, this is what we want to “learn”

Reduced Basis Method: Solution Manifold



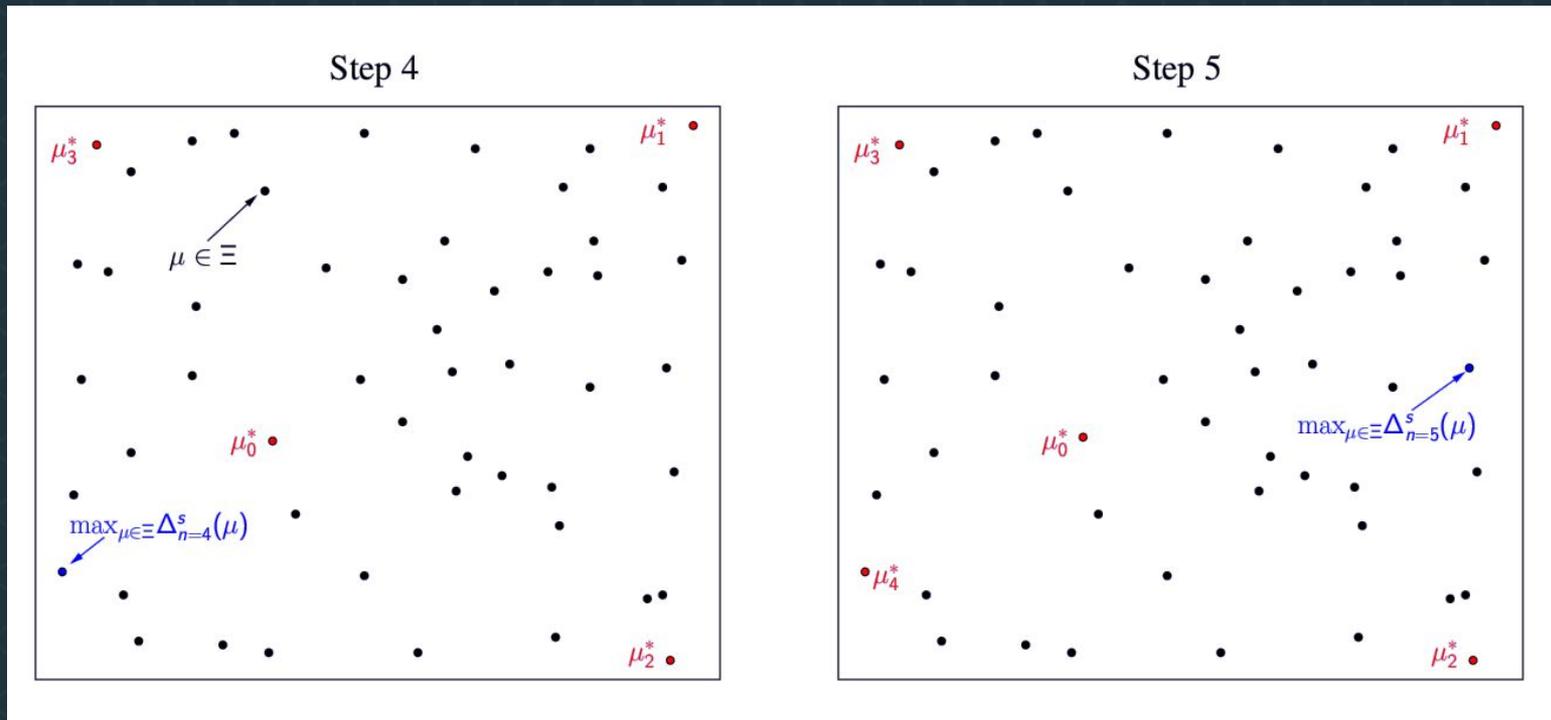
- RB: Generate a subspace highly targeted to the solution manifold via “snapshots”
- Other ML methods aim to learn the nonlinear manifold directly rather than building a subspace

Reduced Basis Method

Two paths to a Reduced Basis:

- **POD: Compute snapshots, apply SVD to get “compressed” Reduced Basis (full order solve for each parameter sample, can be expensive!)**
- **Greedy algorithm: Compute “most beneficial” snapshot at each iteration guided by error estimator (full order solve for each RB basis function only)**

Reduced Basis Method: Greedy Algorithm



Greedy algorithm converges rapidly (exponential convergence under reasonable assumptions, see Binev et al., 2010) hence typically reach tolerance with small RB space

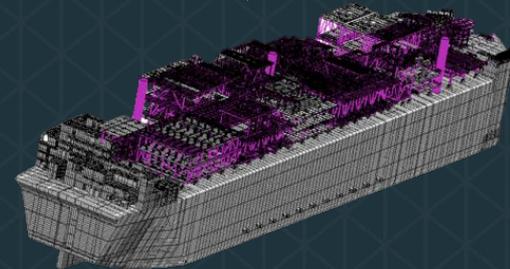
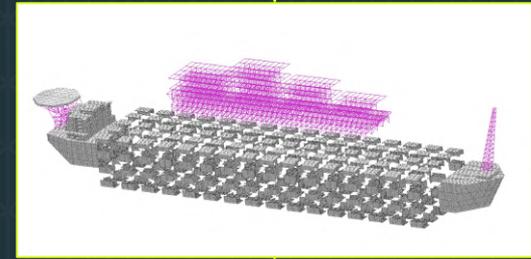
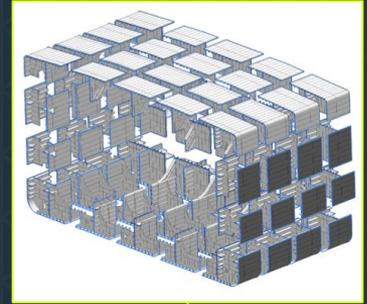
Reduced Basis Method: Extensions & Limitations

- RB has been applied to a wide range of PDE types (time-dependent, frequency domain, nonlinear, etc.) following the framework described above
- Key requirement for nonlinear: “hyper-reduction” (e.g. EIM, DEIM, gappy POD) to ensure fast Online response
- Main limitation of RB: Solution manifold must be “smooth” (low Kolmogorov n -width) to permit an accurate low-dimensional Reduced Basis
- “Single domain” RB: Limited in model size and number of parameters

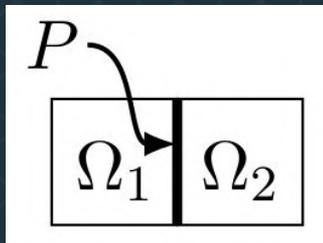
Component-Based RB

Huynh, Knezevic, Patera, "A Static condensation Reduced Basis Element method: approximation and a posteriori error estimation", M2AN 2012.

- Component interior and interface ROMs for efficient system modeling with many parameters
- Automated training based on system-level error indicators
- Training based on individual components and component groups, no "global Full Order" solves required in training!



Component-Based: linear case = static condensation



$$\begin{bmatrix} A_P & A_{P,\Omega_1}^T & A_{P,\Omega_2}^T \\ A_{P,\Omega_1} & A_{\Omega_1} & 0 \\ A_{P,\Omega_2} & 0 & A_{\Omega_2} \end{bmatrix} \begin{bmatrix} \mathbf{U} \\ \mathbf{u}_{\Omega_1} \\ \mathbf{u}_{\Omega_2} \end{bmatrix} = \begin{bmatrix} \mathbf{f}_P \\ \mathbf{f}_{\Omega_1} \\ \mathbf{f}_{\Omega_2} \end{bmatrix}$$

$$\mathcal{O}(\mathcal{N}^{1+\alpha})$$

- Schur complement

$$\mathbb{A} = A_P - A_{P,\Omega_1}^T A_{\Omega_1}^{-1} A_{P,\Omega_1} - A_{P,\Omega_2}^T A_{\Omega_2}^{-1} A_{P,\Omega_2}$$

$$\mathbb{F} = \mathbf{f}_P - A_{P,\Omega_1}^T A_{\Omega_1}^{-1} \mathbf{f}_{\Omega_1} - A_{P,\Omega_2}^T A_{\Omega_2}^{-1} \mathbf{f}_{\Omega_2}$$

$$\underbrace{[\mathbb{A}]}_{\mathcal{N}_p \times \mathcal{N}_p} \underbrace{[\mathbf{U}]}_{\mathcal{N}_p \times 1} = \underbrace{[\mathbb{F}]}_{\mathcal{N}_p \times 1}$$

$$\mathcal{O}(\mathcal{N}_p(\mathcal{N}_1^{1+\alpha} + \mathcal{N}_2^{1+\alpha}) + \mathcal{N}_p^3)$$

Component-Based: reduction

- Solve $A_{\Omega_1}^{-1} A_{P, \Omega_1}$ and $A_{\Omega_1}^{-1} \mathbf{f}_{\Omega_1}$ with reduced basis $\mathcal{O}(\mathcal{N}_p N^3)$ instead of $\mathcal{O}(\mathcal{N}_p \mathcal{N}_1^{1+\alpha})$

In total

$$\mathcal{O}(\mathcal{N}_p N^3 + \mathcal{N}_p^3) \text{ instead of } \mathcal{O}(\mathcal{N}_p (\mathcal{N}_1^{1+\alpha} + \mathcal{N}_2^{1+\alpha}) + \mathcal{N}_p^3)$$

- Use a reduced basis for P to make \mathcal{N}_p as small as possible

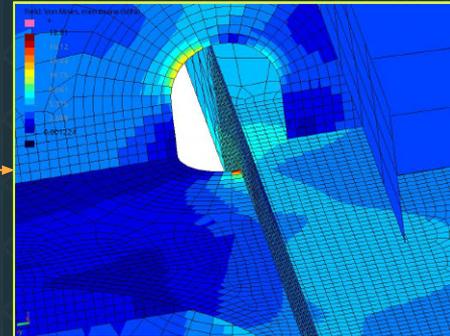
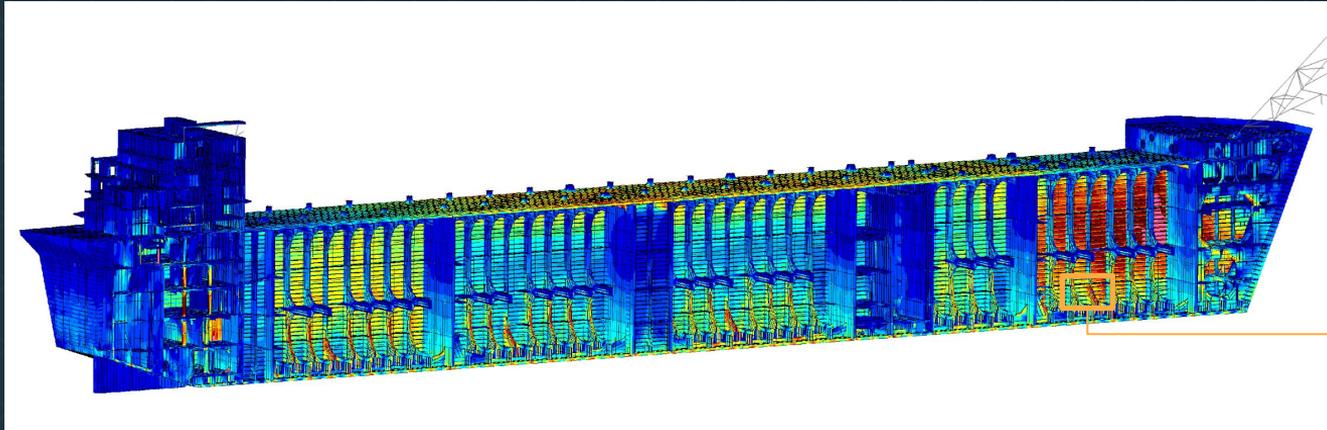
Eftang, Patera, "Port reduction in parametrized component static condensation: approximation and a posteriori error estimation.", IJNME 2013.

Component-Based: system-level error indicator

- **Based on residual calculation (similar to traditional FEA)**
Smetana, "A new certification framework for the port reduced static condensation Reduced Basis Element method", CMAME 2015.
- **Cost is negligible compared to system-level online solve**
- **Critical to ensure trust from customers: all the industry standards refer to FEA accuracy.**

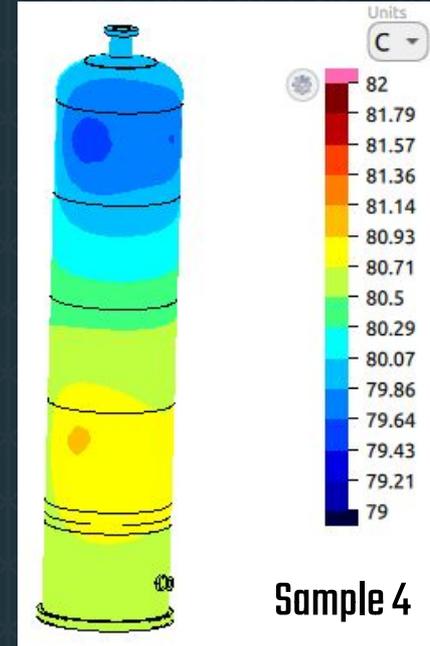
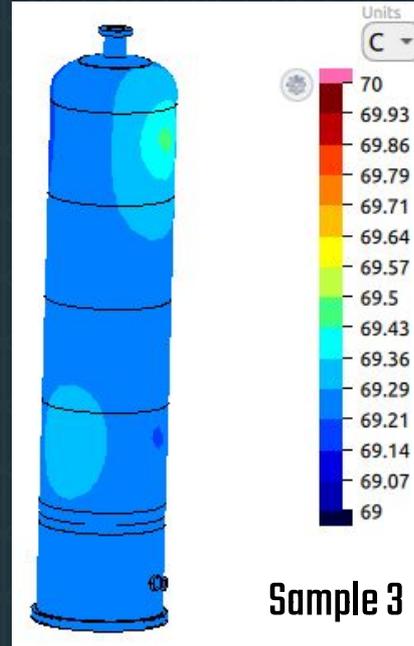
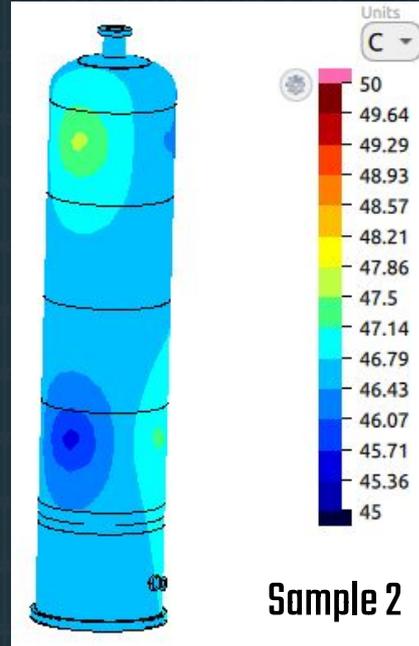
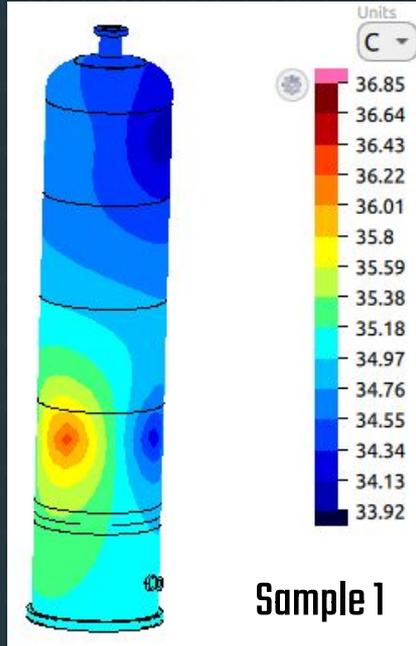
Component-Based RB

- Orders of magnitude **speedup** and “**scale up**” compared to FEA, e.g. >100 million DOF hull model solved in < 10 seconds **with error indicator to ensure accuracy**



Error Indicators + Automated Enrichment

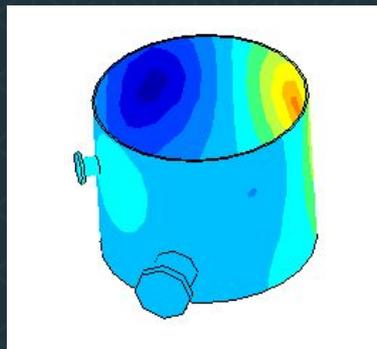
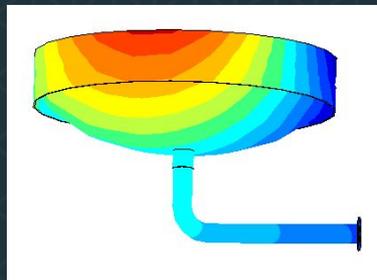
Initial training based on a sample set of relevant data, training runs automatically on cloud-based HPC (components trained in parallel)



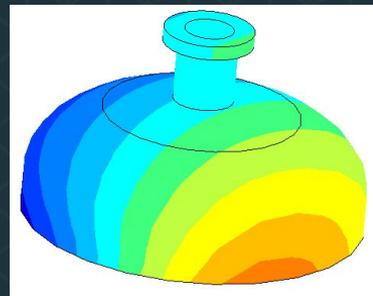
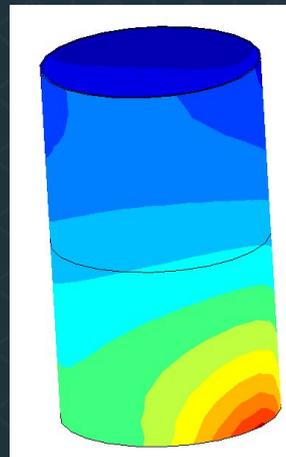
Error Indicators + Automated Enrichment

Training via individual components and groups, “global Full Order” solves not required!

Individual components



Groups



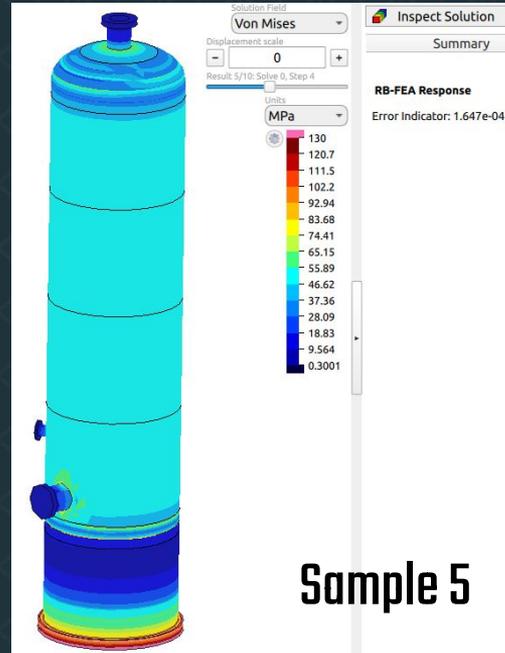
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Error Indicators + Automated Enrichment

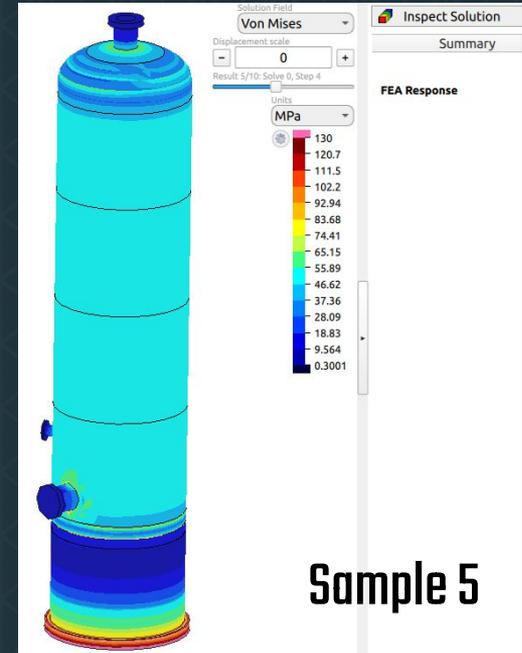
Training ensures **error indicator** < **tolerance** for all samples, typical tolerance: 0.01



before training,
error indicator 0.7061



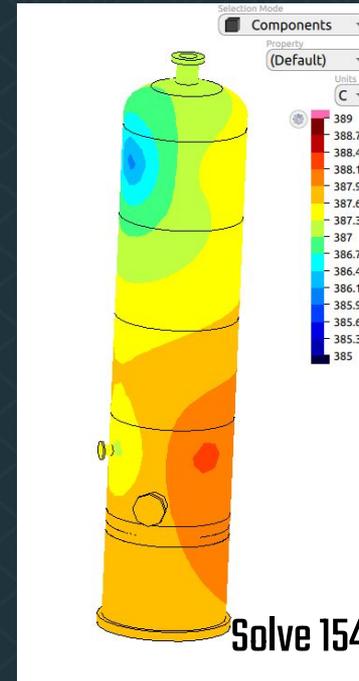
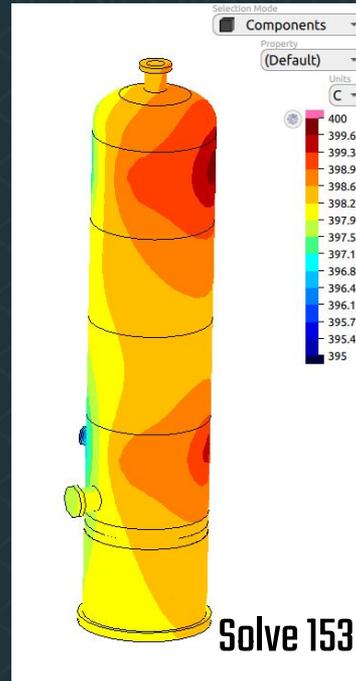
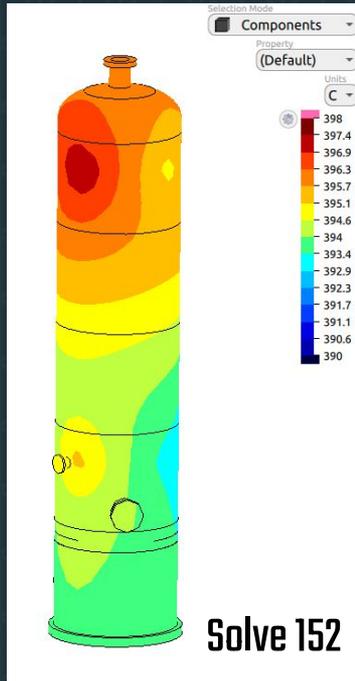
after training,
error indicator 1.647e-4



Check: Compare to FEA

Error Indicators + Automated Enrichment

Deploy in operations, connected to data from asset (e.g. temperature, pressure, load monitoring, inspection data), **will encounter new parameter values!**



Error Indicators + Automated Enrichment

Error indicator is computed for every Online solve, if we exceed specified tolerance auto-enrichment is triggered, hence **model continues to “learn” based on operational data**

Solve	Error Indicator
...	...
152	2.872e-3
153	5.603e-3
154	1.203e-2
155	5.253e-3
156	5.112e-3
157	2.041e-3

enrichment using
parameters from Solve 154

Automated re-solve,
error indicator **9.863e-4**

Hybrid Solver for “Non-Smooth” Nonlinearities

Ballani et al., “A component-based hybrid reduced basis/finite element method for solid mechanics with local nonlinearities”, CMAME 2018.

We use Full Order modeling for “non-smooth” nonlinearities (e.g. plasticity, contact), can be included as localized regions in a “Hybrid” RB/FEA model

Couple RB and FEA regions
using coupling matrix C :

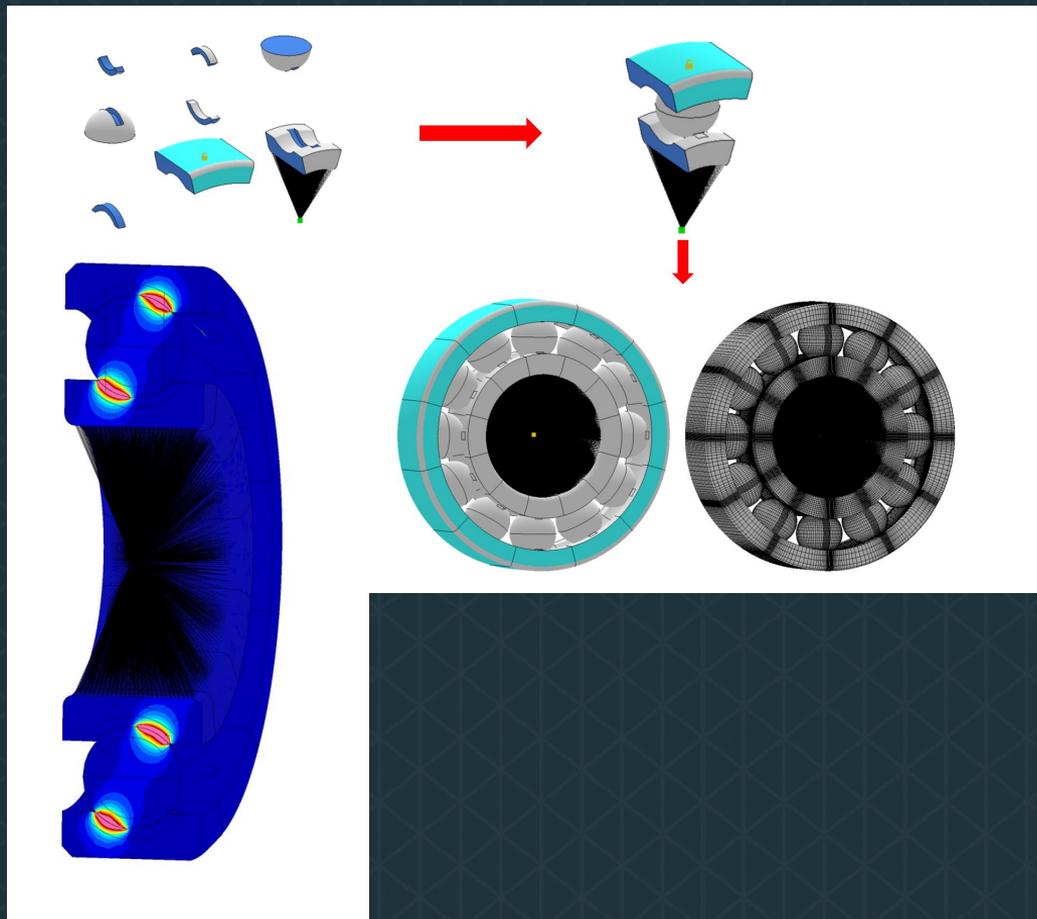
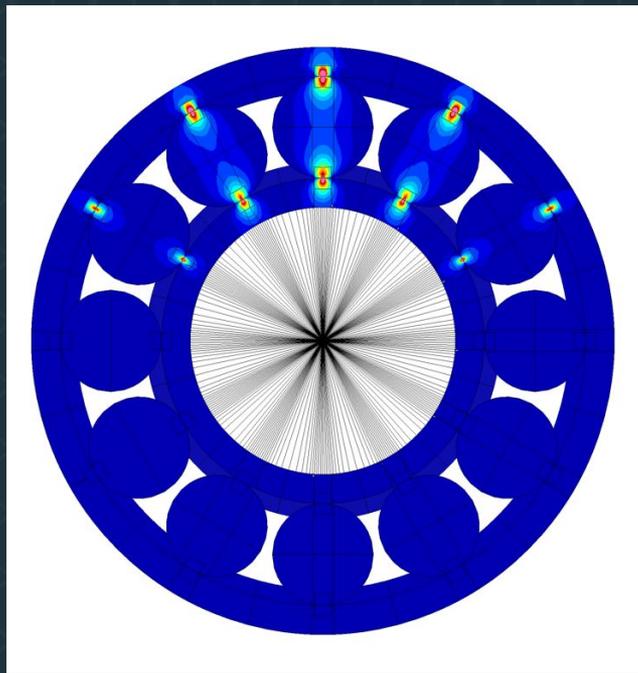
$$G(U) = C^T \begin{bmatrix} \mathbb{F}(\mu) - \mathbb{A}(\mu)U(\mu) \\ G_{\text{FE}}(U) \end{bmatrix}$$

$$J_G(U) = C^T \begin{bmatrix} -\mathbb{A}(\mu) & 0 \\ 0 & J_{G_{\text{FE}}}(U) \end{bmatrix} C$$

Apply Newton’s method to
coupled system:

$$\begin{aligned} J_G(U^k) \Delta U^k &= -G(U^k) \\ U^{k+1} &= U^k + \Delta U^k \end{aligned}$$

Hybrid Solver for “Non-Smooth” Nonlinearities

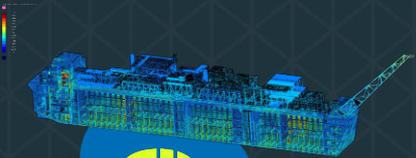


Digital Twin Examples

REAL ASSET



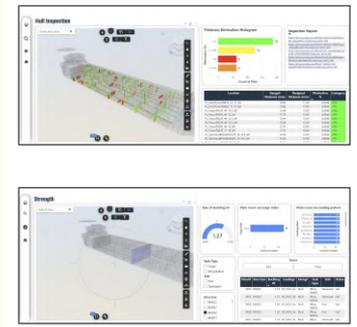
PHYSICS-BASED MODEL



>100 million DOF FEA model

REAL-TIME VISUALIZATION, REPORTING & INTEGRATIONS

DATA VISUALIZATION



DASHBOARD

REPORTING CAPABILITIES



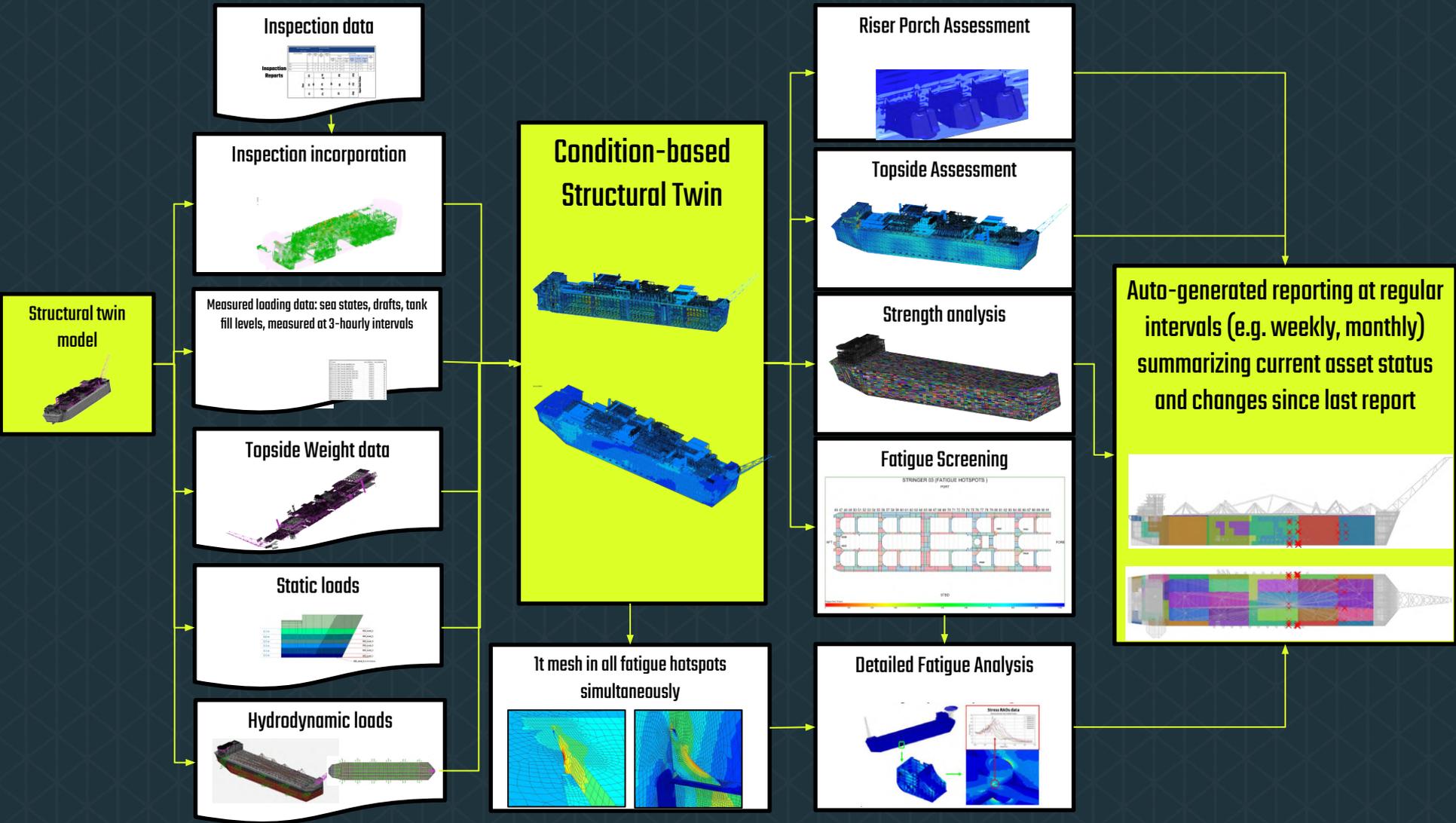
INTEGRATIONS



DATA ACQUISITION

CALCULATION

RESULTS



Inspection data

Inspection Reports

Report ID	Date	Inspector	Status
IR-001	2023-01-15	J. Smith	Completed
IR-002	2023-02-20	A. Brown	In Progress
IR-003	2023-03-10	M. Green	Planned
IR-004	2023-04-05	K. White	Completed
IR-005	2023-05-18	L. Black	In Progress

Inspection incorporation



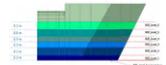
Measured loading data: sea states, drafts, tank fill levels, measured at 3-hourly intervals

Time	Sea State	Draft	Tank 1	Tank 2
00:00	3	12.5	80%	90%
03:00	4	12.8	75%	85%
06:00	3	12.6	82%	88%
09:00	4	13.0	78%	92%

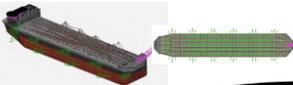
Topside Weight data



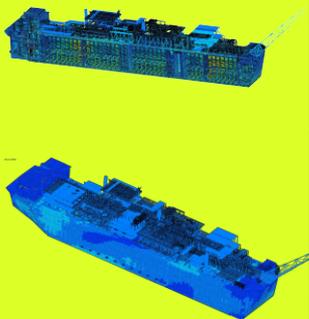
Static loads



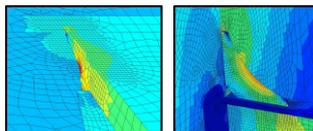
Hydrodynamic loads



Condition-based Structural Twin



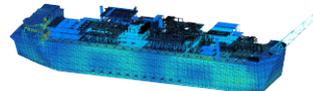
It mesh in all fatigue hotspots simultaneously



Riser Porch Assessment



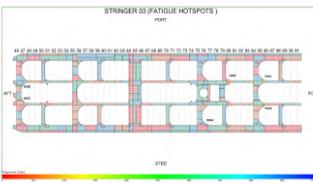
Topside Assessment



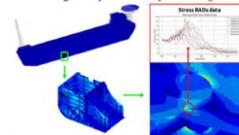
Strength analysis



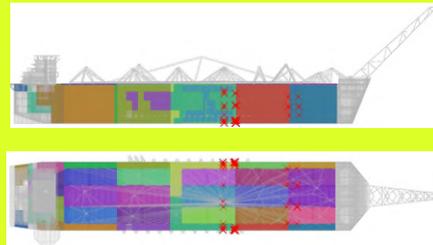
Fatigue Screening



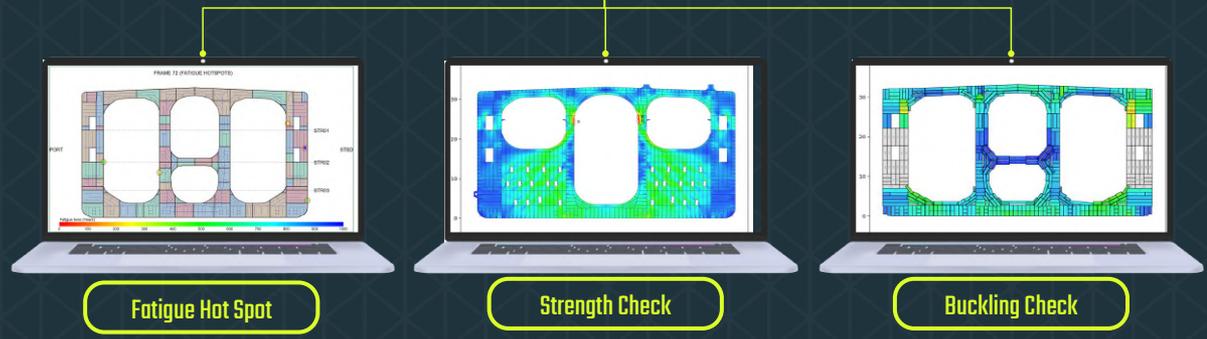
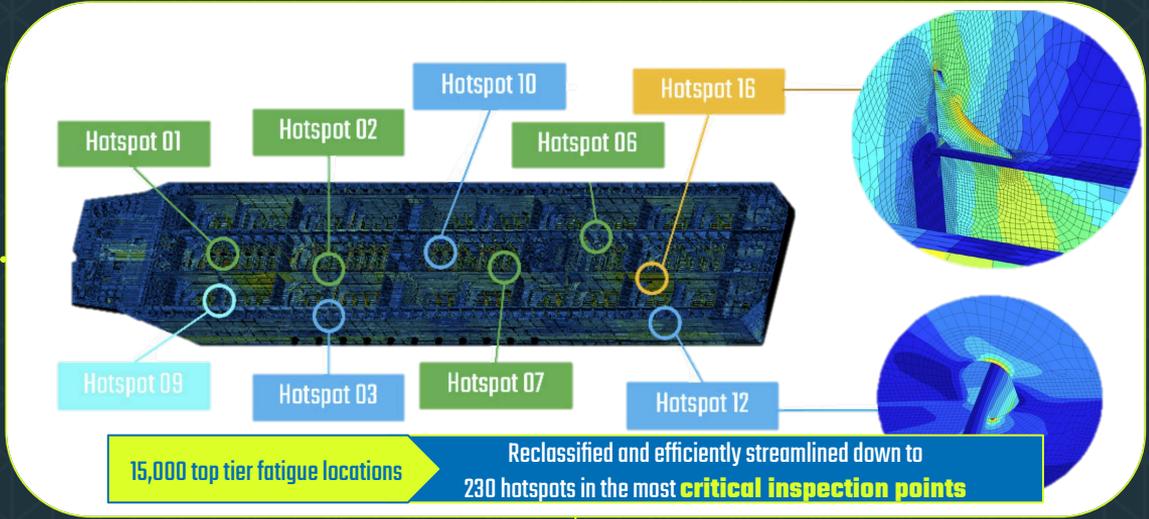
Detailed Fatigue Analysis



Auto-generated reporting at regular intervals (e.g. weekly, monthly) summarizing current asset status and changes since last report



Reduce OPEX – Inspect where it is critical



More Asset Life – As-is assessment with actual metocean data



Inspection

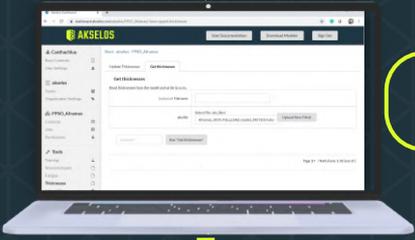
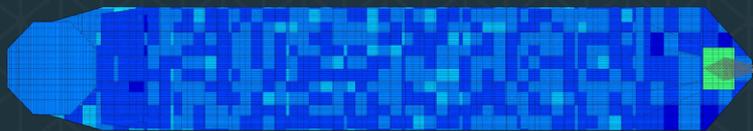
Inspection plan generated by AKSELOS

	A	B	C
1	name	new_thickness	max_diminution
2	CO_D2_STBD_PrimsW_FR78_WP_No48	0.0127	20
3	CO_D2_STBD_PrimsW_FR78_WP_No49	0.0127	20
4	CO_D2_STBD_PrimsW_FR78_WP_No50	0.0128	20
5	CO_D2_STBD_PrimsW_FR78_WP_No51	0.0128	20
6	CO_D2_STBD_PrimsW_FR78_WP_No52	0.0128	20
7	CO_D2_STBD_PrimsW_FR78_WP_No53	0.0197	20
8	CO_D2_STBD_PrimsW_FR78_WP_No54	0.0178	20
9	CO_D2_STBD_PrimsW_FR78_WP_No55	0.0163	20
10	CO_D2_STBD_PrimsW_FR78_WP_No56	0.0162	20
11	CO_D2_STBD_PrimsW_FR78_WP_No57	0.0179	20
12	CO_D2_STBD_PrimsW_FR78_WP_No58	0.0217	20

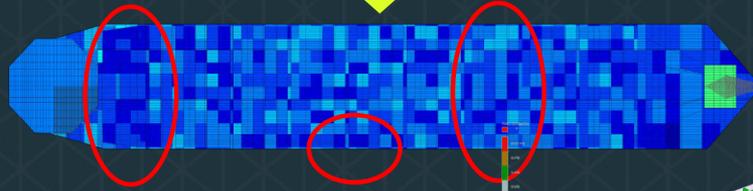
Inspection data (csv format)



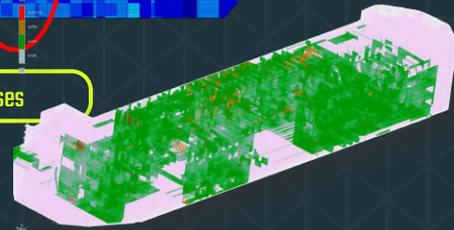
Before updating thicknesses



Thickness Update Tool (web browser)



After updating thicknesses

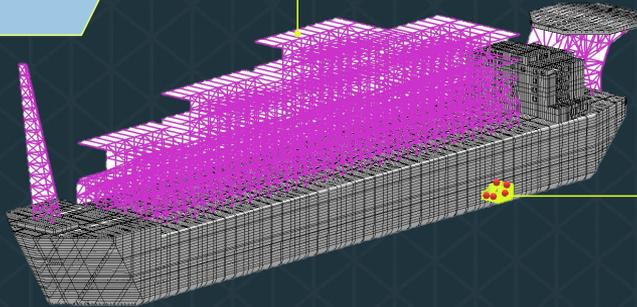


Lower Risk – Assess defects quickly

MORE ASSET LIFE

LOWER RISK

REDUCED OPEX



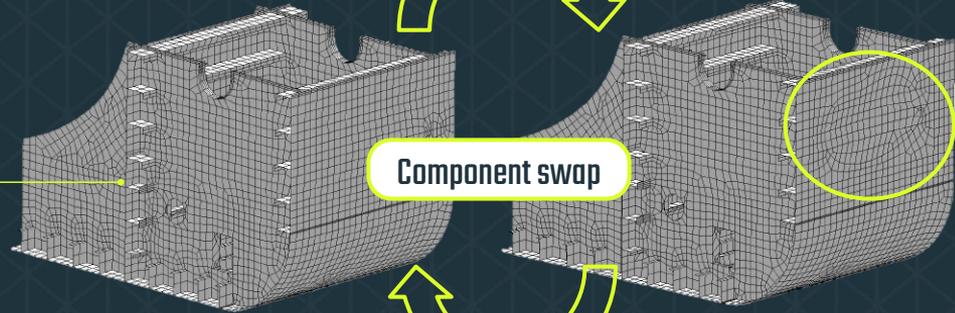
Component based approach



Dent assessment

Quick response

- Model already exists
- Only the effected region needs to be modelled
- Fast assessment of the defect on the entire structure



As designed

Component swap

With defect

Select Location

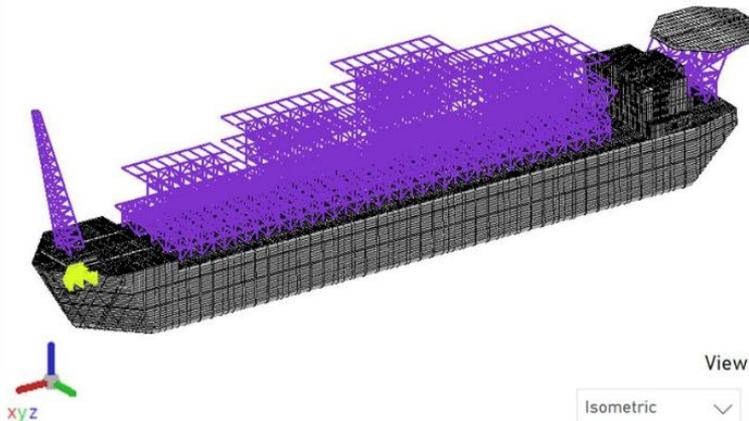
Structure

Mooring 

- Portside Bow
- Portside Stern
- Starboard Bow
- Starboard Stern

Model Viewer

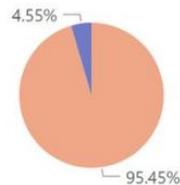
Selected components are highlighted in Yellow



View

Isometric 

Fatigue Damage Sources



● By functional loads ● By vessel motion

Remaining Fatigue Life

274.8

Years

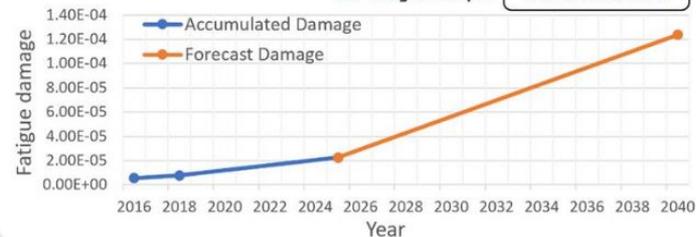
Status: GOOD

Fatigue Result Summary

Location	Hotspot	Accrued damage	Damage rate	Fatigue life
Starboard Bow	HS05	7.10E-002	3.38E-003	274.8
Starboard Bow	HS06	2.45E-002	1.17E-003	834.4
Starboard Bow	HS04	1.96E-002	9.33E-004	1051.2
Starboard Bow	HS02	1.83E-002	8.74E-004	1123.8
Starboard Bow	HS03	1.71E-002	8.12E-004	1209.8
Starboard Bow	HS12	1.09E-002	5.20E-004	1901.7

Hotspot Fatigue History

Fatigue Hotspot: Starboard Bow



CASE STUDY



Steam Methane Reformer

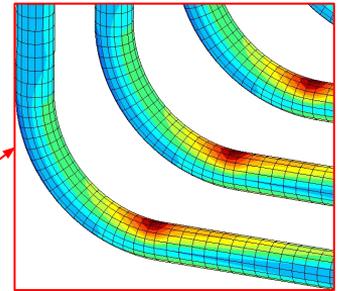
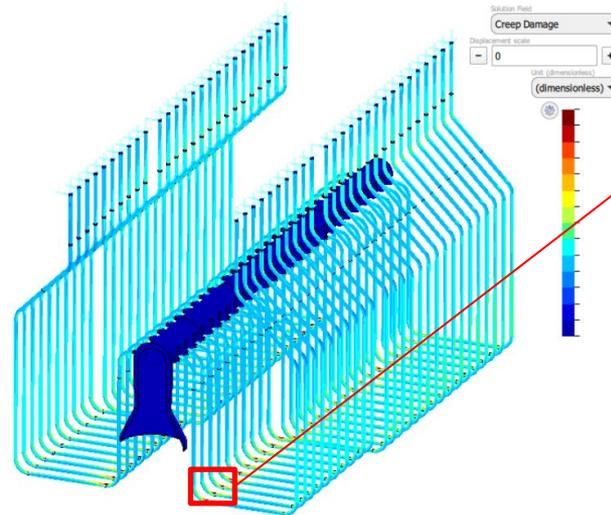
VALUE FRAMES

PREVENT
DAMAGE &
DOWNTIME

EXTEND
ASSET LIFE

CHALLENGE

UNKNOWN IMPACT OF
OPERATIONAL USE ON
ASSET INTEGRITY

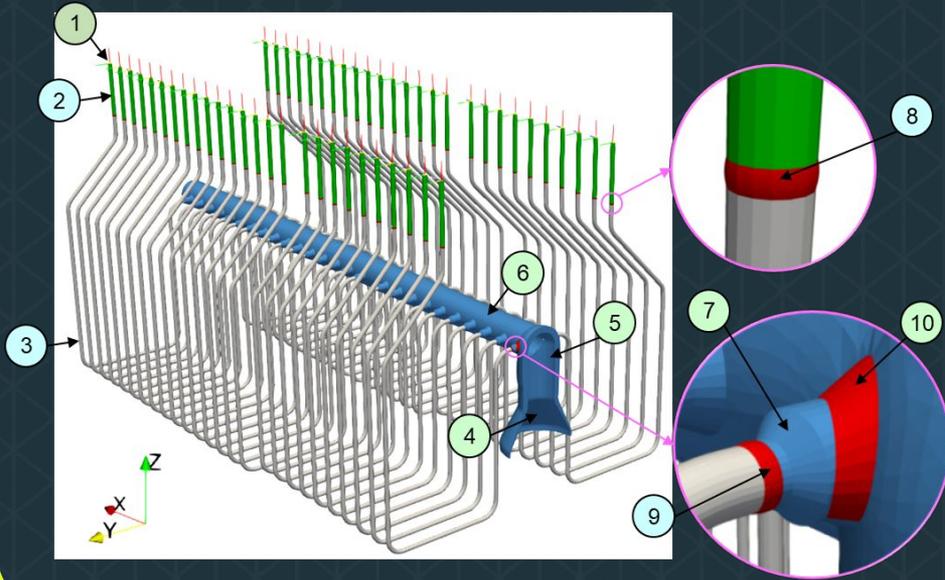


OUTCOME

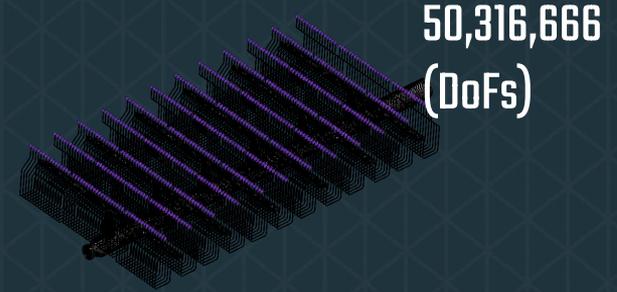
CLIENT ABLE TO
ASSESS CREEP
DAMAGE AND
REMAINING LIFE

Geometry CAD, Material Properties

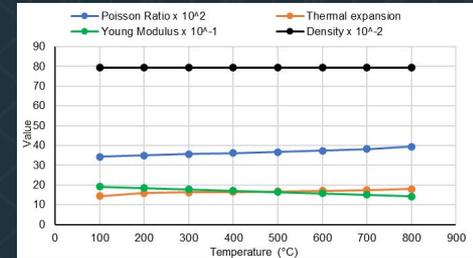
CAD



MODEL



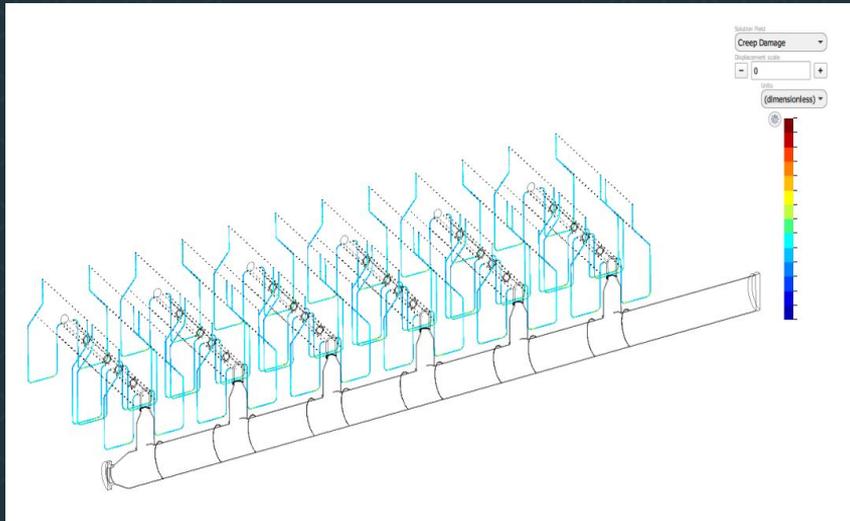
Temperature dependent material properties



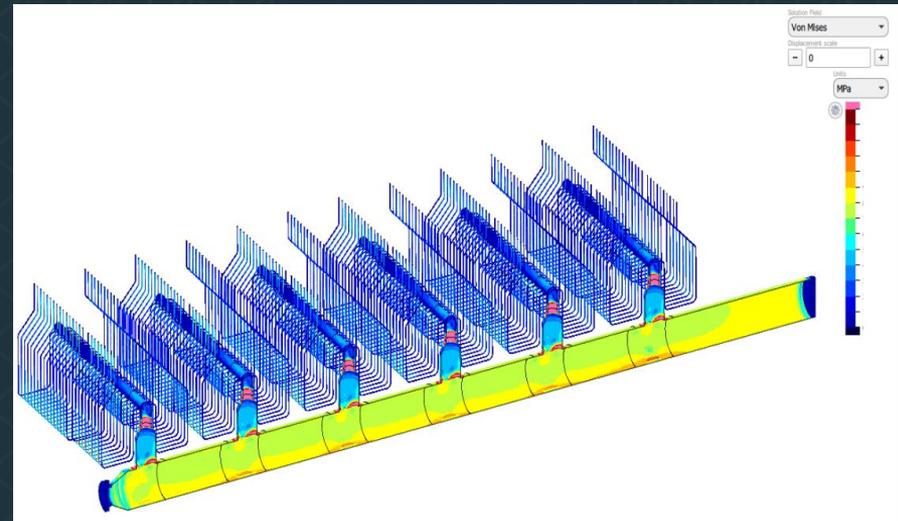
Analysis results

Track creep damage during operation to maximize operational life and enable maximum throughput

Creep Damage



Von Mises Stress



SMR (Steam Methane Reformer)

SMR

Home

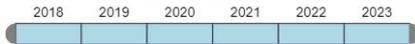
Monitor

Inspection

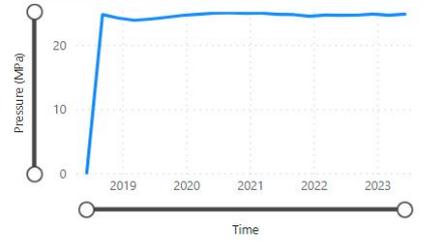
What IF?!

Last update
Friday, June 09, 2023

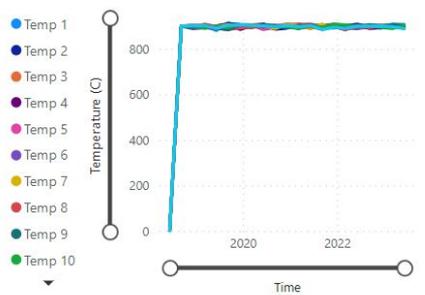
Time Line (years)



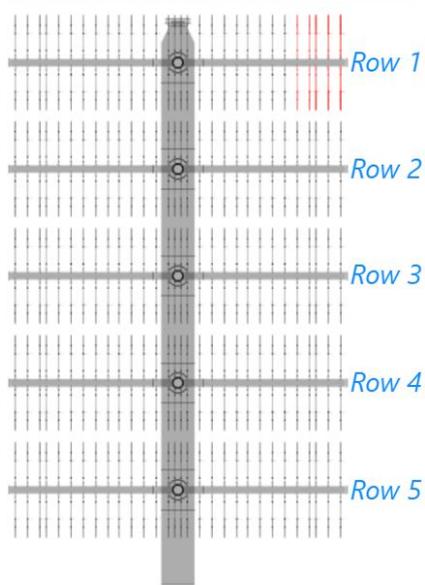
Inlet Pressure



Thermometers



Creep Tracker

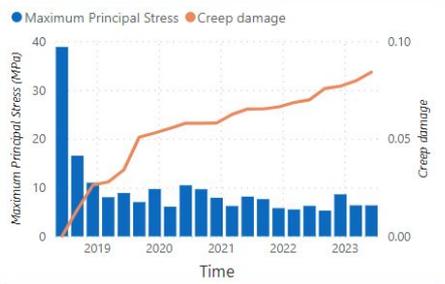


SMR Health



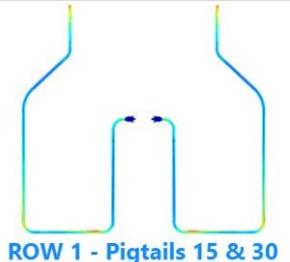
Creep Damage Stress

Creep Damage and Max. Principal Stress

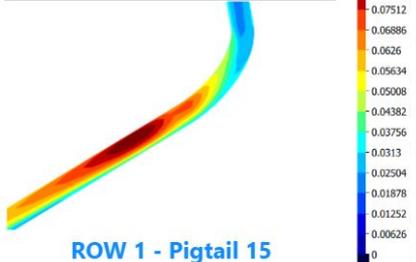


Unit	Pair of Pigtails	Creep
Row 1	Pigtails 15 & 30	0.08764
Row 1	Pigtails 14 & 29	0.08679
Row 1	Pigtails 13 & 28	0.08582
Row 1	Pigtails 12 & 27	0.08529
Row 1	Pigtails 11 & 26	0.08416

Maximum Creep Damage



Maximum Creep - Zoom





Copenhagen Central Square, Rådhuspladsen



Funded by
the European Union



Plan de Recuperación,
Transformación y Resiliencia



GOBIERNO
DE ESPAÑA

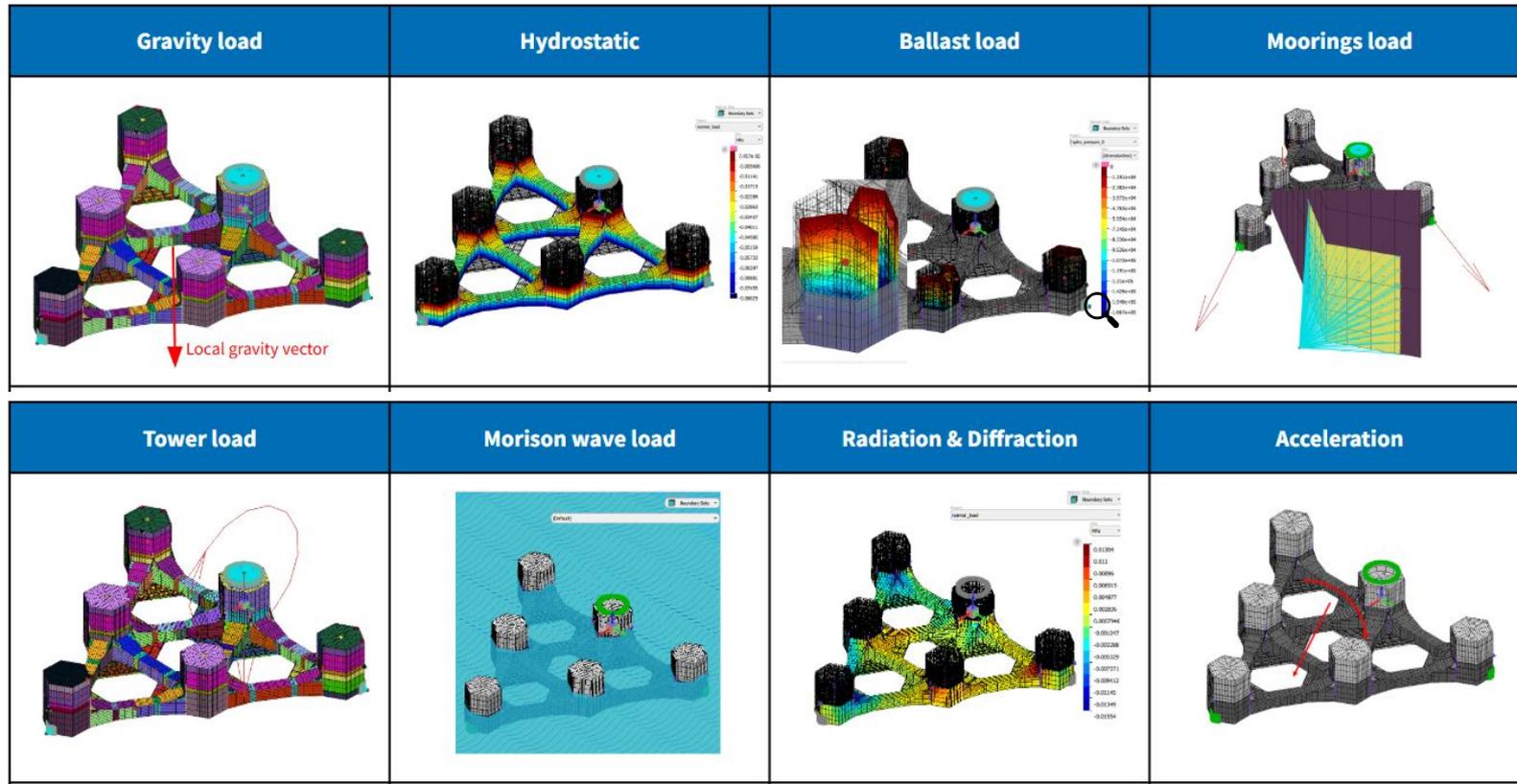
MINISTERIO
DE INDUSTRIA
Y TURISMO

Decimap Project

The Challenges:

- ❖ Validate the **detailed** structural design for Mediterranean conditions
- ❖ Analyse impacts of simultaneous **time domain** loads from WTG (Bladed) and Waves for > 20 000 DLCs
- ❖ Find potential design optimization paths to **reduce weight and increase competitiveness**

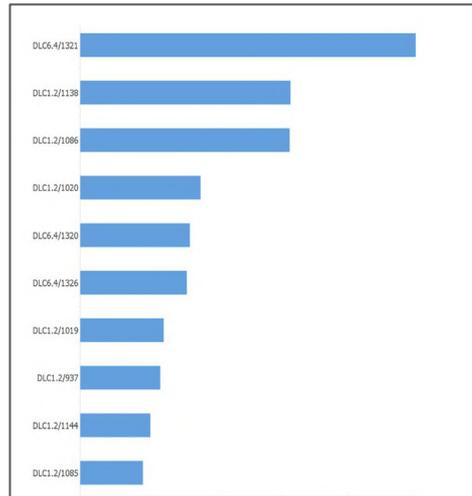
Applied Loads: Permanent load (G) & Environmental load (E)



Detailed Fatigue Analysis

- Detailed fatigue analysis was performed on **1339 simulations**
- total probability of occurrence = **97.7%**.
- **1h** per simulation (18,000 timesteps – 5hz)
- => In total, ~ **24 millions of simulation time steps**
- **6M Degree of Freedom**
- **1000 hotspots**

10 most damaging simulations:

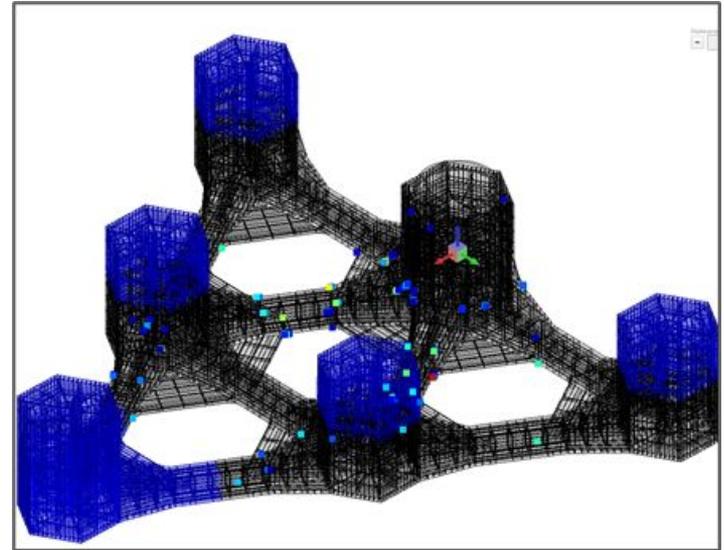


18 000 tsteps -> 2.5CPUh



Full analysis in **less than a day** on parallel cloud

Detailed fatigue results in selected hotspots:



Value(s):

- Full derisking of Structural integrity
- Identification of Critical DLC

Conclusions:



Funded by
the European Union

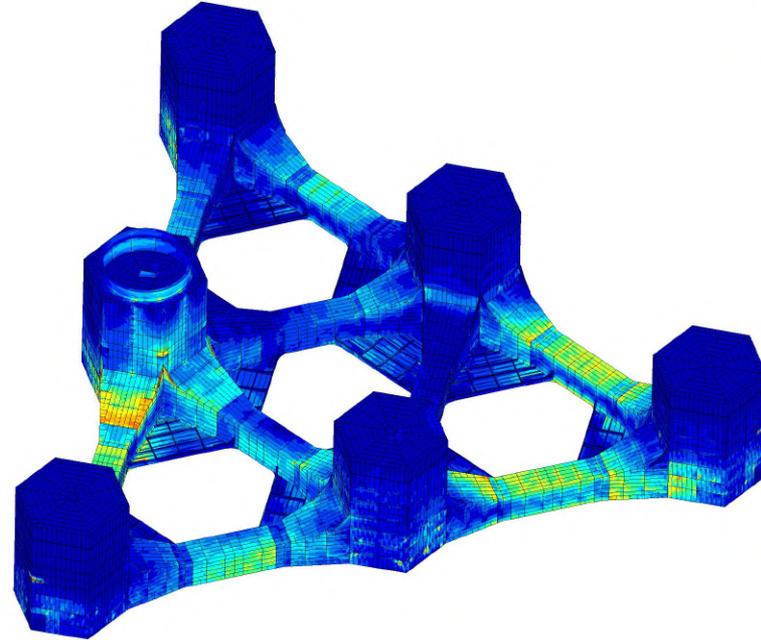


Plan de Recuperación,
Transformación y Resiliencia



GOBIERNO
DE ESPAÑA
MINISTERIO
DE INDUSTRIA
Y TURISMO

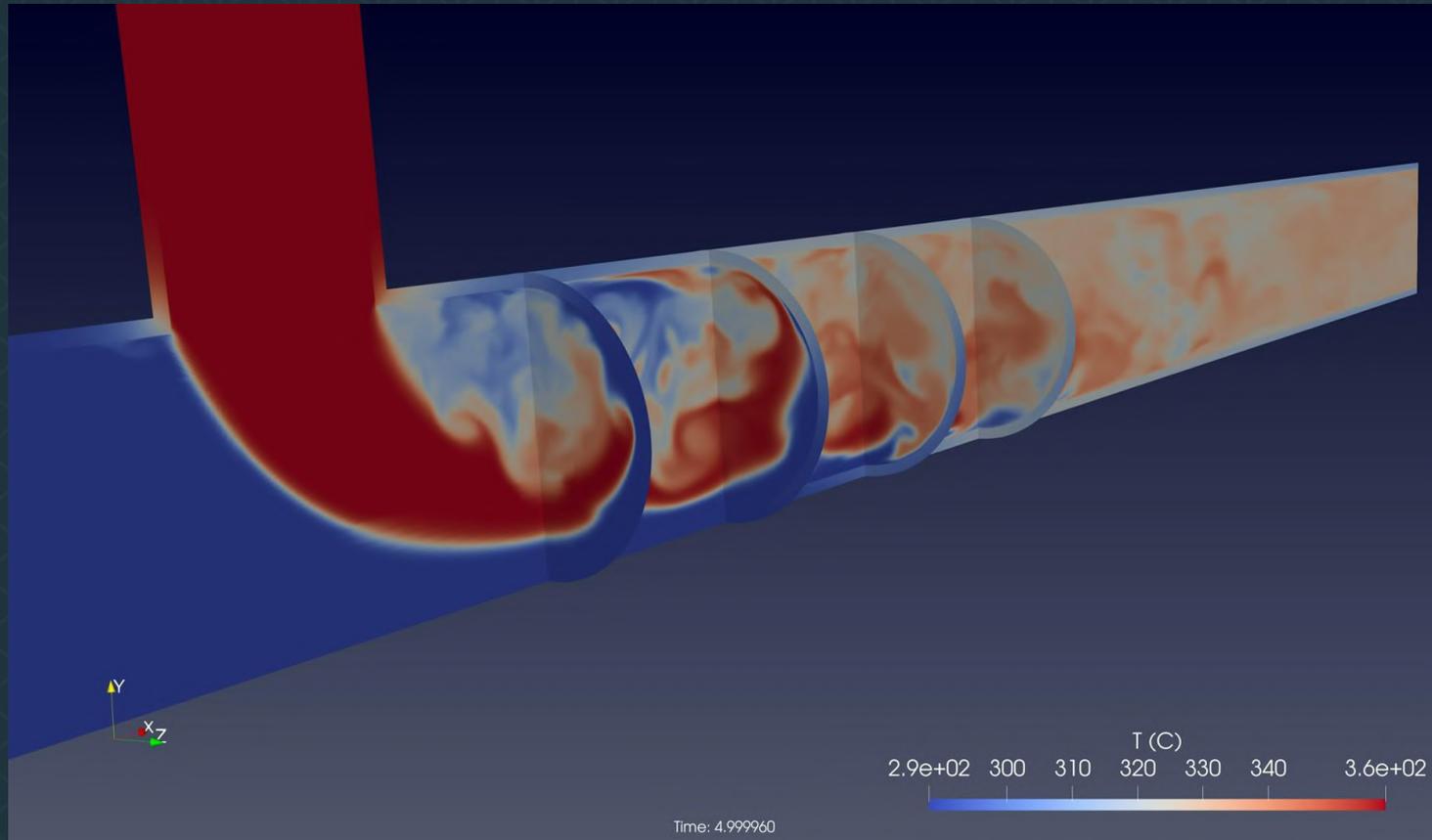
- The Software solution successfully **de-risked the DECIMAP** project using **detailed structural analysis**.
- The project enabled Sener to **adjust its design** to meet standard criteria and identify potential **material savings**.
- Future collaboration will target **the weight optimization** of the HiveWind substructure for commercial projects.



Challenges and opportunities for R&D

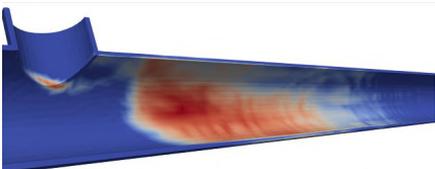
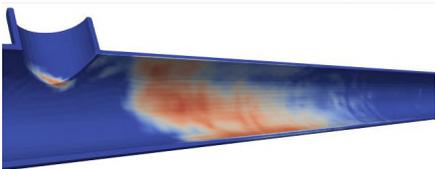
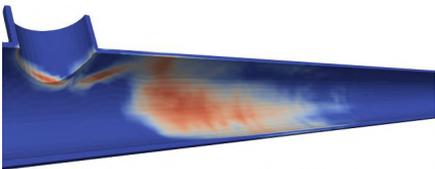
- Transport-dominated phenomena,
example: CFD with high Reynolds number.
- Traveling waves,
example: transient structural dynamics with abrupt load variation.

CFD example: thermal mixpoint

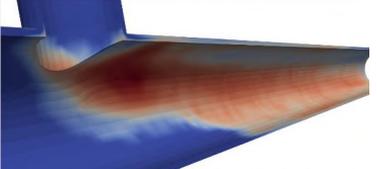
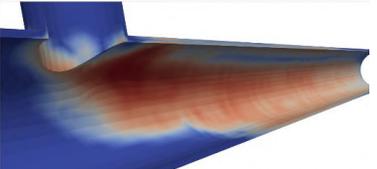
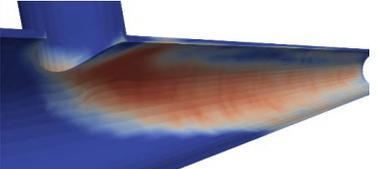


Example Fatigue Results for 12 Representative Cases

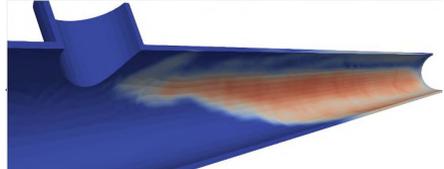
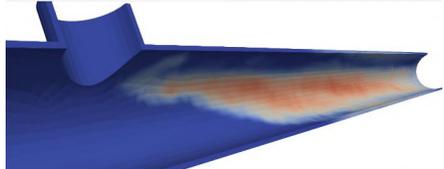
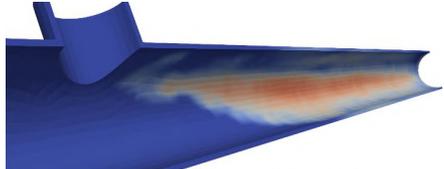
Case 1, Impinging Jet (MFRR=0.2)



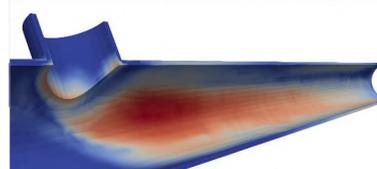
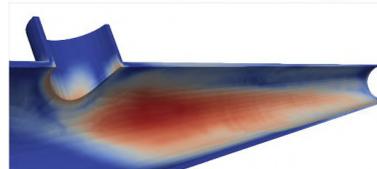
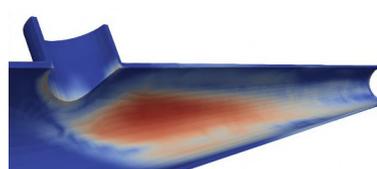
Case 2, Turn Jet (MFRR=0.9)



Case 3, Reattached Jet (MFRR=2)



Case 4, Wall Jet (MFRR=6)



Temperature delta



70K

80K

90K

MFRR = Mass Flow Rate Ratio



